### EXPLANATORY SUPPLEMENT TO THE

## IRAS SERENDIPITOUS SURVEY CATALOG



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1986

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### TABLE OF CONTENTS

I.	INTRODUCTION	Page
II.	POINTED OBSERVATION DATABASE	
	A. Characteristics	II-1
	B. Scheduling of Pointed Observations	II-3
	C. Pointed Observation Processing	II-3
	D. Beam Size Effects	II-7
	E. Photometry	II-9
III.	. SSC DATA PROCESSING	
	A. Grid Pair Selection	III-1
	B. Source Confirmation	III-2
	C. Position and Flux Density Refinement	III-7
	C.1. Position Refinement	III-7
	C.2. Flux Density Refinement	III-8
	D. Confusion Processing	III-8
	E. Band Merging	III-9
	E.1. Positional Tests	III-9
	E.2. Position Refinement	III-10
	F. Effective Grid Areas	III-10
	G. Identification of Overlapping Fields	III-14
	H. Associations with Other Astronomical Catalogs	III-14
IV.	ANALYSIS OF THE SSC	
	A. Confirmation, Reliability and Sensitivity Limits	IV-1
	A.1. Confirmation Tuning and Confirmation Rates	IV-1
	A.2. Reliability of Confirmed Sources	IV-6
	A.3. Band Merging Reliability	IV-7
	A.4. Sensitivity Limits	IV-7
	B. Association Statistics	IV-11
	C. Absolute Positional Accuracy	IV-21
	D. Photometric Accuracy	IV-22
	D.1. Accuracy of Relative Flux Densities	IV-22
	D.2. Accuracy of Absolute Flux Densities	IV-22
	D.3. Flux Density Uncertainty	IV-26
	E. Sky Coverage and Source Densities	IV-27
	F. General Catalog Statistics	IV-36
v.	FORMATS OF THE IRAS SERENDIPITOUS SURVEY CATALOG	
	A. Introduction	V-1
	B. Machine Readable Version	V-1
	C. Printed Version	V-8

### VI. ADDITIONAL CONSIDERATIONS

A. Effects of High Source Density	VI-1
B. Asteroids	VI-1
C. Redundant Sources	VI-4

### VII. REFERENCES

### VIII. ACKNOWLEDGEMENTS

### APPENDIX A: TABLE OF OVERLAPPING FIELDS

### I. INTRODUCTION

In 1983 the sky was surveyed by the Infrared Astronomical Satellite (IRAS) in four broad spectral bands centered at 12, 25, 60 and 100  $\mu$ m. During the course of the 300 day mission, about two-thirds of the satellite time was used to carry out an unbiased sky survey which led to the production of the IRAS Point Source Catalog (IRAS/PSC) containing 245,889 sources. That catalog, along with many other aspects of the mission, are described in the IRAS Catalogs and Atlases Explanatory Supplement (1985) [Referenced below as the "Main IRAS Supplement"]. A portion of the remaining mission was used to conduct a series of Pointed Observations, usually directed at objects of interest, and using the various capabilities of the satellite. Many of these Pointed Observations were performed by repeatedly scanning the 0.5 deg, wide survey detector array over the selected object. These scans were combined to produce a sensitive map of area about one deg.2 around the selected source (or, in some cases, a targeted "blank" field). By spatially coadding the repeated scans comprising each Pointed Observation a large data base was generated. Young et al. (1985) have described these data, the Pointed Observation program and the associated data processing at the Infrared Processing and Analysis Center (IPAC).

This document describes the IRAS Serendipitous Survey Catalog (IRAS/SSC) which has been constructed using the fortuitous observations at 12, 25, 60, and 100  $\mu m$  of 43,866 point-like sources that happened to lie in 1813 of the individual fields included in the Pointed Observation program. Because the Pointed Observations resulted in longer integration times for each source in the field than was possible in the all- sky survey mode, the limiting sensitivity for the IRAS/SSC is typically better than that of the IRAS/PSC by a factor of about 4. Also, the photometric accuracy, especially for faint sources, is improved relative to that of the IRAS/PSC. The amount of sky sampled in the SSC is nearly 1400 deg. but because of uneven sensitivity across the Pointed Observation fields, the effective sky coverage is 1108 deg. Excluding certain areas of great scientific interest to the team who planned the observations (specifically, the Galactic plane and the Magellanic Clouds), the Pointed Observations were widely distributed on the sky. Positional association of the SSC sources with those in the PSC reveal that 11,129 are in both IRAS catalogs; also, 5470 SSC sources have been cataloged at other wavelengths.

The positional accuracy of the SSC is not as high as that of the PSC, in part because of the restricted geometry of the observations themselves and also because of compromises made in processing the data. In those cases where more accurate positions are critically needed, it may be possible to obtain better results through re-processing the observations at one of the IRAS data centers.

The main objective of the Serendipitous Survey was to extend the detection threshold for point sources over a finite but significant portion of the sky so that those sources could be studied individually. No attempt has been made to construct an unbiased sample by removing the targeted sources or by correcting either for the non-random sky coverage or for the uneven depth of the survey corresponding to different characteristics of the several observing modes. Because most of the SSC sources are faint and because it was inherently difficult to achieve a uniform level of completeness in this program, it was decided to emphasize high reliability and photometric accuracy. These important SSC objectives were achieved by retaining only those sources which were detected in each of two independent Pointed Observations and by averaging the two measurements. No fields were included where only a single Pointed Observation was available. This strategy also provided a means for rejecting some asteroids and any other moving objects.

Frequently, independent observations were made of nearly the same region of sky and were treated in this catalog as separate fields; this practice resulted in partially redundant data sets. These overlapping fields are noted in the SSC to facilitate their further study. Because each of the 1813 fields in the SSC is unique in the sense that it may differ from other fields, both according to the observing mode that was used and in the wide range of source densities encountered, the catalog is presented field-by-field along with data pertinent to each field. Enough information is retained to permit the user to reorganize the source lists as needed. Those fields which overlap other fields are cross referenced. The fields are ordered by the right ascensions of their centers and the source list within each field is also ordered by right ascension.

An important objective of this catalog is to present a list of reliable sources found in all the selected Pointed Observation fields despite effects of high source density and/or complex backgrounds. In those heavily crowded fields where source confusion degrades the sensitivity, reliability, completeness, positional accuracy or photometric accuracy, the guiding philosophy has been as follows:

- (a) accept some degradation,
- flag sources where confusion may have affected the confirmation process,
- (c) indicate the local density of sources for each wavelength band,
- (d) provide information on the effects of confusion so that the user is both warned and equipped to make valid scientific judgments.

This policy has the result that many of the SSC fields and sources must be analyzed with particular care by the user, but it also means that many faint sources are included in crowded regions of scientific interest.

In summary, the main features of the SSC relative to the PSC are as follows:

- 1. Enhanced sensitivity for point-like sources in all four wavelength bands over a few percent of the sky.
- 2. Excellent reliability in low surface density fields.
- 3. Uneven sky coverage and completeness.
- 4. Reduced positional accuracy.
- 5. Improved photometric accuracy.
- 6. Much greater depth in crowded fields at the expense of reliability and accuracy.

The user of the SSC should be aware of the following considerations. First, a set of high latitude, unique, less crowded fields, selected as described in Section IV, was used in much of the current analysis. This subset of the catalog is comprised of 450 fields containing 5100 sources. Second, for these high latitude fields, reliability of order 99% was achieved for sources brighter than the flux density limits of 100, 150, 120, and 400 mJy for the 12, 25, 60, and 100  $\mu$ m bands, respectively; note that even within these fields the completeness limits vary. Third, the measured positional accuracy of SSC sources defines a search box with dimensions of 30" x 180" at 12  $\mu$ m, increasing to 60" x 140" at 60  $\mu$ m. The orientation of each search box is indicated by the grid orientation angle given in the appropriate field header. Fourth, for the high latitude subset of fields, the systematic photometric errors introduced by the absolute calibration are nearly identical with those in the PSC. The remaining systematic errors and uncertainties due to lack of reproducibility are less than  $\pm 10\%$  on average for sources detected with high signal-to-noise, and the

effects of noise are well quantified within each field. Fifth, for lower latitude fields, or fields where the underlying background has a complex structure, the reliability, completeness, positional, and photometric accuracies may be substantially degraded and each field must be analyzed with caution. Sixth, as in the PSC many sources are slighty extended and will have erroneous flux densities; other IRAS data bases such as the INTN mode grids (Young et al, 1985) should be used for the study of small extended sources.

In the preparation and presentation of the SSC, an effort was made, so far as possible, to conform to conventions established in the preparation and presentation of the PSC. In the following sections only that information not found in the Main IRAS Supplement (1985) or in the Users Guide to IRAS Pointed Observation Products (Young et al. 1985) and needed for the use of this catalog will be given. This includes: information on the Pointed Observation data base from which the point sources were extracted and the extraction process (Section II), on the data processing used to develop the SSC from the list of extracted sources (Section III), on the reliability and sensitivity of the SSC, its positional and photometric accuracy and certain statistical properties (Section IV), on the format and content of the SSC in its machine-readable and printed forms (Section V), warnings to the user concerning confusion effects, asteroids and redundant sources (Section VI), and a table of overlapping fields (Appendix A).

### II. POINTED OBSERVATIONS DATABASE

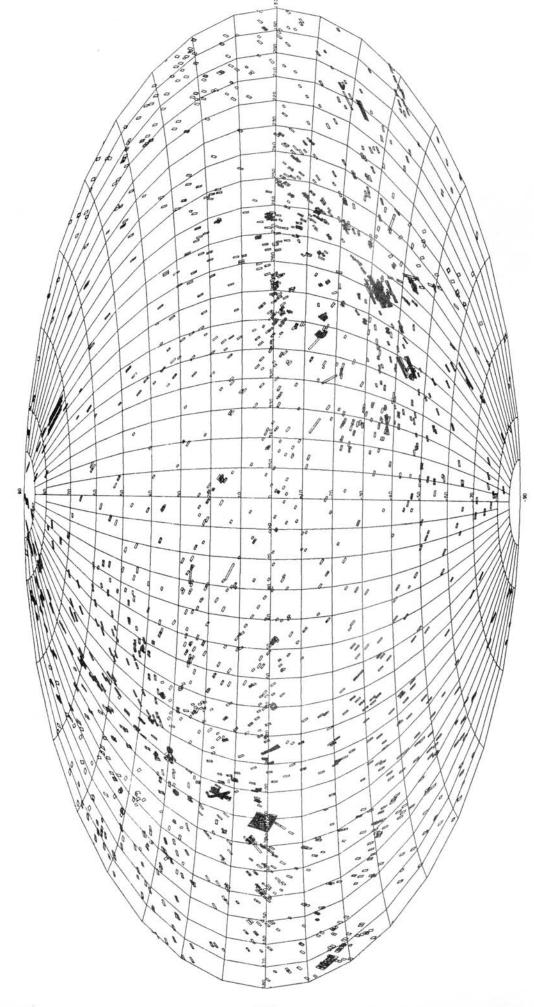
The Pointed Observation database described by Young et al. (1985) is available from the National Space Science Data Center (NSSDC) and at the IRAS data centers. IPAC and the two data centers in Europe provide software and facilities for detailed analysis. The SSC is based on processing of the Pointed Observation data at IPAC including extraction of the point sources which comprise the input to the SSC production software described in Section III; this section describes the Pointed Observation database and key aspects of the processing at IPAC.

### A. Characteristics

All of the IRAS Pointed Observations were made using command sequences (macros) stored in the satellite's computer. The macros are designated by a three letter code giving the generic class of observation, a two-digit number identifying the specific type and a single letter indicating the version. Although the number of macros is large, the vast majority of the survey array observations were made with only a few of these macros. For the Serendipitous Survey, only observations made with the DPS or TPS class macros have been included since these were the only macro classes which provided significant areal coverage combined with improved sensitivity. Moreover, these macros were by far the most important numerically, comprising ~90% of the Pointed Observation program. In these macros, the satellite repeatedly scanned an area of sky using the entire survey array, producing infrared maps of the observed region 0.5 deg, wide and of different lengths ranging from 0.6 to 6 degrees. The scan rate adopted was one-half the survey scan rate of 3.85 arcmin/sec. Variations included the number of scans and the size of the crossscan step between scans; these are indicated by different numbers in the macro name. Characteristics of these macros are given in Table II.A. The improvement in signal-to-noise ratio (SNR) compared to the PSC, was computed from the increased integration time afforded by the macro.

Table II.A. DPS and TPS Macro Characteristics

Macro	Number of	Scan	Cross	SNR	Catalog
Name	Scans	Length	Step	Gain	Code
		(Arcmin)	(Arcmin)		
DPS02B	6	96	0.3	4.8	Α
DPS05B	3	360	1.0	3.5	В
DPS52B	6	96	O	4.8	C
TPS52B	6	96	O	4.8	L
DPS55B	3	360	O	3.5	D
DPS60B	4	60	0.8	4.0	E
DPS60C	5	48	0.4	4.4	K
DPS60D	5	48	0.4	4.4	F
DPS60M	5	48	0.4	4.4	M
DPS61C	12	48	0.2	6.9	G
DPS61D	15	48	0.2	7.7	Н
DPS62D	9	96	0.4	6.0	I
DPS63D	3	96	0.8	3.5	J



Locations of IRAS Pointed Observations in Galactic Coordinates. Figure II.A

### **B. Scheduling of Pointed Observations**

The all-sky survey was given first priority in the selection of satellite observing time; the Pointed Observations were inserted into the satellite operations plan on the basis of an internal priority rating system and sky viewing constraints. As a method of deciding on the targets for the Pointed Observations, the Joint IRAS Science Working Group (JISWG) selected targets of scientific interest and assigned their relative priorities. In practice, the complexities of the scheduling and the overall highest priority assigned to the survey, coupled with the limited area in which the telescope could point at any given time, meant that Pointed Observations were not carried out on priority standing alone. Additionally, a large list of blank fields evenly spaced on the sky was available if no higher priority targets were suitable during a given observing period.

In particular, a further guideline used in scheduling of the Pointed Observations was designed to allow discrimination of transient phenomena in the IRAS bands such as asteroids, earth satellites, and dust particles. An attempt was made to repeat each observation at least once. To increase the integration time some observations were repeated many times. It is this strategy which permits the SSC to be based on the "confirmation" process described in Section III.B.

The coverage of the Pointed Observations on the sky in galactic coordinates is depicted in Figure II.A. The user of the Serendipitous Survey is reminded that sky coverage is not strictly random for two reasons. First, the targeted positions usually contained a source of specific scientific interest. Second, constraints due to the survey strategy and the satellite design strongly affected the sky available for Pointed Observations. Because of the orbital motion of the satellite, and the various pointing constraints (including Earth limb and Sun avoidance), the observations tended to concentrate near the ecliptic poles (I = 96 deg., b = +30 deg. and I = 276 deg., b = -30 deg.) where most of the observing time was available.

### C. Pointed Observation Processing

The detector output and positional data for the Pointed Observations were processed by the Deep Sky Coadd Observations Processor (DSCO) at the IPAC. The primary output of the processor is a set of eight two-dimensional arrays of numbers (called maps), produced by positionally coadding the detector data. The eight maps represent the signal and the noise in each of the four IRAS bands for the region of sky covered by the observation. The eight maps comprise a "grid".

Two kinds of grids were produced, FLUX mode and intensity or INTN mode grids. INTN grids are unfiltered and preserve the total intensity information of the observed region. For the FLUX grids, the detector data are filtered with a zero-sum bandpass filter centered on the point source spatial frequency. This processing technique suppresses the extended spatial scale information and achieves the highest sensitivity for the detection of point sources in uncomplicated fields. Because the IRAS Serendipitous Survey is intended to produce a catalog of faint point sources, only FLUX mode grids were used for the SSC processing.

The important process steps in producing FLUX grids are:

- 1. Removal of residual radiation hits and other glitches from the data.
- 2. Bandpass filtering of the detector data.
- 3. Mapping the detector samples to a spatial grid using the refined pointing data from the satellite.

- 4. Binning the data in a two-dimensional spatial array.
- 5. Computing the weighted flux and noise estimates for each pixel in the grid.
- 6. Extracting sources from grids.
- 7. Applying suitable calibration factors.

High frequency noise spikes such as charged particle hits are removed using a simple algorithm that compares the power in a high frequency (or glitch) band to the power in a band centered on the point source frequency. If the glitch is of sufficient amplitude and if the ratio of the power in the glitch band to the power in the source band exceeds a predetermined threshold, three samples are removed from the data stream. Note that a point source contains at least six samples. This filter successfully removes over 90% of the narrow glitches from the data.

In the next stage of processing, the data stream is passed through a digital zero-sum filter centered on the point source spatial frequency. The filter consists of a running 18-sample weighted average of the detector values. The weights for each of the first six and final six points are -1/12 and for the middle six points are +1/6. Thus, for smooth backgrounds, the filter output is zero. A position for the output point is assigned based on the mid position of the input samples. Figure II.B shows the resultant in-scan profile for a point source.

After filtering, the grid coordinates of the detector center at the sample time are computed. The data value is coadded to each grid cell whose center falls within a specified in-scan and cross-scan distance from the detector center. The cell sizes used in the maps are given in Table II.B. These values were set in part by the detector field of view, but mainly by the spatial smoothing applied in the DSCO processor.

Table II.B. Grid Pixel Sizes

Band	In-Scan	Cross-Scan
$(\mu m)$	(Arcmin)	(Arcmin)
12	0.25	0.60
25	0.25	0.60
60	0.50	0.60
100	1.00	0.60

Following the filtering and binning process, maps of the signal and the noise are generated for each wavelength band. The signal grid consists of the weighted averages of the detector data in each grid cell (or pixel). The weighting gives minimum variance for the samples added into a pixel. If  $f_i$  is a flux sample added into a pixel and  $n_i$  is the noise estimate associated with that sample, the averaged flux <f> of M samples is given by:

$$\langle f \rangle = \frac{\sum f_i \ w_i}{\sum w_i}$$
 II.1

where the weighting factor  $w_i = (n_i)^{-2}$ . For each detector, the noise is estimated using a median estimator similar to the type used in the production of the PSC. Median noise estimates are described in Section V.C.2 of the Main IRAS Supplement. The median of all the individual detector noise estimates for a given band defines the median noise in that band.

The noise map is generated by combining the sample variance with the detector noise weights for each pixel. The chi-square for a pixel is defined as:

$$\chi^2 = \sum f_i^2 w_i - (\sum w_i) < f > 2$$
 II.2

The estimated local noise  $\langle \sigma \rangle$  is then:

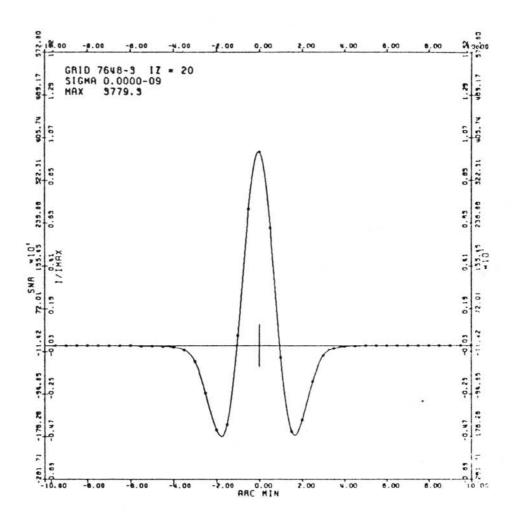
$$\langle \sigma \rangle = \left( \frac{1 + \chi^2}{M \sum w_i} \right)^{1/2}$$
 II.3

This local noise is nearly equal to the minimum variance estimate for a small number of scans, but approaches the sample variance/ $\sqrt{M}$  for a large number of scans. In complex fields it is sensitive to structure and can be artificially high in such areas.

The sources for the Serendipitous Survey were extracted with a simple threshold extractor which used both the signal and local noise maps to identify sources. The signal map is scanned for contiguous groups of pixels above a predetermined flux threshold. This threshold is expressed in terms of the median noise for the grid and has been set at 3.0 for this catalog. At the corresponding positions in the local noise grid, the initial source extraction required the signal to local noise ratio to be greater than 2.5.

Once contiguous regions above the thresholds are identified, an attempt is made to separate partially overlapping sources. A rethresholding technique is used to identify and separate these sources. This new extraction threshold is the original threshold plus a contribution from the median signal-to-noise ratio over the region to be separated. The user is cautioned that only well defined sources of roughly equal intensity are reliably separated by this algorithm. The Serendipitous Survey includes many examples, primarily in fields where the source density is high, of overlapping sources that have not been separated by the rethresholding technique. For such sources, the extracted position is then a flux weighted average of the positions of the constituent sources.

A correlation coefficient for an extracted source was calculated using a point source profile based on observations of the asteroid Egeria. A typical profile is shown in Figure II.B. This template was obtained from half survey rate observations which were binned at twice the normal pixel resolution and then resampled evenly using a cubic spline interpolation technique. The calculation of the correlation coefficient was similar to that for the PSC described in Section V.C.4 of the Main IRAS Supplement, except that the slope and baseline were zero due to the bandpass filtering of the data (see the Main IRAS Supplement for the definition of these quantities).



FLUX In-Scan Point Source Signature, 60 um Band

Figure II.B The SSC point source response function at 60  $\mu m$  illustrating the result of FLUX filtering.

### D. Beam Size Effects

The presence of negative sidelobes in the FLUX filtered point spread function complicates the analysis of high source density regions. Although the solid angle "covered" by the full filtered point spread function is nearly three times the geometrical solid angle of the detector, the beam size appropriate for estimating effects of confusion is significantly smaller. Unlike a more typical beam profile, with only positive sidelobes, the character of the confusion effects in the SSC depend on the source density in a non-monotonic fashion. It is possible to distinguish two cases, the first case applies to moderately crowded fields and the second to more heavily crowded situations.

Two competing effects will modify the source extractions from a FLUX filtered grid. In the first case, at moderate source densities, weak sources within the negative sidelobes of another source (within 60", 60", 120", and 240" for the 12, 25, 60, and 100  $\mu$ m bands, respectively) are reduced in flux. At these source densities, the primary penalty is a loss of completeness. For the second case, the source density is high enough for multiple sources to occur within the central filter peak. Then the extracted fluxes will often be higher than the true fluxes, leading to the usual effects of confusion. Given the filter parameters chosen for Pointed Observations processing, the effective beam size associated with this second case is very nearly the geometrical solid angle of the detector.

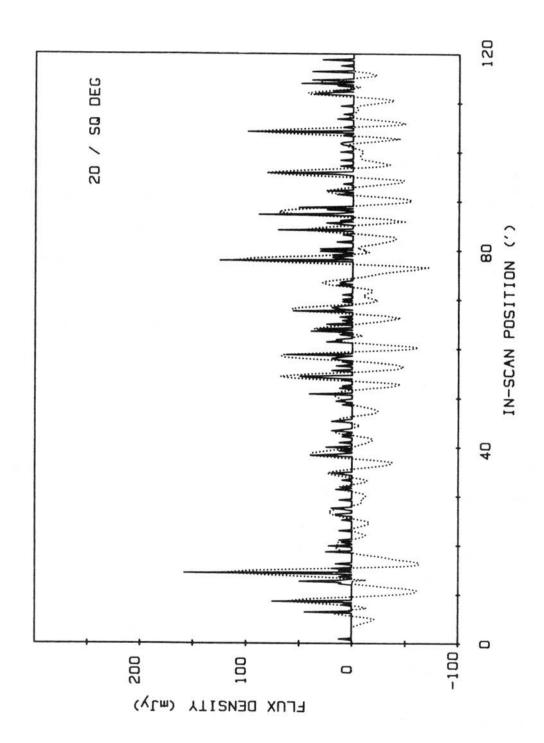
To illustrate these two effects, the response of a one-dimensional FLUX filter was simulated for source distributions of various densities and log N vs log F power laws. Figure II.C shows the results from a simulation at 60  $\mu m$  in which the density of sources brighter than 100 mJy is 20/deg.2 and a -1.5 power law is assumed for the relationship between source density and flux. The solid line represents the assumed underlying source distribution at 15" in-scan resolution. The dotted line represents the output of the FLUX filter. As can be seen from the comparison, the brighter sources will be extracted with slightly underestimated fluxes. Only at lower thresholds, and hence higher source densities, are there cases of merged sources producing flux overestimates. Note that at 60  $\mu$ m a density of 20 sources/deg. 2 corresponds to 27 beams/source using the geometric area of the beam appropriate for case 2. For comparison, the point source catalog used a confusion processing threshold of 25 beams/source (cf. Main IRAS Supplement, Section VIII-C). Table II.C summarizes the source densities where the two potential confusion effects become important; the threshold is set at 25 beams/source and the -1.5 power law is assumed as in the simulation.

Table II.C. Confusion Thresholds (Sources/Deg.2)1

Band	Case 1	Case 2
$(\mu m)$		
12	18	44
25	16	41
60	9	22
100	4	10

NOTE:

 $<sup>^1</sup>$  The density of sources with F  $_{\!\nu}$  > 0.1 Jy.



Solid curve represents a simulated one-dimensional source distribution for: log N vs log F slope = -1.5, and 20 sources/deg.<sup>2</sup> at F(60  $\mu$ m) > 0.1 Jy. Dotted curve represents the FLUX filtered output. Two effects of confusion are shown: (a) amplitudes of sources within the negative sidelobes of other sources are reduced, (b) higher amplitude single sources occur in the output when multiple sources fall within the positive beam.

Figure II.C

### E. Photometry

The flux density estimate for an extracted source is calculated from its peak amplitude above the baseline. Extended sources will have systematically low flux densities on FLUX grids. The SSC has been calibrated to the same absolute flux density scale as the PSC. This calibration is based on observations of standard stars and selected asteroids. Details of the absolute calibration can be found in Section VI.C of the Main IRAS Supplement and here in Section IV.D. Flux densities are given in units of Janskys at wavelengths of 12, 25, 60 and 100  $\mu m$  assuming a continuum flux density distribution which is inversely proportional to frequency. Color correction tables for other energy distributions are given in the Main IRAS Supplement. Because of the wide bandwidths of the IRAS spectral filters, these color corrections are generally quite significant and must be applied to the tabulated values in the SSC.

Corrections have been applied to remove a number of known systematic errors in the processed data. In particular, non-linear effects which depend on the flux of the source and the macro have been corrected. Additionally, there is a background-dependent correction that has not been applied to the Serendipitous Survey sources. We have assumed, instead, that the sources were all measured at a low background characteristic of high ecliptic and galactic latitudes. The error in making this assumption is generally less than 2% in the flux density.

The photometric accuracy of extracted point sources is dependent on the details of the observation. The various sources of uncertainty and bias in the photometric accuracy are discussed separately below.

- 1. The absolute calibration, in the sense of a knowledge of the flux densities of a set of standard stars and asteroids, has an estimated uncertainty of 2, 5, 5 and 10 percent in the 12, 25, 60 and 100  $\mu$ m bands, respectively (see Chapter VI of the Main IRAS Supplement). This does not include: (a) uncorrected systematic errors, (b) the effects of noise or (c) lack of reproducibility caused by various instrumental instabilities or pointing errors.
- 2. The IRAS detector array showed systematic variation in response as a function of cross-scan track with a peak-to-peak amplitude of  $\pm$  10%, 6%, 9%, and 10% in the 12, 25, 60 and 100  $\mu$ m bands, respectively. Because the current IRAS processing does not correct for this effect and because serendipitous sources are found on all possible tracks, some sources suffer errors.
- 3. For the IRAS detector sampling rates, use of the peak amplitude above baseline for the determination of flux density results in a maximum error of 10% and a typical error of 2 to 5% independent of the signal to noise ratio of the source. For bright sources, a template fit can give more precise photometric results. We have chosen, however, to use the peak estimate since it gives a more reliable flux estimate for sources with low signal-to-noise ratio.
- 4. It is expected that the uncertainties introduced by corrections for the frequency dependent responsivity and the non-linearity of the load resistors are less than 3%, for all the 12 and 25  $\mu$ m sources and for 25 and 60  $\mu$ m sources fainter than the primary IRAS reference source NGC 6543 (108 and 129 Jy at 25 and 60  $\mu$ m, respectively). However, for the brightest 100  $\mu$ m sources the responsivity may vary with frequency by as much as 60% (cf. Main IRAS Supplement, Section VI.B.4).
- 5. The Pointed Observations were calibrated via flashes of an internal reference source. When observations were made near the Galactic plane, in other highly crowded regions, or where the backgrounds are high, the reference flashes were frequently so confused by local structure in the baseline or by discrete sources that they were rejected by the calibration processor, and the

calibration transfer were based on an adjacent reference flash. Approximately 20% of all the Pointed Observations are affected by this rejected reference flash problem. For the 12, 25 and 60  $\mu$ m bands, the responsivities of the detectors were constant to better than +/-12% (see Figure IV.A.2 of the Main IRAS Supplement), so the worst case error would be ~24%. For the 100  $\mu$ m band the dispersion in detector responsivities was about twice that of the other bands. In general, however, the errors due to rejected calibration flashes are much smaller than these maximum values.

- 6. In crowded fields, both cross-scan and in-scan confusion causes errors in both position and flux strength of a source. The zero-sum filter used to produce the FLUX grids increases these effects due to its large negative side lobes; as shown in Figure II.B, these effects extend to nearly one source width on each side of a source in the scan direction.
- 7. Because the primary purpose of the Pointed Observations was to maximize the sensitivity for weak sources, the majority of the observations were carried out in the high gain mode of the satellite analog electronics. Consequently, a number of very bright sources have erroneous flux densities because of analog to digital converter saturation. The user should refer to the PSC for the flux densities of these very bright sources. A list of grids that have saturated pixels is given in Young et al. (1985).

In summary, taking into account that the two independent observations of each source are averaged, the uncertainties in the flux densities quoted in the Serendipitous Survey are generally of order 10%. Cases where larger errors are anticipated are indicated by flags in the SSC listing, as described in Section III. However, the uncertainties are sufficiently non-Gaussian that each case must be interpreted in the context of the specific observation.

### III. SSC DATA PROCESSING

Given the list of point sources that had been extracted from each of the grids included in the Pointed Observation program (Section II), preparation of the SSC required further data processing as follows:

- 1. Grid Selection: For each field observed, select the two grids which should yield the maximum number of twice-observed sources.
- Confirmation: Within each grid pair, and within each of the four IRAS bands, discard the sources that were detected with a low correlation coefficient, or low local signal-to-noise (Section II.C). Determine which of the remaining sources were seen near the same position and at approximately the same flux density in both grids.
- 3. Parameter Refinement: Combine the fluxes and positions of the individual detections to derive an improved position and flux density of each confirmed source.
- 4. Confusion Processing: For the list of "confirmed" sources found in each of the 4 bands, flag those detected in crowded regions.
- 5. Band Merging: Combine sources confirmed in two or more bands into a single source, and provide upper limits for bands where confirmed sources were not detected. Derive improved positions for band-merged sources.
- 6. Cirrus Flagging: Flag fields possibly contaminated by a significant number of spurious point sources related to spatial gradients in the diffuse emission [see Low et al (1984) for a description of infrared cirrus].
- 7. Effective Area Measurement: Compute the effective areal coverage for each macro type (Section II.A).
- 8. Redundant Field Indication: Identify those grid pairs which overlapped with other grid pairs and quantify the degree of overlap.
- 9. Associations: As for the PSC, seek associations between SSC sources in the final band-merged list and sources in other astronomical catalogs.

With the exception of the last step, all of this processing was carried out on a VAX 11/750 computer at the headquarters of the National Optical Astronomy Observatories in Tucson, Arizona. Details are given below.

### A. Grid Pair Selection

The first step in the Serendipitous Survey processing was to identify pairs of grids which could later be compared with one another to verify sources. The objective of this selection process was to maximize the number of sources that could be confirmed by finding grids with the maximum percentage of overlapping area coverage and with the least median noise.

In most cases, repeated observations of the same field with the same observing parameters can be readily identified by their observation identification number (OBSID). (The individual observations for a given OBSID can be distinguished by their grid numbers (cf. Young et al. 1985).) Where 3 or more observations had the same OBSID number, the two "best" observations were selected by defining a figure of merit (FOM) designed to maximize the number of 60  $\mu$ m sources that could be confirmed.

$$FOM = (1 - \Delta \theta) n^{-1.5}$$

III.1

In this equation,  $\Delta$   $\theta$  is the difference in position angle between the two grids and n is the median noise in the 60  $\mu$ m band for the grid having the higher 60  $\mu$ m median noise. (Hereafter, the grid having the lesser median noise at 60  $\mu$ m is denoted the "reference grid", while the grid having the higher 60  $\mu$ m median noise is the "confirming grid".) The first factor in Eqn. III.1 is an estimate of the fractional area of overlap of the two grids, which (for small differences in orientation angle) varies directly as  $\Delta$   $\theta$ , since the aspect ratio is invariant for grids with the same OBSID. The second factor rests on the assumption that the number of sources, N, detected in the 60  $\mu$ m Band should increase as

$$N \ (> f_{\nu}(60\mu m)) = constant \cdot f_{\nu}(60\mu m)^{-1.5}$$
 III.2

where  $f_{\nu}(60\mu\text{m})$  is the source flux density at 60  $\mu\text{m}$ . (The use of the 60  $\mu\text{m}$  noise as an indicator of the quality of a grid was predicated on earlier analyses of the PSC, which suggested that, because the 60  $\mu\text{m}$  source counts were dominated by galaxies rather than stars or infrared "cirrus", they should be more sensitive to to gains in sensitivity than source counts at other wavelengths.)

For about 60% of the fields observed, only two observations could be paired on the basis of their OBSID number, and for these fields no selection on the basis of overlapping area or noise was applied.

For about 10% of the grids the OBSID was unique. These grids were paired with one another on the basis of the proximity of their field centers. No area or noise selection was applied to the grid pairs that were identified by this process.

In all cases, grids were paired only if their centers coincided to within 5 arcmin.

### **B. Source Confirmation**

The major goal of the confirmation processing was to select, from among the point sources extracted from each observation pair, those sources which exceeded limits of local signal-to-noise and correlation coefficient that were determined to distinguish reliable point sources, and which were detected near the same position and flux on both the reference and confirming grids. This process was carried out separately for each of the four IRAS bands.

As a preliminary step in the confirmation process, all sources lying within two pixels of the grid boundaries were discarded, since such sources are likely to have erroneous fluxes and positions.

Using the resulting list of acceptable sources, the positions of sources within each of the two grids in a pair were compared. This positional discrepancy test actually consists of two tests applied serially, since the fields of view of all of the detectors were non-circular (cf. Table II.B). In particular, most fields of view were elongated in the direction perpendicular to that in which they were scanned across a field, so that the allowable "in-scan" positional discrepancies were generally smaller than the "cross-scan" discrepancies.

Projection of the positional differences of sources onto the cross-scan and inscan directions was complicated by the fact that the scan directions (or orientation angles) of the two grids in each grid pair were not identical. Since these differences were usually small, the average orientation angle of the grid pair was used:

$$\langle \theta \rangle = \frac{\theta_r + \theta_c}{2}$$
 III.3

In Eqn. III.3 and hereafter, the subscript "r" refers to the reference grid, while the subscript "c" refers to the confirming grid of the grid pair.

The relevant geometry is shown schematically in Figure III.A. The projection of the difference in position in the in-scan (cross-scan) direction along (across) the direction corresponding to the average orientation angle is related to the right ascension and the declination of the source positions as follows:

$$\Delta y = \Delta r \sin(\phi - \langle \theta \rangle)$$
 III.4a

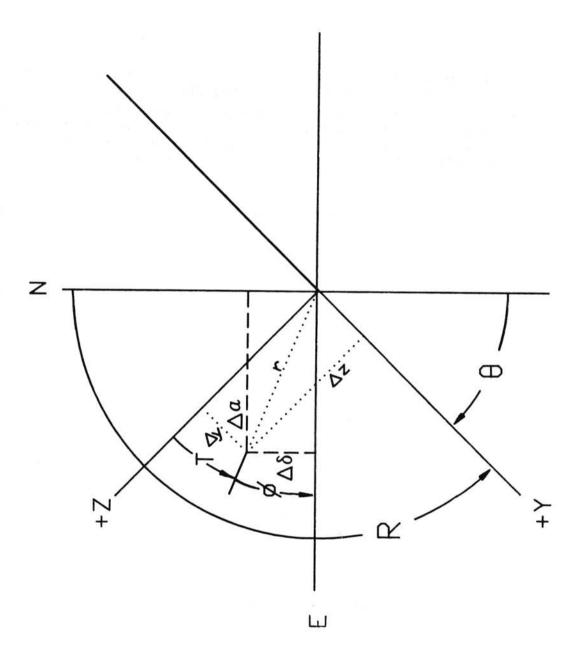
$$\Delta z = \Delta r \cos (\phi - \langle \theta \rangle)$$
 III.4b

where,

$$\Delta r = \left[ (\alpha_r - \alpha_c)^2 + (\delta_r - \delta_c)^2 \right]^{1/2} * Cos \left( \frac{\delta_r + \delta_c}{2} \right) * 3600$$

$$\phi = \tan^{-1} \left( \frac{\delta_r - \delta_c}{\alpha_r - \alpha_c} \right) \qquad \text{for } \delta_r - \delta_c > 0$$

$$\phi = \tan^{-1} \left( \frac{\delta_r - \delta_c}{\alpha_r - \alpha_c} \right) + \pi \qquad \text{for } \delta_r - \delta_c < 0$$



In the above equations,  $\alpha$  and  $\delta$  are the right ascension and declination of each source in radians,  $\Delta r$  is the total positional difference between source i (detected in the reference grid) and source j (detected in the confirming grid) in arcsec,  $\Delta\theta$  is the position angle of the vector from source i to source j and  $\Delta y$  and  $\Delta z$  are the in-scan and cross-scan position difference measured parallel and perpendicular to the average scan direction of the grid pair. In order to pass the positional confirmation test. it was required that  $\Delta y$  and  $\Delta z$  not exceed the constraints listed in Table III.A. These limits were determined by examining the distribution of position differences between sources extracted from the two grids. The distribution of valid source confirmations is sharply peaked about zero, while the spurious confirmations show up as a constant level background. The magnitudes of the final confirmation windows were defined by the half-widths of the peaked distributions at the points where they exceed the background distribution by a factor of three. Figure III.B shows the observed distribution of in-scan (y direction) and cross-scan (z direction) separations, as well as the adopted upper limits for positional differences. Only grids with |b| > 30 deg, were used in these determinations to minimize the effects of confusion from high density regions.

Sources passing the positional difference test were then passed on to a filter that checked the flux density ratio; it required

$$0.5 < F_r / F_c < 2.0$$
 III.5

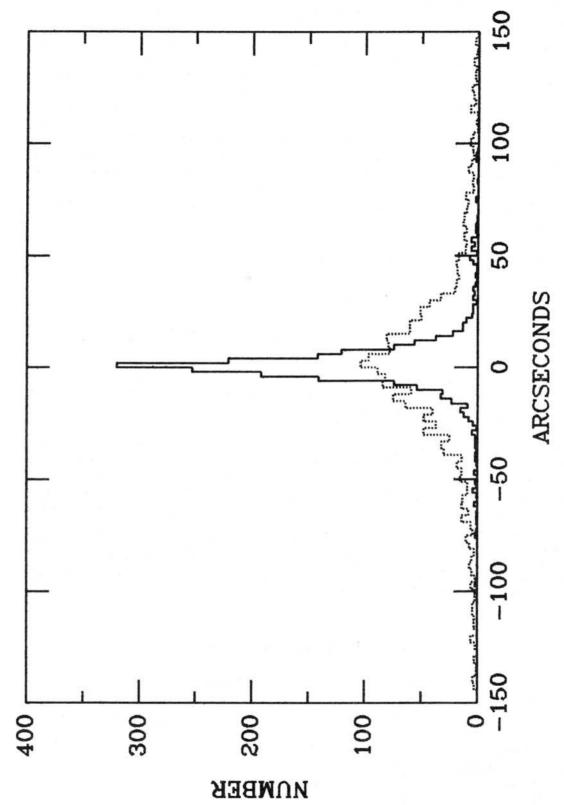
This test helped to eliminate moving sources that coincided by chance with a source or a noise event.

Sources with acceptable grid positions were then checked to determine whether their correlation coefficients and local signal-to-noise ratios exceeded certain lower limits. These limits were optimized by an empirical procedure described in Section IV.F.1 and are listed in Table III.A.

Differences among the four IRAS bands in the acceptable limits on positional and flux discrepancies, local signal-to-noise ratio and correlation coefficient, among the 4 IRAS bands are due to variations in noise and detector fields of view. In addition, because of a periodic noise pickup in one of the 12  $\mu$ m detectors, a higher local noise threshold was used for one track in the 12  $\mu$ m grids. The offending detector showed low level 1 Hz clock pulses from the spacecraft computer at cross scan coordinate 11 (i.e., 11 x 0.6 arcmin from the detector #27 edge). Since these pulses could in some cases repeat from observation to observation, they occasionally mimicked real, but faint, sources. For candidate detections within one cross scan pixel (i.e., +/- 0.6 arcmin) of the "noise track", the local signal-to-noise threshold was set at 5.5.

**Table III.A. Confirmation Requirements** 

Minimum Band Median SNR	Minimum Minimum Median Local		Minimum Correlation	Maximum Position Difference	
	SNR	SNR	Coefficient	In-Scan (Arcsec)	Cross-Scan (Arcsec)
$12 \mu m$	3.0	3.0	0.70	27.5	92.5
12 μm "clock tracks"	3.0	5.5	0.70	27.5	92.5
25 μm	3.0	4.0	0.70	27.5	92.5
$60 \mu m$	3.0	2.5	0.70	70.0	142.5
$100 \mu m$	3.0	2.5	0.70	142.0	142.5



Number of sources versus separation between positions in the reference and confirming grids, in-scan (solid line) and cross-scan (dotted line). Figure III.B

### C. Position and Flux Density Refinement

Sources in each grid pair which satisfied all of the criteria listed in Table III.A were identified as high quality sources. A weighted position and flux density was derived for each confirmed source.

Sources which satisfied only the criteria of positional and flux density agreement were retained as medium quality sources, as long as one of the two sources exceeded the limits on local signal-to-noise and correlation coefficients. The positions and flux densities of these medium quality sources were taken from the extraction satisfying all verification criteria. Finally, sources not meeting both the positional and the flux density tests were rejected from further processing in the SSC.

### C.1. Position Refinement

Positional uncertainties for all confirmed sources were derived from data obtained in the verification process. The position differences between the pairs of source detections were binned according to the local signal-to-noise (LSNR) of the source in the confirming grid as follows:

where MINLSNR is the threshold LSNR for each band (Table III.A). Within each bin, rms values for the cross-scan and in-scan position differences of each source pair were computed. The positional uncertainty of all sources detected in a given range (BIN) of local signal-to-noise was then defined to be equal to 2<sup>-0.5</sup> of the derived rms value for the positional differences. Table III.B lists the results.

Table III.B. Assigned Position Uncertainty for Confirmed Sources

LSNR		In-Scan	(Arcsec)			Cross-Sca	an (Arcse	c)
BIN	$12 \mu m$	$25 \mu m$	$60 \mu m$	$100 \mu m$	$12 \mu m$	$25 \mu m$	60 μm	100 μm
O	14.3	11.0	36.5	57.3	55.2	53.6	64.7	66.3
1	11.2	9.7	30.9	50.6	53.1	50.3	63.4	66.1
2	9.5	9.1	22.9	43.2	48.4	47.9	60.1	62.9
3	8.9	8.2	20.1	37.3	46.7	44.7	55.4	58.9
4	7.7	7.2	16.9	29.9	42.1	41.7	51.4	55.4
5	7.2	6.4	14.6	26.0	40.7	37.5	47.3	50.2
6	6.7	6.3	12.7	22.0	37.8	35.8	43.6	46.1
7	6.2	6.1	10.1	20.4	33.2	34.6	38.1	45.3
8	6.2	5.9	9.2	18.0	31.5	31.1	33.0	40.6
9	6.0	6.1	8.5	15.1	28.3	31.7	31.1	35.7
10	5.9	6.4	8.0	13.9	26.6	27.9	28.1	33.8
11	6.3	7.2	8.9	13.5	25.6	28.1	29.6	34.7
12	6.2	7.3	7.7	13.5	22.2	29.1	29.1	32.0

The positions of high quality confirmed sources were refined according to Eqns. III.7a and b, which give increments to the in-scan and cross-scan positions:

$$\delta z = (z_c - z_r) / (1 + \sigma_c^2(z) / \sigma_r^2(z))$$
 III.7.b

$$\delta Z = (Z_c - Z_r) / (1 + \sigma_c^2(z) / \sigma_r^2(z))$$
 III.7.b

The refined equatorial coordinates of the confirmed source are obtained by projecting these increments onto equatorial coordinates:

$$\alpha = \alpha_r + \frac{\delta_y \sin <\theta > + \delta_z \cos <\theta >}{3600 \cos \left(\frac{\delta_r + \delta_c}{2}\right)}$$
 III.8.a

$$\delta = \delta_r + \frac{\delta_z \sin \langle \theta \rangle - \delta_y \cos \langle \theta \rangle}{3600}$$
 III.8.b

### C.2 Flux Density Refinement

To derive the most accurate flux density for confirmed sources, the flux densities of individual source extractions were combined and weighted according to the median noises in their respective grids, thus:

$$\langle F \rangle = F_r + (F_c - F_r) / (1 + n_c^2 / n_r^2)$$
 III.9

Here  $n_r$  is the median noise in the reference grid, in the band where the source was detected, and  $n_c$  is the median noise in the same band in the confirming grid. The refined flux density uncertainty is taken to be

$$\langle n \rangle = \left( \frac{n_r^2 n_c^2}{n_r^2 + n_c^2} \right)^{1/2}$$
 III.10

### D. Confusion Processing

Potentially confused sources were flagged during the confirmation processing, by counting the number of confirmed sources which occurred within a specified range in the cross-scan and in-scan directions. The processing steps are identical to those used in the confirmation processing itself, except that the source positions from the reference grid and from the confirming grid are both replaced by the refined positions of confirmed sources, and the confusion windows in  $\Delta y$  and  $\Delta z$  are taken to be a factor of two larger than the confirmation windows given in Table III.A.

### E. Band Merging

The process of identifying sources that were detected in two or more IRAS bands, and of setting upper limits on the fluxes of sources not detected in all four of the IRAS bands, is called band merging. The process of band merging relied solely on positional coincidence, and used positional tests similar to those used in the confirmation processing (Section III.B). The sources selected for band merging were limited to the high quality confirmed sources. However, in cases where a high quality Band i source had no apparent counterpart among the high quality Band j sources, the list of medium quality sources in Band j was scanned for a possible positional coincidence. In cases where no band merger candidate could be found among either the high or medium quality sources, an upper limit to the flux in the merging band was derived from the median noise in the reference grid, nr. In most cases the upper limit is taken to be  $4.5 \times n_r$ . Upper limits at  $12 \mu m$  for sources located near the region which suffered "clock interference" (Section III.B) are given as  $5.5 \times n_r$ .

The band merge process was executed in the same order as that of the PSC (Main IRAS Supplement, Chapter V.D.3) as shown repeated in Table III.C. In particular, it began by attempting to band merge the high quality sources detected at 12  $\mu$ m with those detected at 25  $\mu$ m. If a merger was found, the position and positional uncertainty of the source was refined (cf. Section III.E.2), and a merger was then sought among the high quality sources from 60  $\mu$ m etc. Sources that had been band merged were flagged, and were not available for band-merging with other high quality sources. Thus, in the second pass of the band merging process, mergers were sought only for high quality sources detected at 25  $\mu$ m that had not been previously merged with any source detected at 12  $\mu$ m.

The final stage of the band merge processing was a count of the number of 100  $\mu$ m sources that could not be merged with any other sources detected at other wavelengths. The areal density of these sources is taken to be an indication of the presence of infrared cirrus in the region.

Table III.C. Order of Band Merging

Primary Band Secondary Ban			ind		
$(\mu m)$	$(\mu m)$				
12	25,	60,	100		
25	12,	60,	100		
60	25,	100,	12		
100	60,	25,	12		

### E.1 Positional Tests for Band Merging

The test for positional coincidence in band merging is similar to that used in the confirmation processing. However, in the band merging process, the positional difference is tested against the combined positional uncertainties of the potential merging sources in the in scan and cross scan directions. That is, for a source in Band i to merge with a source in Band j, it is required that:

$$\Delta y_{ij} < 4 * \sigma_{ij}(y)$$
 III.11.a

$$\Delta Z_{ij} < 4 * \sigma_{ij}(z)$$
 III.11.b

where  $\sigma_{ij}(y)$  and  $\sigma_{ij}(z)$ , the total uncertainties in the in-scan and cross-scan directions, are computed from the uncertainties of the two potentially merging sources:

$$\sigma_{ij}(y) = \left[ \frac{\sigma_i^2(y) \sigma_j^2(y)}{\sigma_i^2(y) + \sigma_j^2(y)} \right]^{1/2}$$
III.12.a

$$\sigma_{ij}(z) = \left[ \frac{\sigma_i^2(z) \sigma_j^2(z)}{\sigma_i^2(z) + \sigma_j^2(z)} \right]^{1/2}$$
III.12.b

In cases where more than one high quality source might satisfy the positional coincidence test, the merger having the least positional discrepancy is used.

### E.2 Position and Position Uncertainty Refinement

After each successful band merger, i.e., after a band merger of two high quality sources, the position and positional uncertainty of a merged source were refined using the same algorithms applied in the confirmation processing (Eqns. III.7 and III.8). However, in the case of the band merging process, the subscript 1 refers to the source seen in the primary band (the left-most column in Table III.8), while the subscript 2 refers to the secondary band in which the band merger was sought. After a source has been band merged once, then the subscript 1 refers to the refined position and positional uncertainty. The refinement of positions and positional uncertainties (in cases where two high quality sources were band merged) occurred immediately after each band merger, and thus tightly constrains mergers of sources in more than two bands.

If a high quality source could not be merged with any other high quality source, but was found to be located near a medium quality source, then the medium quality source was used to estimate the flux in the band in which a merger was sought. However, the position and positional uncertainty of the high quality source was retained as the parameters of the "primary" band, and no position refinement was executed.

### F. Effective Field Areas

The effective sky coverage of the fields used in the SSC processing is smaller than the areas deduced from the scan geometries of individual grids alone. This reduction in area is due to imperfect overlap of the reference and confirming grids and to non uniform sensitivities across the focal plane detector array.

The nominal grid area is the geometric area covered by the Pointed Observation scans (as specified by the macro type; see Table II.A) minus the two pixel borders (Section III.B), and is given by

$$A = (ny - 4) (nz - 4) * S_y * S_z$$
 III.13

where ny and nz are the number of in-scan and cross-scan pixels in the map, respectively, and  $S_y$  and  $S_z$  are the in-scan and cross-scan pixel sizes as listed in Table II.B. The nominal grid areas for each macro type are listed in Table III.D. For Eqn. III.13, it is assumed that the two grids which comprise the confirming pair have identical areas. This assumption is accurate for about 90% of the grid pairs, but there are examples where one grid may be up to 10 pixels shorter in the in-scan direction than its companion grid. Such discrepancies should amount to no more than a  $\sim 10\%$  effective area loss for those few fields.

The effective area for each SSC field, A', was estimated as the product of the nominal geometric grid area, A, with several correction factors, as follows:

$$A' = A \cdot C_1 (dy, dz) \cdot C_2 (\Delta \theta) \cdot W(y) \cdot W(z)$$
 III.14

Factors  $C_1$  and  $C_2$  are purely geometric corrections which compensate for small positional offsets and scan angle differences between the reference and confirming grids, and will be different for each grid pair. For small offsets these factors are approximated by:

$$C_1 = (1 - 2dy/y) \cdot (1 - 2dz/z)$$
 III.15.a

and

$$C_2 = (1 - \tan \Delta \theta)$$
 III.15.b

where dy and dz are the in-scan and cross-scan grid offsets, y and z are the in-scan and cross-scan lengths, which vary between macro types, and  $\Delta\theta$  is the difference in orientation angle. In general, positional agreements between grid centers is excellent; 99% of the SSC fields have dy < 15" and dz < 45". The range of scan angle differences in the grid pairs is also relatively small, typically < 6 degrees. However, there are a few cases with  $\Delta\theta$  up to ~25 degrees.

Because the local sensitivity is a function of position on the grid, the effective area over which the maximum sensitivity can be attained is smaller than the geometric grid overlap area. To estimate the correction for this effect, the "equivalent widths" of the grids in the in-scan and cross-scan directions, W(y) and W(z), were evaluated. These equivalent widths are defined to be the size that a uniform sensitivity grid would have so that the integral of its sensitivity over its area would be equal to the integral of the actual sensitivity profile over the geometric grid area. For use in equation III.14 the equivalent width is normalized to the geometric width, thus a uniform sensitivity grid would have W(y) = W(z) = 1.0.

To determine the actual sensitivity profiles it was assumed that the net sensitivity could be traced by counting the numbers of sources detected at each position

on the grid; a uniform sensitivity grid representing many observations of randomly distributed sources should exhibit flat source distributions in both the in-scan and cross-scan directions. The actual distributions were evaluated by sorting all of the SSC fields into one of four macro classes defined by the macro scan lengths given in Table II.A, and for each macro class counting the numbers of confirmed sources which occurred at each in-scan and cross-scan grid position. As an illustration, the grid positions of all 12 um sources found in fields with DPS02B, 52B, 62D and 63D are histogrammed in Figure III.C. A roll-off in sensitivity towards the edges of the grids is manifested by the decrease in number of sources/unit area. The sharp peaks in the distributions are the result of the pointing procedure which consistently placed the targeted objects of each observation on the most sensitive detectors.

From these histograms the values of the grid equivalent widths for each macro class were determined using the following equations:

$$W(y) = 1/(ny-4) \cdot \left(\frac{\sum n_p(y) \Delta p_y}{N_{Ymax}}\right)$$
 III.16.a

$$W(z) = 1/(nz-4) \cdot \left(\frac{\sum n_p(z) \Delta p_z}{N_{zmax}}\right)$$
 III.16.b

where  $n_p(y)$  and  $n_p(z)$  are the number of sources found in a given in-scan and cross-scan position bin,  $\Delta p_y$  and  $\Delta p_z$  are the sizes of the position bins in pixels, and Nymax and Nzmax are the mean number of sources found within the most sensitive region of the grid (defined as the region with the highest source density). In equations III.16a and 16b the sums are taken over all position bins, and  $Ny_{\rm max}$  and  $Nz_{\rm max}$  are equal to the level of the "continuum" on either side of the targeted source peaks. In Table III.D the resulting values of W(y) and W(z) are listed for each macro type.

The effective field area was calculated separately for each field in the SSC using Eqn. III.14, and the results are listed in each field header in units of 100 times the area in square degrees. Use of the equivalent width values listed in Table III.D assumes that the reference and confirming grids register perfectly. If the input grid pairs have large scan angle differences,  $\Delta\theta$ , these values may be slightly underestimated. In such fields, there may also be a deficiency of confirmed sources in the corners unrelated to sensitivity, but simply due to the non-overlap of the grids in these areas. This effect would produce a roll-off in the number of sources found at the edges of both the in-scan and cross-scan distributions. Because of the relatively uniform cross-scan distributions of sources found in all macro classes this effect has not been included in these calculations.

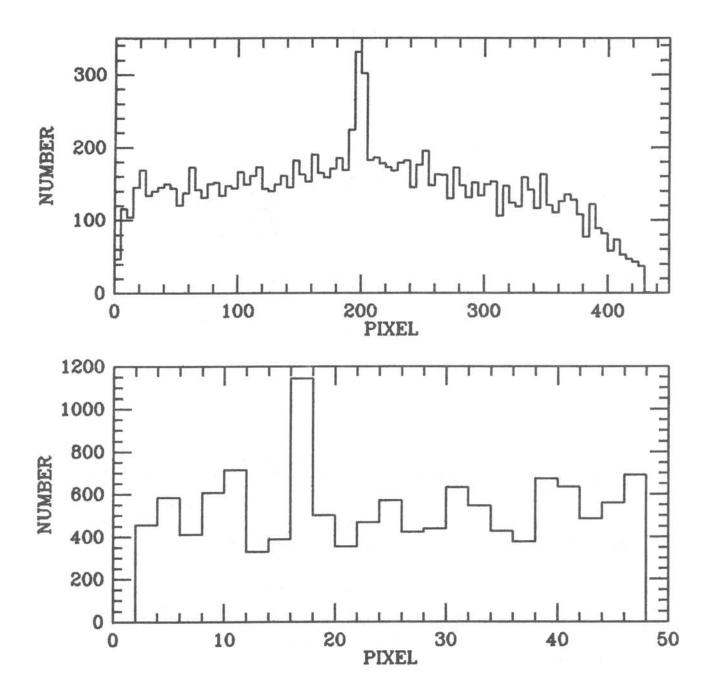


Figure III.C Distribution of sources as a function of in-scan pixel position (upper plot) and cross-scan pixel position (lower plot) for all DPS02B, 52B, 62D and 63D macro observations.

The effective areas given in the field headers are useful for statistical calculations concerning the effective sky coverage of the SSC at a given limiting flux density. In all references to area coverage and source density in this document these areas were used. When the geometric overlap areas of an SSC field are required, the effective areas should be divided by the factors given in Table III.D.

Table III.D. Effective Grid Area Parameters

Macro	Nominal	W(y)	W(z)
Code	Grid Area	1.515	383.5
	(Degree <sup>2</sup> )		
A	0.822	0.81	1.00
В	2.754	0.85	1.00
C	0.822	0.81	1.00
D	2.754	0.85	1.00
E	0.575	0.82	1.00
K	0.562	0.82	1.00
F	0.575	0.74	1.00
M	0.406	0.82	1.00
G	0.575	0.82	1.00
Н	0.575	0.74	1.00
1	0.822	0.81	1.00
J	0.822	0.81	1.00
L	0.822	0.81	1.00

### G. Identification of Overlapping Fields

The targeted fields in the Pointed Observation program occasionally overlapped one another. In particular, the region near NGC 6543 (the primary reference source for IRAS calibrations), the Large Magellanic Cloud, and the Small Magellanic Cloud were observed many times during the course of the mission. To identify cases where grids overlapped, pixel positions of nearby grids were mapped onto the grid coordinate system of each grid used in the catalog. All fields where more than 5% of the area of the reference grid overlapped the reference grid of another field are listed in Appendix A. The amount of overlap (calculated on the basis of integer pixels) is given in units of square arc minutes.

The NGC 6543 fields are treated as a special case by this catalog. Over the course of the mission, more than 100 Pointed Observations of that object were made. These observations have been coadded and analyzed by Hacking and Houck (1986). Since their study of this region goes to much fainter levels than this catalog, we have chosen to delete these fields from the Serendipitous Survey.

### H. Associations With Other Astronomical Catalogs

Positional associations of SSC sources were made with objects in other astronomical catalogs; the processing was carried out at the IPAC. Associations for the SSC used the same catalogs and search boxes as the PSC (cf. Main IRAS Supplement, Chapter V.H.9 for details of catalogs, search radius and catalog information), with the following exceptions:

- 1. Positional associations are made with the PSC when SSC and PSC positions agree to within 60 ". The PSC catalog is assigned catalog number 41.
- 2. The search box for associations with high precision stellar catalogs, 13 (SAO), 15 (Bright Star catalog), and 24 (Two Micron Sky Survey with Improved Positions) is  $28" \times 180"$  rather than the  $16" \times 90"$  search box used for associations in the PSC.
- 3. The search radius for associations with the Dearborn catalog is increased to 120".

### IV. ANALYSIS OF THE SSC

The field-by-field organization of the SSC reflects the great diversity in the Pointed Observation program on which it is based. Because of the range of observational properties represented in the SSC fields, it is difficult to quantify broad statistical characteristics of the catalog as a whole. Therefore, for the purpose of this analysis it proved necessary to define a high latitude subset of relatively uncrowded, non- overlapping fields. Most of the analysis which follows was confined to this subset of the SSC although many of the results do pertain to the catalog as a whole. The subset of fields was selected as follows:

- (a) field centers were located at | b | > 30°,
- (b) only one field was included from each group of overlapping fields, and that field was selected by starting with a right ascension ordered list of fields and selecting the first field from each group of overlapping fields as listed in Appendix A,
- (c) only those fields were included with surface densities of 60  $\mu$ m sources less than 20 sources/deg.<sup>2</sup>.

Although there are 721 fields which satisfy condition (a), the high latitude subset is comprised of only 450 fields containing 5100 individual sources. According to condition (b) there were 133 overlapping fields included and 206 excluded; condition (c) excluded 70 fields to avoid further undesirable confusion effects. Seventy-seven fields are located in the Magellanic clouds and were excluded from the high latitude subset either by condition (b) or (c). The subset contains 1245, 614, 2765 and 2427 sources at 12, 25, 60, and 100  $\mu$ m, respectively, and the combined effective area of the fields is 271 deg.<sup>2</sup>.

### A. Confirmation, Reliability and Sensitivity Limits

The confirmation strategy, on which reliability and accuracy rests, was finely tuned before the final processing was begun. In addition, the character of the raw data and the final results of the data processing determine the "confirmation rate" measured in each band. This parameter indicates the degree of difficulty encountered in separating reliable astronomical sources from the various sources of noise and interference. The question of reliability in the SSC refers both to the reliability of the confirmed sources within each of the four bands, and to the accuracy of band merging in producing merged sources.

The completeness level in the SSC varies widely from field to field because of the large dispersion in the median noise levels, as illustrated in Figures IV.A.1-4. Rather than attempting a global estimate of completeness, which would be of little value, the limiting flux densities in each band are determined for the high latitude subset of fields. Figures IV.A.1-4 show the relatively narrow distribution of median noise levels for these fields.

### A.1 Confirmation Tuning and Confirmation Rates

The goal of the entire confirmation procedure was to produce lists of highly reliable point sources. Therefore, confirmation itself, which requires that a source must appear at nearly the same location and have a similar flux level in two independent observations of each field, is the first level of reliability assurance for sources in individual bands.

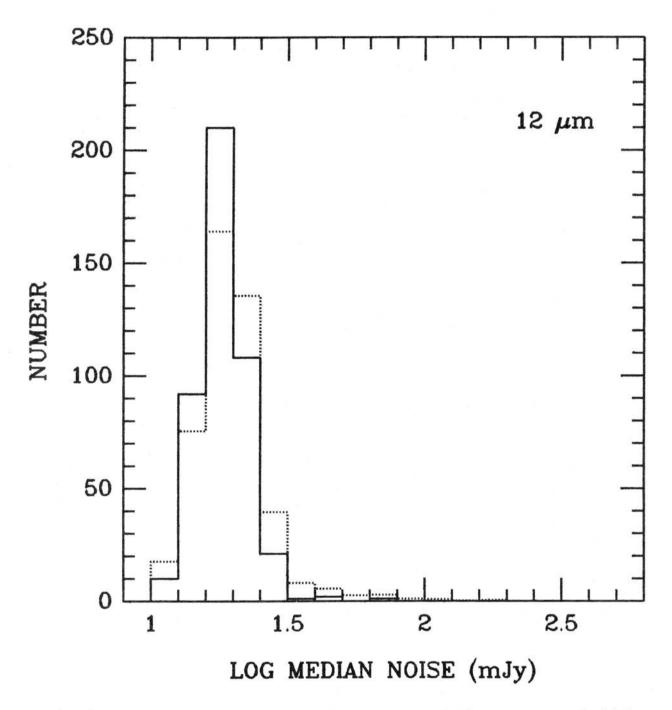


Figure IV.A.1 Number of fields versus median noise; solid line represents the high latitude subset of fields, the dotted line represents the complete set of fields with the verticle scale divided by 4.

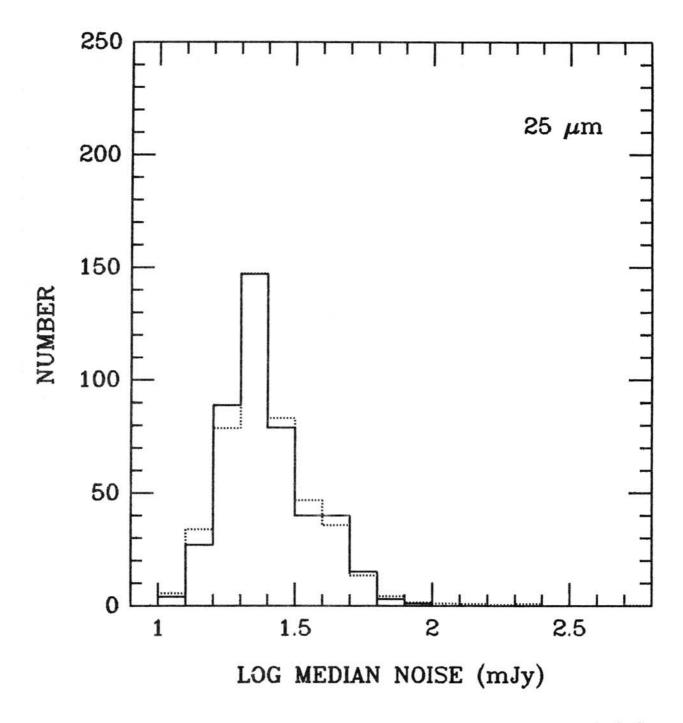


Figure IV.A.2 Number of fields versus median noise; solid line represents the high latitude subset of fields, the dotted line represents the complete set of fields with the verticle scale divided by 4.

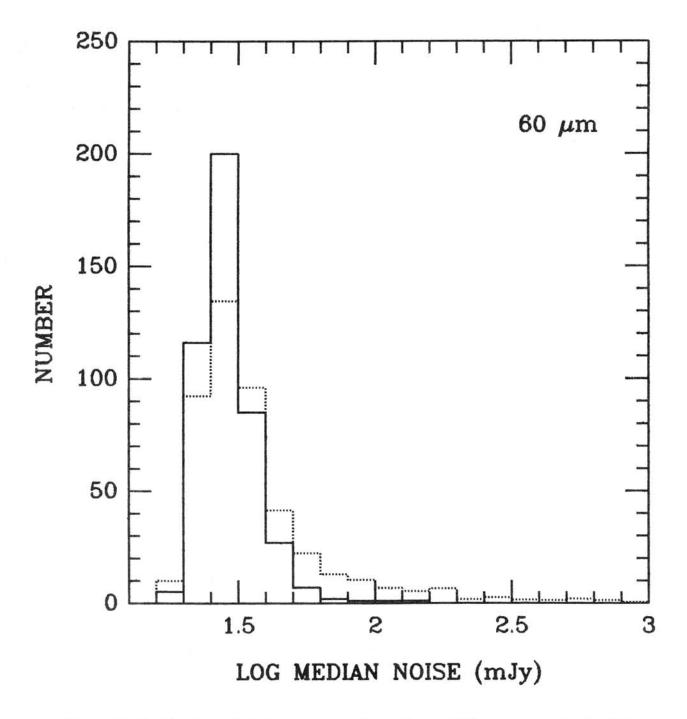


Figure IV.A.3 Number of fields versus median noise; solid line represents the high latitude subset of fields, the dotted line represents the complete set of fields with the verticle scale divided by 4.

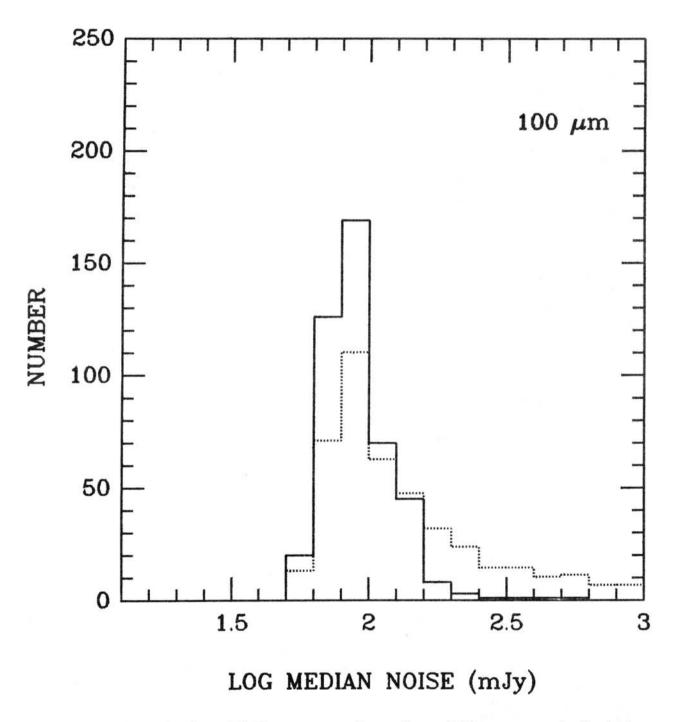


Figure IV.A.4 Number of fields versus median noise; solid line represents the high latitude subset of fields, the dotted line represents the complete set of fields with the verticle scale divided by 4.

The process used to optimize or "tune" the confirmation parameters (Section III.B) is in essence a process to make the natural trade-off between reliability and sensitivity. Data from 10 randomly selected fields, which were observed a minimum of three times during the Pointed Observation program, were co-added to yield a higher net sensitivity than was achieved for the SSC. Lists of sources from these fields were taken to constitute "truth-tables" against which the sources produced by the SSC processing of these fields could be compared. It is quite important to note that, although the co-addition of independent observations decreases the effective detector noise in a field allowing the detection of fainter sources, crowded co-added fields can still contain fixed-pattern noise caused by source confusion.

During the tuning procedure several confirmation parameters, including the positional windows, the flux ratio limits, minimum local signal-to-noise, and minimum correlation coefficients were varied. The sources confirmed using selected values of these parameters were compared to those in the deeply co-added fields. A source which was identified in both the SSC processing and the co-added field was considered verified. Sources which appeared in the SSC lists but failed to be detected in the co-adds were taken to be spurious. Those sources which were included in the deep co-adds and not the SSC were noted, and follow-up investigation was carried out to ascertain why they were not confirmed for the SSC.

Figures IV.B and IV.C illustrate the results of two such co- additions of fields corresponding to the SSC fields with reference grid numbers 13783 and 8595. Field 13783 covers a mid- latitude region of low source density. Nine individual observations were co-added to produce the contour maps which show the positions of 12 and 60  $\mu$ m sources for this field. Three observations were co-added to produce the 12  $\mu$ m map of field 8595; this very crowded field lies only a few degrees from the galactic plane. Single contours on the 12  $\mu$ m maps represent sources with flux densities of 20 and 32 mJy for 13783 and 8595 respectively, and the single contours on the 60  $\mu$ m map of 13783 indicate 90 mJy sources. Each additional contour represents an isophote a factor of three higher. Superimposed on the source contours are the locations of SSC source identifications.

The parameters were tuned until all spurious sources were eliminated, that is, until the reliability level of the test fields was nearly 100%. The final adopted parameters (cf. Section III.B) were conservative in the sense that some sacrifice of sensitivity was made, but they were consistent with the goal of emphasizing reliability.

The confirmation rate for an SSC field may be defined as the ratio of the number of confirmed sources in the field to the number of extractions in the reference grid. Based on results using the final confirmation parameters, the confirmation rates for fields in the high latitude subset are 0.12 at 12  $\mu$ m, 0.09 at 25  $\mu$ m, 0.39 at 60  $\mu$ m and 0.41 at 100  $\mu$ m. These rates vary with wavelength in a manner roughly consistent with the simplified view that for a constant signal-to-noise ratio the confirmation rate should increase with an increase in the surface density of sources until confusion dominates. As expected, using the observed source densities from Table IV.G, the ratios of confirmation rates to the source densities are, in order of increasing wavelength, 0.03, 0.04, 0.04 and 0.05. The relative constancy supports the foregoing interpretation despite the possible effects of confusion at 100  $\mu$ m and the presence of highly non-random noise at 12  $\mu$ m.

# A.2 Reliability of Confirmed Sources

Final reliability testing was carried out by comparing the source lists of an additional 11 randomly selected deep co-added fields with the SSC source lists. These test fields spanned a representative range of source density and position on

the sky. In the combined 21 test fields, the SSC processing confirmed 572 sources: 139 at 12  $\mu\text{m}$ , 91 at 25  $\mu\text{m}$ , 198 at 60  $\mu\text{m}$  and 144 at 100  $\mu\text{m}$ . Of these, only 5 sources were found to be spurious. One 60  $\mu\text{m}$  source in a low density, high galactic latitude field, with a reported flux density of 160 mJy had no counterpart in the deep co-adds. The remaining 4 spurious confirmations, 3 at 25  $\mu\text{m}$  and 1 at 60  $\mu\text{m}$ , were all found in a single high density field centered on a dense molecular cloud region.

For non-complex fields the reliability testing indicates that the confidence level for the SSC confirmations in all bands is >98%. In high density regions, the reliability is compromised, as evidenced by the 4 spurious confirmations. It is due to the effects of confusion operating on both the source extractions and the confirmation processing.

# A.3 Band Merging Reliability

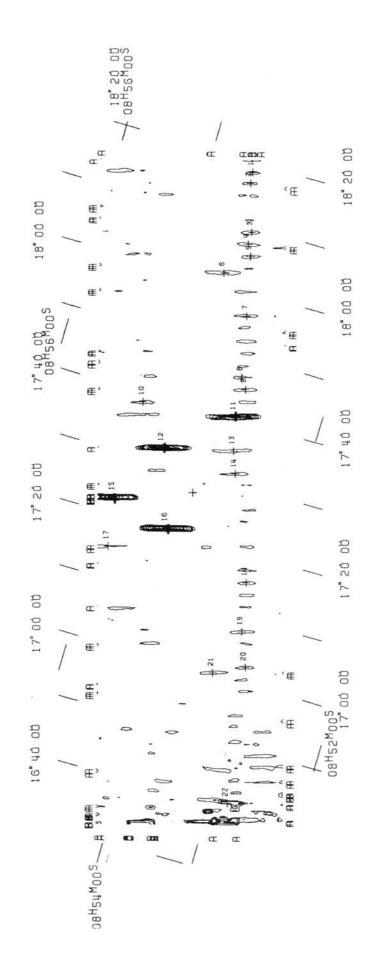
Because band merging windows are based on positional uncertainties which were refined during the confirmation procedure, the band merge process is quite conservative in the sense that merges are more likely to be missed rather than to be performed incorrectly. Preliminary analysis of the reliability level of the band merging was carried out graphically during the examination of the deep coadded field outputs. Among the 572 single band sources in the 21 test fields there are 133 reported merged sources in the SSC processing. Based on their positional proximity, there were four instances where sources in one or two bands failed to merge with the proper source in another band, and in one instance what should have been a single source detected in four bands was reported as two sources, each detected in two bands. *On no occasion were spurious band merges found.* 

The positional testing for band merge accuracy does not take into account whether a particular merge is physically reasonable. The flux-flux plots shown in Figures IV.D, IV.E and IV.F clearly illustrate that for mid- to high latitude fields, no grossly nonphysical matches were made during the processing. This is further supported by the color-color plots shown in Figures IV.G.1-2. None of the sources detected in at least 3 bands examined in the analysis fields appear to lie outside the color regions consistent with known astronomical sources.

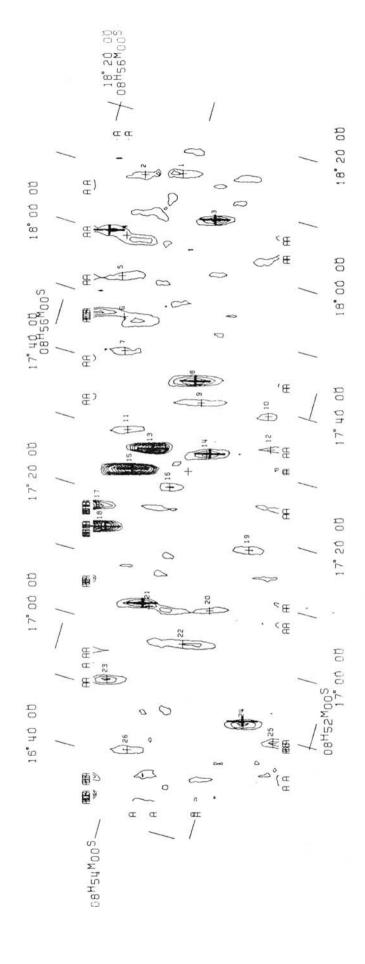
The very high quality of the band merge processing in the SSC is a consequence of the goal of reliability. It was accepted that some fraction of the true band merges would be missed in order to avoid spurious ones. The user is encouraged to examine nearby sources within the field of interest to search for additional band merge candidates. All information necessary to reconstruct source positions in the individual input grids, or to construct new band merges with less conservative windowing has been retained in the SSC source listings.

#### A.4 Sensitivity Limits

The analysis of the deep co-added fields was also used to form the first of two sensitivity estimates for the SSC. All sources which were found in the "truth-table" source lists, but were not reported in the SSC fields were summarized. The flux density of the brightest true source missed in each band should then define the sensitivity limit for that field. The brightest sources which failed to be confirmed in the test fields had flux densities of 94, 185, 110 and 400 mJy at 12, 25, 60 and 100  $\mu$ m, respectively and, for the four bands in the same order, the faintest sources confirmed were at flux densities of 65, 70, 80, and 250 mJy.



12  $\mu$ m FLUX filtered map of a low source density region. Confirmed 12  $\mu$ m sources indicated by heavy crosses; light crosses with numbers indicate source extractions prior to confirmation processing. Figure IV.B.1



 $60 \mu m$  FLUX filtered map of a low source density region. Confirmed  $60 \mu m$  sources indicated by heavy crosses; light crosses with numbers indicate source extractions prior to confirmation processing. Figure IV.B.2

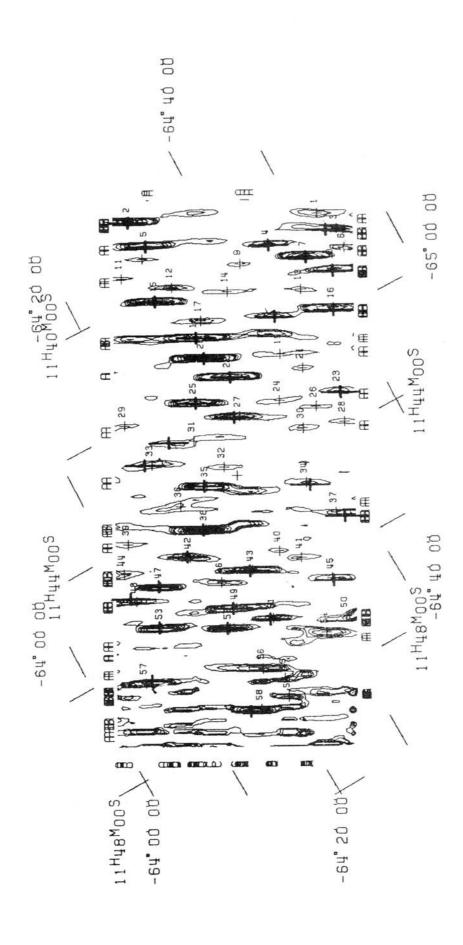


Figure IV.C 12  $\mu$ m FLUX filtered map of a high source density region. Confirmed 12  $\mu$ m sources indicated by heavy crosses; light crosses with numbers indicate source extractions prior to confirmation processing.

Figures IV.H.1-4 represent the differential Log N vs Log F relationships at 12, 25, 60 and 100  $\mu m$  for all sources in the high latitude subset. A second estimate for the sensitivity limit of the highest quality fields in the SSC may be deduced from the turnover point at which the observed Log N vs Log F curves deviate from simple power laws. From these figures the formal 90% completeness limits occur at approximately 120  $\pm$  10 mJy for 12  $\mu m$  sources, 150  $\pm$  15 mJy at 25 um, 120  $\pm$  10 mJy at 60  $\mu m$  and 440  $\pm$  50 mJy at 100  $\mu m$ , values which are reasonably consistent with the estimates made from the examination of the deep co-added fields. Furthermore, the detection threshhold, defined here as the faintest sources confirmed, is the same for both the deep co-added fields and the larger subset of high latitude fields.

The Log N vs Log F plots of Figure IV.H illustrate several complications introduced by the selection effects and biases of the SSC. The structure seen in these plots is not necessarily a true representation of the average infrared sky at these flux levels since corrections have not been applied for a number of known observational effects including: targeted sources, variation in the sensitivity levels and source confusion.

#### **B.** Association Statistics

Table IV.A contains a summary of the number of sources in the SSC which have been positionally associated with objects in various celestial catalogs. The catalog identification numbers are as listed in Table X.B.4 of the Main IRAS Supplement and in Section III.H of this document.

A total of 16,599 SSC sources are associated with objects in one or more of the reference catalogs. Of the associated sources in the SSC, only 11,129 are associated with the PSC. Therefore, ~75% of the detections in the SSC are "new" infrared sources, in the sense that they are not found in the PSC. The actual number of unique new sources is somewhat smaller due to the presence of redundant sources from overlapping fields.

Table IV.A. Associations with Various Catalogs

Catalog	Number in SSC	Catalog	Number in SSC
1	687	19	35
2	1003	20	109
3	297	21	24
4	312	22	238
5	516	23	2150
	537	24	117
6 7 8 9	286	25	18
8	30	26	55
9	545	27	117
10	1215	28	61
11	60	29	261
12	860	30	59
13	2906	31	61
14	821	32	1106
15	482	39	1770
16	538	40	869
17	155	41	11129
18	154		

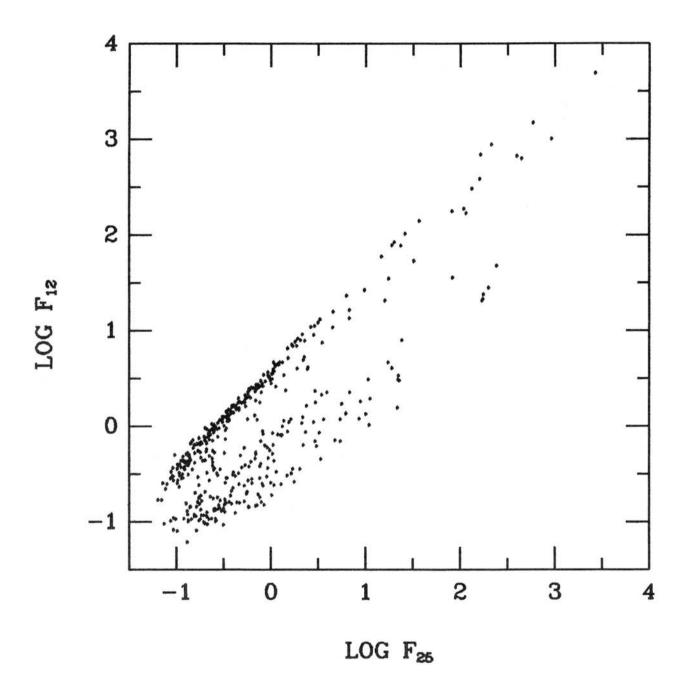


Figure IV.D Flux density, in Jy, at 12  $\mu$ m versus 25  $\mu$ m for sources at lbl > 30°.

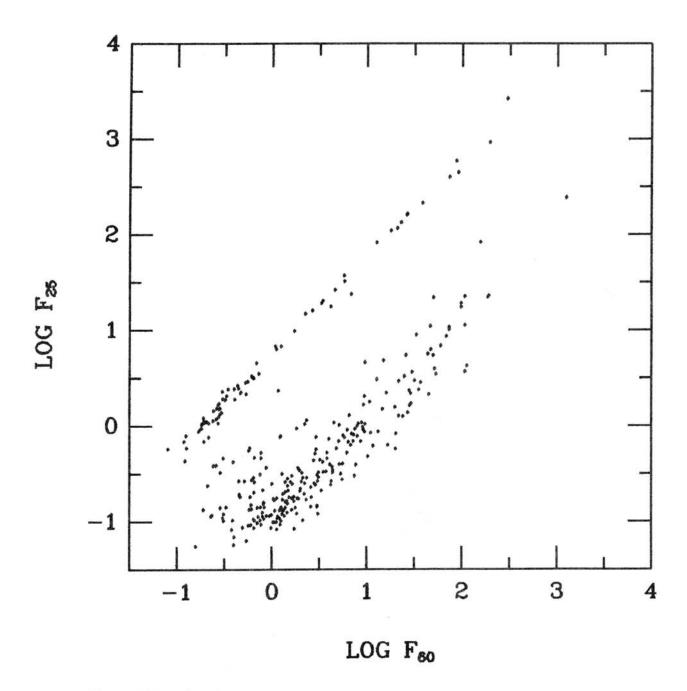


Figure IV.E Flux density, in Jy, at 25  $\mu m$  versus 60  $\mu m$  for sources at lbl > 30°.

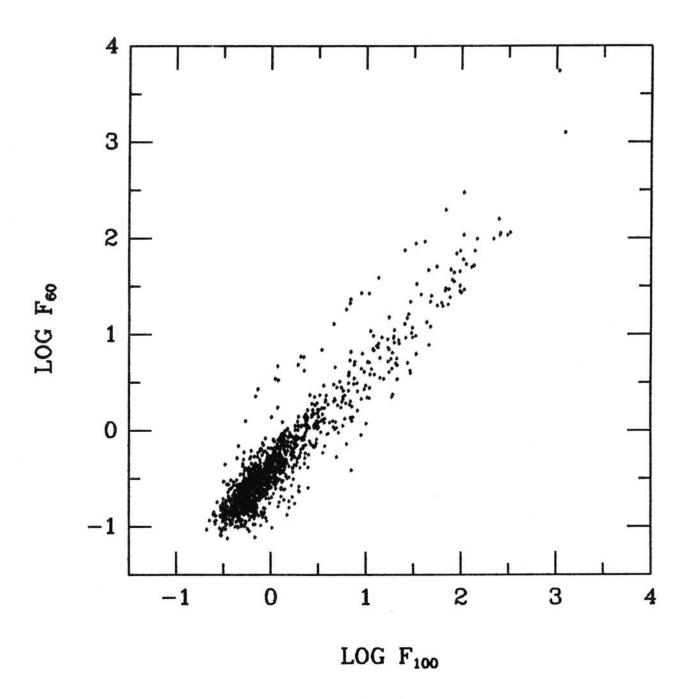


Figure IV.F Flux density, in Jy, at 60  $\mu$ m versus 100  $\mu$ m for sources at lbl > 30°.

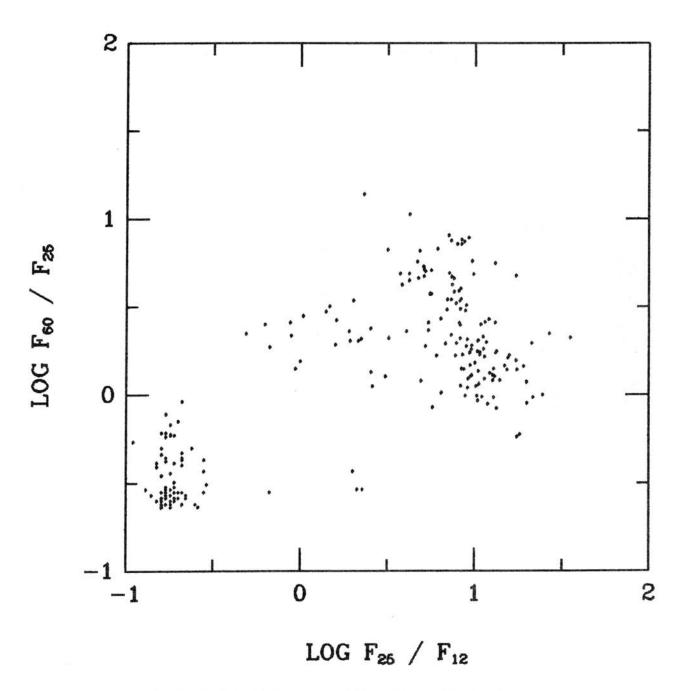


Figure IV.G.1 Color-color plot for high latitude subset sources.

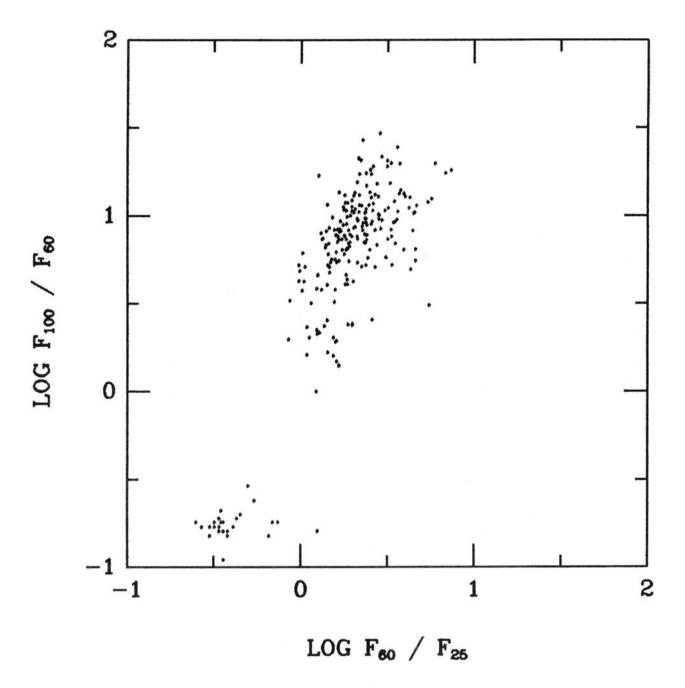


Figure IV.G.2 Color-color plot for high latitude subset sources.

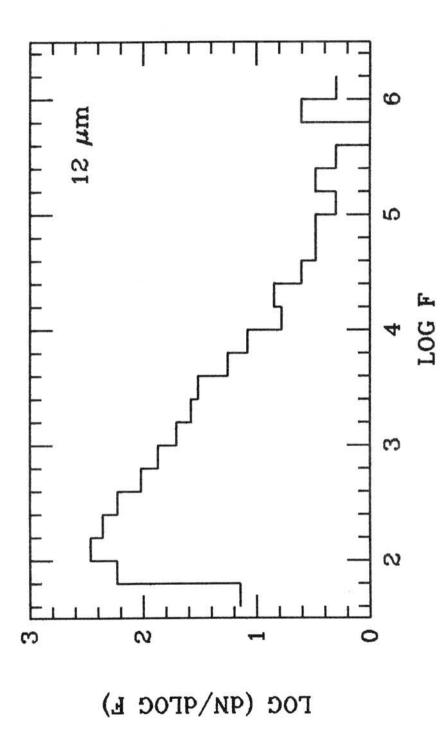


Figure IV.H.1 Differential Log N versus Log F relation for high latitude subset sources; flux density in mJy.

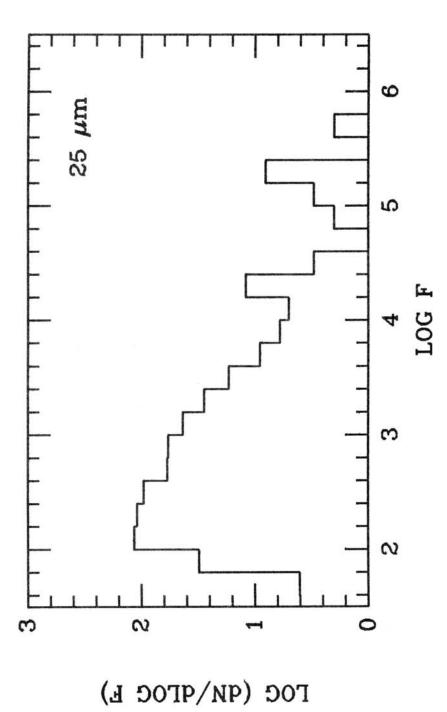


Figure IV.H.2 Differential Log N versus Log F relation for high latitude subset sources; flux density in mJy.

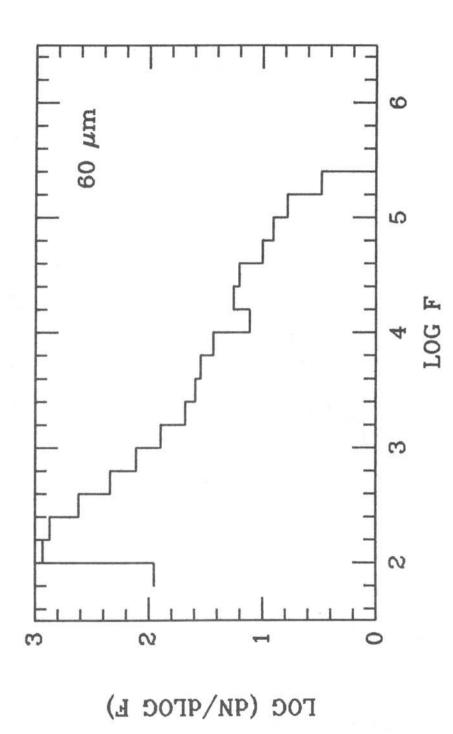


Figure IV.H.3 Differential Log N versus Log F relation for high latitude subset sources; flux density in mJy.

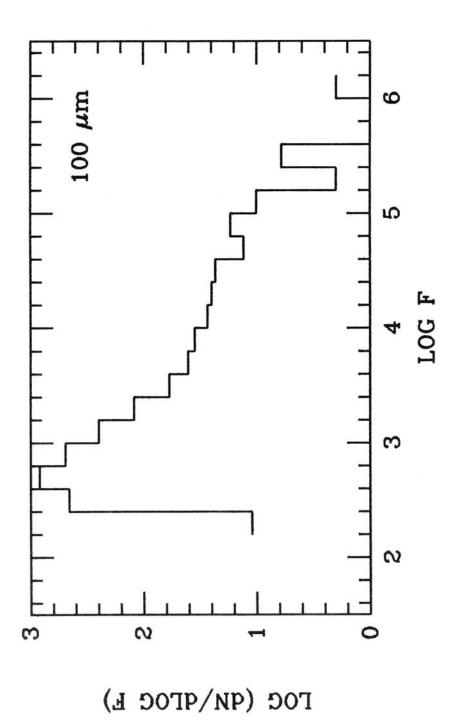


Figure IV.H.4 Differential Log N versus Log F relation for high latitude subset sources; flux density in mJy.

## C. Absolute Positional Accuracy

The Pointed Observation Users Guide (Young et al. 1985) reports that individual Pointed Observations yield 12  $\mu$ m positions of SAO stars which have an absolute accuracy of 1 sigma ~7 arcsec in the in-scan direction and ~35 arcsec cross-scan. Since the SSC effectively averages two independent observations during the confirmation process, positional accuracy should improve by a factor of  $\sqrt{2}$ . In practice, however, systematic effects can degrade this improvement. Such effects include errors in pointing repeatability, and the influence of other bands during positional updating for band merged sources.

To test the actual absolute accuracy of the source positions in the SSC, the reported positions of all sources at lbl > 30 deg. which were associated with objects in the SAO Star Catalog and the subset of the UGC which have accurate positions (Dressel and Condon 1976) were compared with the positions from the respective catalogs. The positions of band-merged SSC sources were evaluated as weighted means of the positions of the source in each individual band, such that the final position was most strongly influenced by the band with the highest signal-to-noise ratio. Therefore, the precision of the coordinates of SSC sources associated with SAO catalog stars is indicative of all 12  $\mu$ m dominant sources. Equivalently, those sources associated with UGC galaxies will represent most 60  $\mu$ m dominant sources. The positional differences between SSC and individual catalog sources were computed for the in-scan and cross-scan directions. Figures IV.I and IV.J show histograms of the positional differences for the SAO stars and UGC galaxies, respectively.

The distribution of in-scan and cross-scan position differences are well-approximated by Gaussian functions. To characterize these distributions, recursive fits were made using combinations of a Gaussian function and a constant "background" term. The background term accounts for the possible occurrences of chance associations of SSC sources with catalog objects, sources with uncharacteristically bad positions, or the rare spurious source. Table IV.B contains a listing of the best-fit parameters for the in-scan and cross-scan position distributions for the SAO and UGC sources. Sigma represents the half-width of the Gaussian and thus the absolute positional accuracy relative to the catalog positions. The level of the background term in sources per separation bin is denoted NB. For the associations with SAO stars, these bins were 2" in the in-scan direction and 3" in the cross-scan direction. In the case of the UGC galaxies, they were 3" in-scan and 5" cross-scan. For comparison, the table also shows the positional accuracy according to the Main IRAS Supplement for PSC sources fainter than 1.2 Jy at 12  $\mu$ m and fainter than 1.9 Jy at 60  $\mu$ m.

The positional uncertainties listed in Table IV.B should be taken as the 1 sigma dimensions of the uncertainty ellipses of 12 and 60  $\mu m$  SSC sources. Inspection of Figures IV.I and IV.J indicates that there are significant numbers of sources with positional discrepancies out to several sigma, especially in the cross-scan direction. A small number of these (<10%) are due to bad associations. The remainder may result from poor position reconstruction in the confirmation and band merging processing because of significant scan angle differences between the two input grids. Because of the large tails of the distributions, the user is recommended to use greater than 3 sigma positional uncertainties when making tests of source locations in the SSC. Specifically, at 12  $\mu m$  the search box should be 30" x 180" and at 60  $\mu m$  it should be 60" x 140", with the orientation as indicated in the appropriate field header.

Table IV.B. Absolute Positional Accuracy of SSC Sources

	Sigma (SSC) (Arcsec)	NB	Sigma (PSC) (Arcsec)
SAO Stars			
In-scan	6.5	0	2.8
Cross-scan	25.5	4	15.6
UGC Galaxies <sup>1</sup>			
In-scan	8.8	5	5.7
Cross-scan	23.5	3	15.2

NOTE: <sup>1</sup> This group includes only those whose accurate positions were measured by Dressel and Condon (1976).

## **D. Photometric Accuracy**

#### D.1. Accuracy of Relative Flux Densities

A measure of the relative flux accuracy of the SSC can be obtained by comparing the fluxes of merged sources in different bands. Figures IV.D - V.F show these relationships for 12 - 25 um, 25 - 60  $\mu$ m and 60 - 100  $\mu$ m band combinations for the high latitude subset of SSC sources. These results should be compared to the corresponding plots in the Main IRAS Supplement, Figures VII.D.1,2,3. Over the full range of SSC flux densities, there are no obvious departures from the expected flux ratios. Furthermore, the confinement of most points below the boundary corresponding to an infinitely hot blackbody provides confidence in the accuracy of the absolute calibrations used in the SSC processing.

# D.2 Accuracy of Absolute Flux Densities

The absolute calibration of the SSC is based on the same calibration sources and procedures used in the PSC (cf. Section VI.C of the Main IRAS Supplement). In this section a comparison is made between the photometry of a specially selected and processed set of stellar observations and the catalog values for these stars from the SSC and the PSC version 2.0. The method by which the magnitudes of these stars were obtained and the conversion from flux density to magnitude are described in the Main IRAS Supplement.

Table IV.C includes the magnitudes of eleven selected stars which were observed using the macro DPS61D. The observations were carefully hand-reduced from the raw data to provide an independent check of the entire processing chain. Nine of these stars are bright enough to be measured in all four bands and five are included in Table VI.C.I in the Main IRAS Supplement. The differences between the hand calibrated magnitudes and those found in the SSC are tabulated along with the same results for the PSC version 2.0. As explained in the IRAS Circular (Nov. 1986) which accompanied version 2.0 of the PSC, systematic errors in the PSC at low flux densities were corrected in this version using the preliminary SSC results to "tune" the correction algorithm. This procedure did not affect the PSC flux densities above 2.0 Jy. The average magnitude differences, shown at the bottom of the table, indicate that both catalogs share the same calibration and the largest errors are at 100  $\mu$ m. At 12  $\mu$ m the difference of -0.053 magnitudes between the calibration stars and

**Table IV.C Magnitudes of Calibration Stars** 

Star	Wavelength (μm)	m <sub>cal</sub>	△m <sub>ssc</sub> 1	∆m <sub>psc</sub> 2
IRC 10011	12	-3.635	-0.158	-0.011
	25	-5.125	-0.151	-0.104
	60	-5.26	-0.01	0.08
	100	-5.44	-0.02	0.03
Eri	12	1.616	-0.038	0.030
	25	1.406	0.012	0.025
	60	-0.096	0.045	-0.036
	100	-1.537	0.110	-0.023
3 Pic	12	2.751	0.003	0.066
	25	0.068	0.016	0.017
	60	-2.729	-0.001	0.028
	100	-3.464	0.084	-0.010
z CMi	12	-0.742	-0.020	-0.030
	25	-0.715	-0.019	0.007
	60	-0.798	-0.054	-0.060
	100	*****	****	*****
3 Pup	12	-2.016	-0.041	-0.020
	25	-2.915	-0.041	0.058
	60	-3.086	-0.029	-0.050
	100	-2.968	0.087	0.006
Com	12	1 107	0.022	0.000
3 Gem	25	-1.197 -1.179	-0.023 -0.017	0.009
	60	-1.173	0.051	0.014
	100	-1.306	0.016	-0.072
P	12	2.15.1	0.079	0.064
Воо	12 25	-3.151 -3.092	-0.078 0.005	0.064 -0.004
	60	-3.127	-0.042	-0.004
	100	-3.183	0.033	-0.116
Time.	12	0.013	-0.015	0.027
Lyr	25	-0.203	0.005	-0.041
	60	-1.950	0.031	0.005
	100	-3.049	0.067	-0.002
• • • • • • • • • • • • • • • • • • • •	12	2.270	0.022	0.020
R Lyr	12	-2.370	-0.023	0.020
	25 60	-2.517 -2.710	0.006 -0.063	0.019 -0.059
	100	-3.303	-0.078	-0.133
\$ 20			0.000	0.000
Aql	12	0.174	-0.029	-0.063
	25 60	0.191	0.011 0.051	0.014
	100	0.303	0.031	0.033
		2 400	0.150	0.000
3 Gru	12	-3.490	-0.156	-0.088
	25	-3.459 -3.526	-0.077 -0.037	0.038
	60 100	-3.572	0.094	-0.051
				12.00=
Vavelength (μm)	12	25	60	100
<∆m <sub>ssc</sub> >	-0.053	-0.025	-0.005	+0.021
	(-0.023) <sup>3</sup>	(-0.007) <sup>3</sup>	(+0.004) <sup>3</sup>	(+0.048) <sup>3</sup>
itd.Dev.	0.017	0.015	0.013	0.026
:∆m <sub>psc</sub> > td.Dev.	+0.000	+0.004	-0.005 0.018	-0.042 0.019
	+0.053	+0.025	+0.001	-0.085
m <sub>ssc</sub> -m <sub>psc</sub> > td.Dev.	0.017	0.014	0.014	0.020

<sup>&</sup>lt;sup>1</sup> The difference between the calibrated magnitude and the SSC magnitude:  $m_{cal} - m_{ssc}$ .

<sup>2</sup> The difference between the calibrated magnitude and the PSC version 2.0 magnitude:  $m_{cal} - m_{psc}$ .

 $<sup>^3</sup>$  < $\Delta m_{\rm SSC}>$  excluding IRC 10011, lpha Boo, and eta Gru.

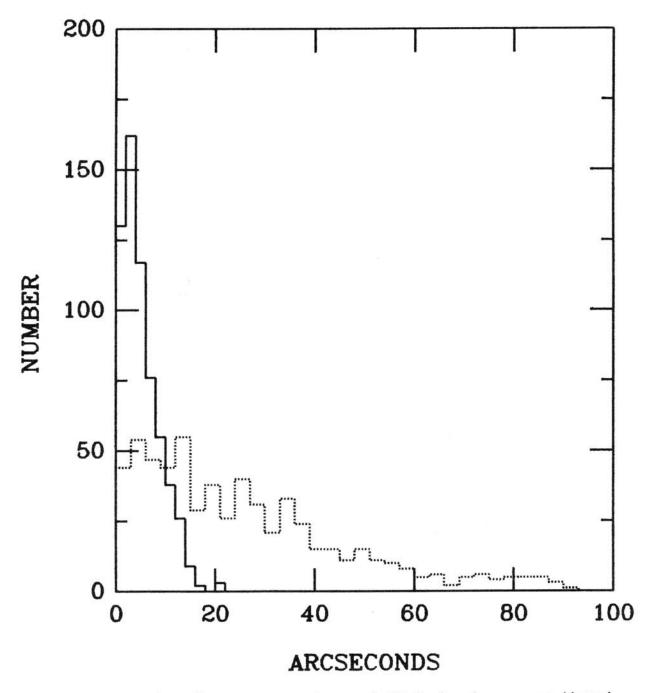


Figure IV.I Number of sources versus in-scan (solid line) and cross-scan (dotted line) separation between SSC position and SAO position for associated sources at |b| > 30°.

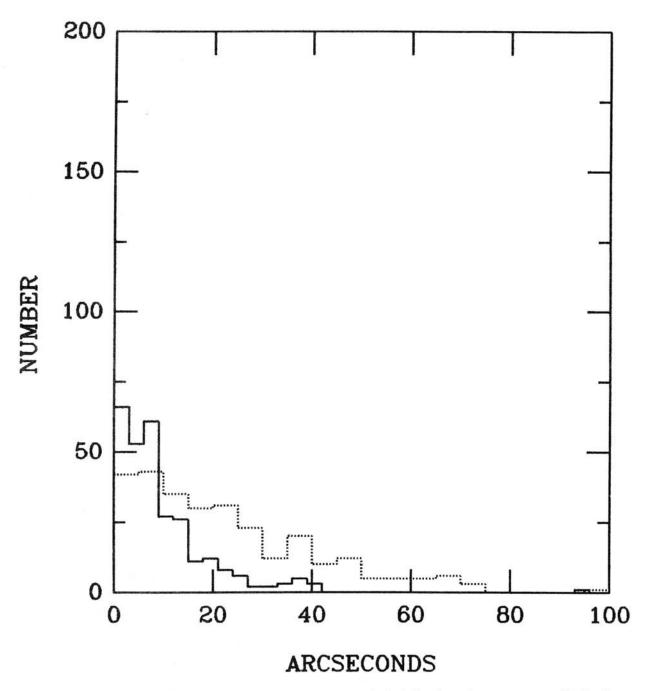


Figure IV.J Number of sources versus in-scan (solid line) and cross-scan (dotted line) separation between SSC position and selected UGC position for associated sources at  $|b| > 30^{\circ}$ .

their SSC magnitudes is influenced significantly by the three brightest stars in the sample; if these three objects are removed the difference is reduced to -0.02 magnitudes, suggesting an uncorrected systematic error at 12  $\mu$ m magnitudes brighter than -3. Since the SSC is to be used for much fainter sources and the magnitudes of virtually all such bright objects are found in the PSC, this potential errors has not been corrected.

A second comparison between the two catalogs is illustrated in Figures IV.K.1-4. Here the flux densities of a large sample of objects common to both catalogs are ratioed, displaying the dispersion withint each sample and providing another measure of the systematic errors between the two catalogs. Again, the overall agreement is quite good with percentage differences in the mean of -5.2%, 1.1%, 4.2% and 9.6% at 12, 25, 60 and 100  $\mu$ m, respectively.

# D.3 Flux Density Uncertainties

Three measures of the flux density uncertainty for each band in which a detection is reported are included in each SSC source listing: the relative flux density uncertainty,  $\langle n \rangle / \langle F \rangle$ , the local signal-to-noise ratio, LSNR, and the flux density ratio,  $F_c/F_r$  (Section III.C.2). Each of these parameters offers an independent indication of the uncertainty in the flux densities.

The relative flux density uncertainty in each band is the most accurate assessment of the noise level relative to that of the signal because it is determined from the median noises of the two input fields. As discussed in Section II.C, the median noise represents the average noise for the entire field and is therefore less susceptible to isolated events such as residual radiation hits. Figures IV.L.1-4 show the relative flux density uncertainty as a function of flux density in the four IRAS bands for the high latitude subset of fields. In the 12 and 25  $\mu m$  bands and for most sources at 60  $\mu m$  the relative flux density uncertainty scales roughly as the inverse square root of the flux density, as expected when the uncertainty is primarily driven by detector noise. At 100  $\mu m$ , the uncertainty follows an 1/F relationship because other sources of noise affect the median noise measurement, in particular the presence of cirrus throughout the Pointed Observation fields and confusion noise in complex regions.

The local signal-to-noise ratio gives a similar estimate of statistical quality in most fields, but it is very sensitive to small-scale structure in high source density fields. As a consequence, the LSNR often overestimates the true flux density uncertainty.

The ratio of flux densities of a source from the two input grids provides a measure of both the intrinsic uncertainty in the flux density and the potential error produced by systematic differences between the two individual scans. In some cases the source brightness may have changed during the time between the two observations. Figures IV.M.1,2 show histograms of the flux density ratios for sources in the high latitude subset. Sources brighter than 0.5 Jy at 12, 25, and 60  $\mu$ m and than 1.0 Jy at 100  $\mu$ m are presented in Figure IV.M.1, while fainter sources are presented in Figures IV.M.2. These figures illustrate that systematic differences between the fluxes reported from the two input grids of each pair are minimal. The full width at half maximum (FWHM) of the distributions offer a measure of the characteristic flux density uncertainties for the two brightness regimes. In Table IV.D are listed the relative uncertainties calculated by measuring  $10^{\rm FWHM/2}$ - 1 for the bright and faint flux ratio distributions. While the actual flux density uncertainty is a continuous function of the flux level, these values represent additional guidelines by which the general photometric quality of arbitrary SSC sources may be estimated.

Table IV.D. Relative Flux Uncertainty
Estimated From Flux-Ratio Distributions

Source		$\sigma(F)$	$_{\rm r}/{\rm F}_{\rm c})$	
Brightness	12 μm	25 μm	60 μm	100 μm
High 1	0.06	0.06	0.08	0.12
High <sup>1</sup> Low <sup>2</sup>	0.13	0.15	0.18	0.19

#### NOTES:

# E. Sky Coverage and Source Densities

The IRAS Serendipitous Survey utilizes the results from 1813 Pointed Observation fields. The grid pairs which comprise these fields were selected by the guidelines stated in Section III.A. In Table IV.E are listed the number of fields as a function of macro type and galactic latitude. The distribution of fields on the sky is shown in Figure II.A.

Table IV.E Distribution of Fields with Macro Type and Galactic Latitude

Macro			N(bl)		
Code	<10°	10-30°	30-50°	>50°	Total
A	174	258	213	143	788
В	3	2	21	2	28
C	54	48	15	10	127
D	16	9	0	0	25
E	13	23	20	9	65
F	56	37	29	12	134
M	1	0	0	0	1
Н	62	100	69	17	248
ï	33	160	113	24	330
i	9	29	19	5	62
Ĺ	2	3	0	0	5
Total	423	669	499	222	1813
Effective					
Area (Degree <sup>2</sup> )	255.8	401.4	318.0	132.6	1107.7

The effective sky coverage, also listed in Table IV.E, is the area sampled at a uniform sensitivity near the maximum of the survey (cf. Section III.F. An effective area of  $1108~\rm deg^2$  on the sky is sampled by the SSC. The nominal sampling area of the SSC, that is, the purely geometric coverage of the fields, is approximately  $1400~\rm deg^2$ .

 $<sup>^{1}</sup>$  F  $_{\nu}$  > 0.5 Jy at 12, 25 and 60  $\mu m$  and > 1.0 Jy at 100  $\mu m$  .

 $<sup>^{2}</sup>$  F<sub> $\nu$ </sub> < 0.5 Jy at 12, 25 and 60  $\mu$ m and < 1.0 Jy at 100  $\mu$ m.

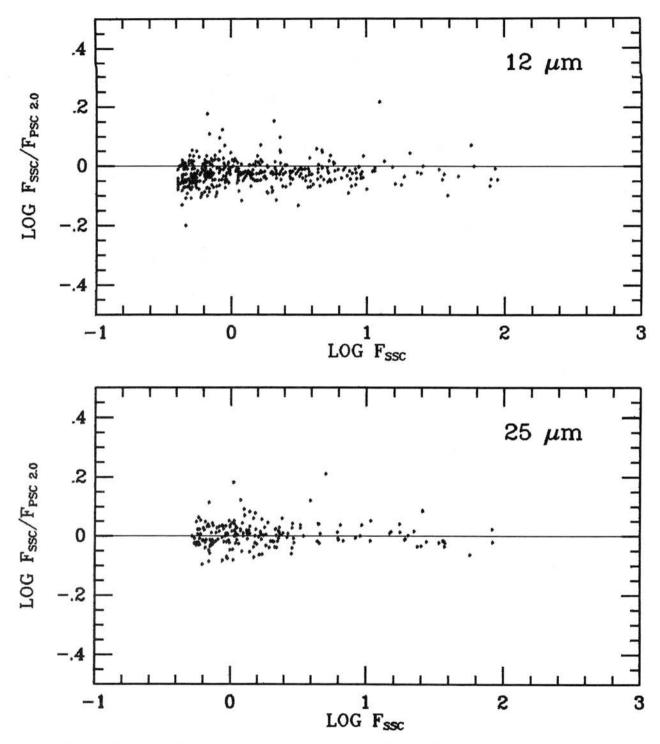


Figure IV.K.1-2 Ratio of SSC to PSC version 2.0 flux densities versus SSC flux density at 12 and 25  $\mu m$  for sources selected from both catalogs. Expressed as a percentage difference from unity, the mean at 12 and 25  $\mu m$  are -5.2% and 1.1%, respectively.

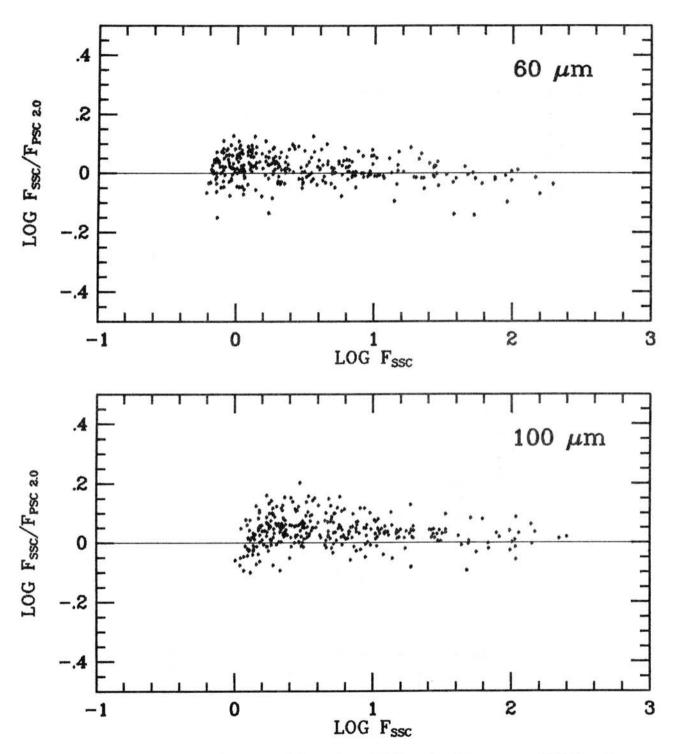


Figure IV.K.3-4 Ratio of SSC to PSC version 2.0 flux densities versus SSC flux densities at 60 and 100  $\mu$ m for sources selected from both catalogs. Expressed as a percentage difference from unity, the mean at 60 and 100  $\mu$ m are 4.2% and 9.6%, respectively.

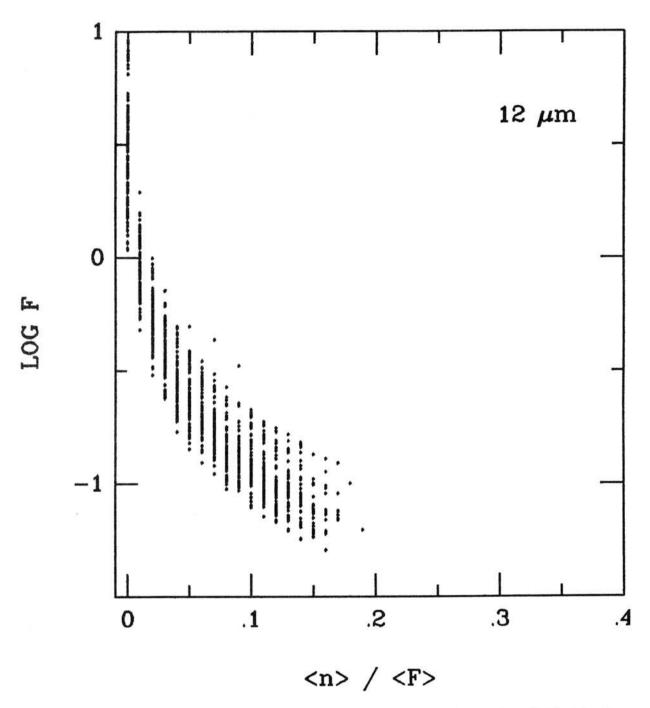


Figure IV.L.1 Flux density versus <n>/F, a measure of median noise divided by the flux density.

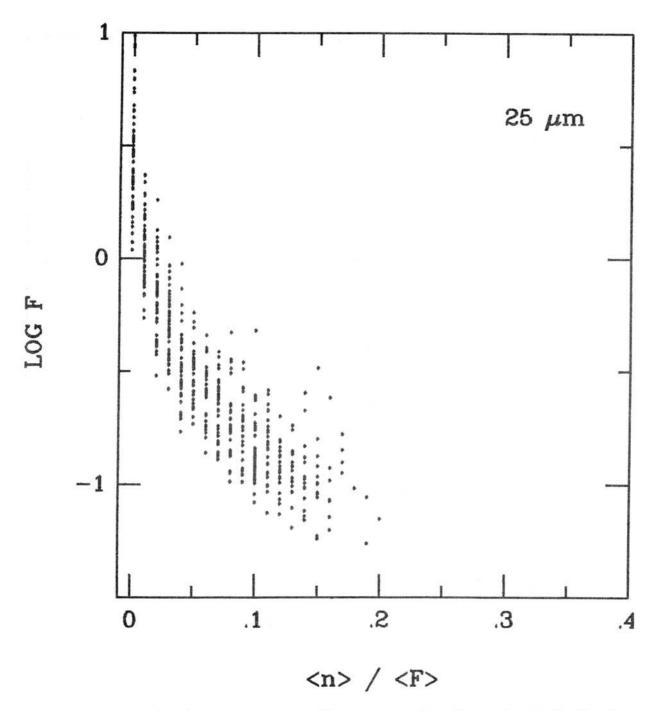


Figure IV.L.2 Flux density versus <n>/F, a measure of median noise divided by the flux density.

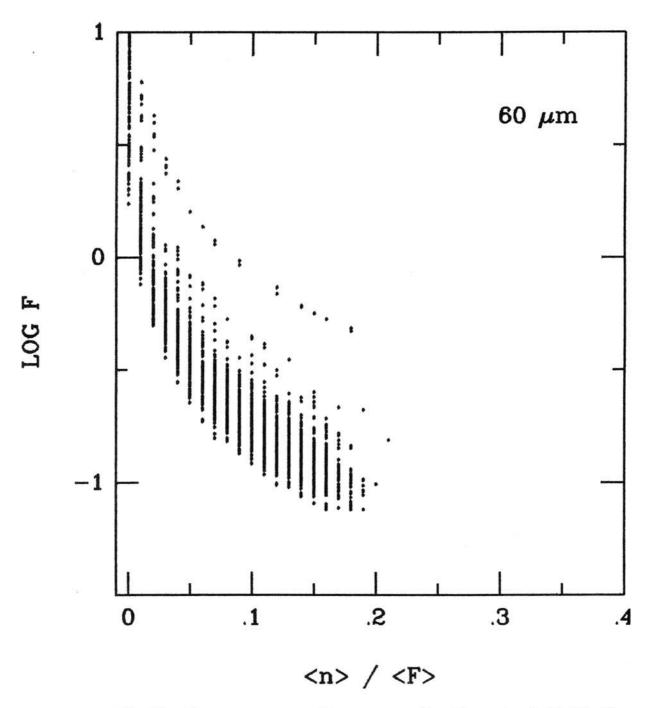


Figure IV.L.3 Flux density versus < n > /F, a measure of median noise divided by the flux density.

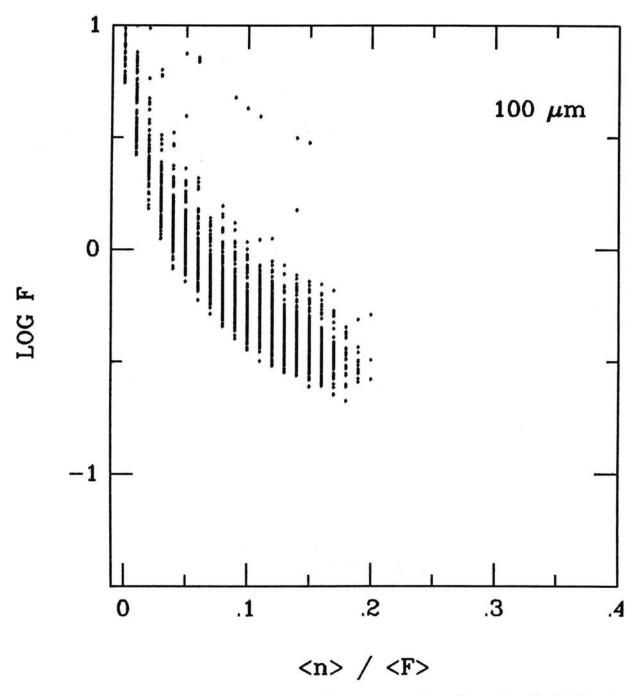


Figure IV.L.4 Flux density versus < n > /F, a measure of median noise divided by the flux density.

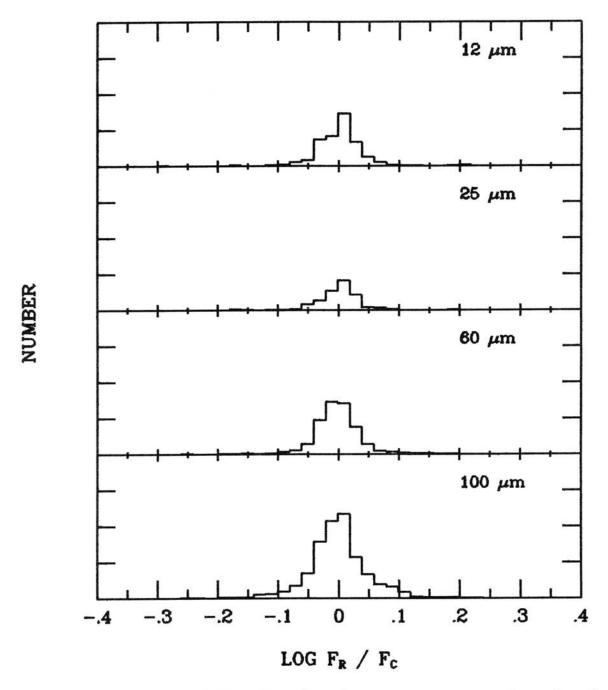


Figure IV.M.1 Number of high latitude subset sources versus the ratio of confirming source to reference source flux densities; high flux density, high latitude subset. 400 sources full scale in each band.

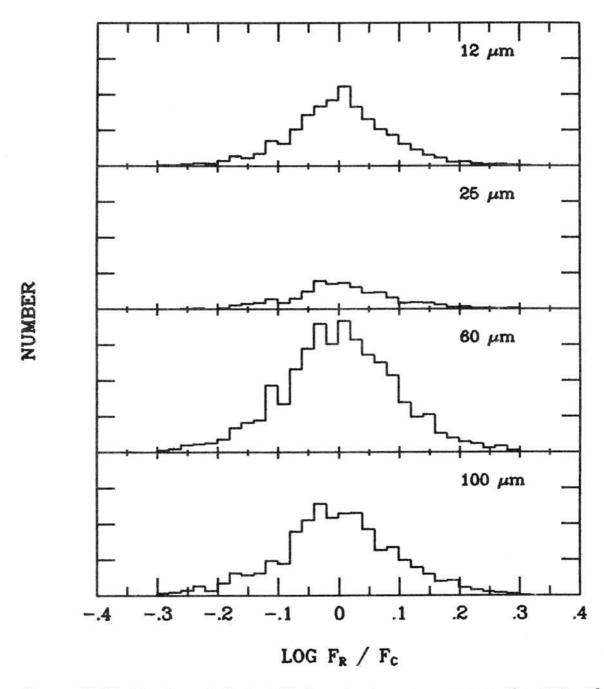


Figure IV.M.2 Number of high latitude subset sources versus the ratio of confirming source to reference source flux densities; low flux density, high latitude subset. 400 sources full scale in each band.

#### F. General Catalog Statistics

The IRAS SSC contains 43,886 infrared sources. The number of high quality point sources detected in each of the four IRAS bandpasses, and the resultant source densities are summarized in Table IV.F. Mean source densities in each band as a function of galactic latitude are listed in Table IV.G.

Table IV.F. Number of Point Source Detections in Each Band

	Band $(\mu m)$			
	12	25	60	100
No. of Sources	17,697	10,895	18,805	13,007
Mean Surface Density	16.0	9.8	17.0	11.7
No. of Merged Sources				43,886

Table IV.G. Distribution of Sources with Galactic Latitude

lbl		Sky Coverage (Degree <sup>2</sup> )			
	12 μm	25 μm	$60 \mu m$	100 μm	
<10°	39.6	25.6	26.8	14.5	255.8
10-30°	10.3	4.9	14.7	12.0	401.4
30-50°	9.2	6.6	14.5	10.5	317.9
>50°	3.8	2.1	10.6	8.4	132.6

For comparison, the PSC contains approximately 0.6 point sources/deg<sup>2</sup> brighter than 0.5 Jy at 12, 25, and 60  $\mu$ m at high galactic latitudes. At the flux densities greater than the sensitivity limits of the SSC (cf. Section IV.A.3), the Log N vs. Log F relationship determined for the PSC, as reported in the Main IRAS Supplement, predicts that approximately 3, 2, and 6 sources/deg<sup>2</sup> should be observed at 12, 25, and 60  $\mu$ m, respectively. Some number of excess detections can be understood in terms of the selection biases introduced by targeting of Pointed Observation fields.

The relatively high density of infrared sources found between Galactic latitude 30 deg. and 50 deg. is due primarily to the inclusion of Pointed Observations of the Large and Small Magellanic Clouds. Source densities in fields centered on the Magellanic Clouds exceed those found in other regions at similar Galactic latitudes by more than a factor of ten.

A summary of the spectral information contained in the SSC is given in Table IV.H. In a fashion similar to that in the Main IRAS Supplement, this table lists the numbers of sources with moderate to high quality detections in various band combinations. The four-digit row headings specify the band-detection combination, where "1" signifies that a detection is present in a given band and "0" denotes an upper limit. For example, the row labeled "1000" pertains to  $12~\mu m$  only sources, and "1100" to sources with moderate or high quality detections at  $12~and~25~\mu m$ . For

comparison, the ratios of the number of various band- detection combinations to the total number of sources are listed for the SSC, and for the PSC.

Table IV.H. Spectral Information Content of the SSC

Combination	Total Number	Percent of	f Total
o i <del>n</del> element de traver e la propiation de la propiation		SSC	PSC
1000	9120	.208	.274
1100	5351	.122	.273
1110	1542	.035	.054
1111	878	.020	.026
0100	2215	.051	.016
0110	789	.018	.015
0111	400	.009	.016
0010	10799	.246	.078
0011	4252	.097	.092
0001	7332	.167	.135
1101	136	.003	.008
1010	557	.013	.005
1011	192	.004	.002
1001	209	.005	.005
0101	114	.003	.002

There are significant differences between the spectral statistics of the SSC and the PSC; one case is the larger percentage of  $60~\mu m$  only sources in the SSC. This difference can be understood in terms of the relative increase in sensitivity at  $60~and~100~\mu m$ . The sensitivity of the measurements in the SSC exceeds that in the PSC by nearly a factor of 5 at  $60~\mu m$ , but only by ~2.5 at  $100~\mu m$ . If most of the  $60~\mu m$  sources in the SSC are associated with objects having galaxy-like spectra, which is the case in the PSC, and these objects follow the Log N vs. Log F relationship reported for the PSC, then the SSC should contain roughly a factor of 3 times more  $60~\mu m$  only sources. Given these rather simple assumptions, the fractional increase in  $60~\mu m$  only sources agrees well with expectation.

#### V. THE FORMATS OF THE IRAS SERENDIPITOUS SURVEY CATALOG

#### A. Introduction

This chapter describes the formats of the IRAS Serendipitous Survey Catalog in its printed and machine-readable forms. A brief description is given of each entry in the catalog; tables describe each column of the catalog in more detail and give, for the machine readable versions, the logical type of each variable and its length in bytes. The catalog consists of three basic parts; a) field headers, b) source listings, and c) redundant fields (a printed list of the redundant fields is also available in Appendix A). The field header includes information on the global properties of each pair of reference/confirming grids. The source listing documents the properties of the individual confirmed sources found in each field. The redundant field listing identifies those grid pairs with more than 5% overlapping coverage on the sky.

Because the Serendipitous Survey fields are non-uniformly distributed on the sky, the catalog has been arranged by fields, with the fields ordered by the right ascension of the field center. The field header is located at the beginning of the source listing for that field. Within a field the sources are also arranged in order of right ascension. The redundant field listing is separate and follows the rest of the catalog. As much as possible, the conventions established for the IRAS/PSC have been adopted for the Serendipitous Survey.

# **B.** The Machine Readable Version

The tape version of the SSC is written with 80-character (ASCII) logical records and blocked with 256 logical records per physical record so that one can regard the tape as a sequence of card images. The entries are arranged so that the source data fit into two records. Association information requires an additional 40 characters per association and appears in subsequent records, two associations per record.

Like other IRAS catalogs, the tape contains a header file containing the date and version number of the data on the Tape (Table V.A)

Start	Name	Description	Length
Byte			
00	Name	Name of IRAS	30A1
		data product	
30	Date	Date of Production	12A1
42	Vers	Version Number	5A1
47	Comment	32 bytes of comment	32A1

Table V.A. Format of Header Files

Table V.B describes each entry in the tape field header. Each catalog field header entry requires 160 bytes. Those columns that are also included in the printed version of the Serendipitous Survey are marked.

Table V.C describes each entry in the catalog tape source listing. Each catalog source entry requires 160 + NID \* 40 bytes where NID is the number of catalog associations, including the IRAS/PSC, for each source. In the tables, the Column "format" refers to the length and type of the (FORTRAN) character field used to read or write each entry.

Table V.B. Format of Field Headers 1 (SSC Tape Version)

Byte		Description	Units	Format
byte	2			
00	FNAME <sup>2</sup>	Field Name		13A1
13	RGRID <sup>2</sup>	Reference Grid No.		15
18	RDATE <sup>2</sup>	Obs. Date, Ref. Grid	Days	13
			JD 2445000 +	
21	CGRID <sup>2</sup>	Confirming Grid No.		15
26	CDATE <sup>2</sup>	Obs. Date, Conf. Grid	Days	13
			JD 2445000 +	
29	MACRO <sup>2</sup>	Macro Type		1A1
30	GLON <sup>2</sup>	Galactic Longitude	Degree	13
33	GLAT <sup>2</sup>	Galactic Latitude	Degree	13
36	PDRAS	Sign of R.A. Difference	+/-	1A1
		Between Grid centers		
37	PDRA	Amplitude of R.A. Difference	Arcsec	13
0.		Between Grid Centers		
40	PDDECS	Sign of Dec. Difference	+/-	1A1
10	IDDLCO	Between Grid Centers	= In Passer	
41	PDDEC	Amplitude of Dec. Difference	Arcsec	13
11	IDDLC	Between Grid Centers	Allesee	13
44	RANGLE	Reference Grid Scan	Degree	14
11	KANGLL	Direction (E of N)	Degree	
48	CANGLE	Confirming Grid Scan	Degree	14
40	CANGLL	Direction (E of N)	Degree	1-1
52	EFFAREA <sup>2</sup>	100x Effective Area	Degree <sup>2</sup>	13
32	EFFAREA	of Grid Overlap	Degree	13
	RUNDF <sup>2</sup>	No. of Fields with	NN	12
55	KUNDF		1/1/1/	12
<b>-</b> -	CDAREC	Overlap > 5%		23A1
57	SPARES	23 spare bytes		23A1
00		New Record		415
80	RNOISE	Median Noise of Ref.	mJy	415
100	CHOICE	Grid (1 value per band)	som Too.	415
100	CNOISE	Median Noise of Conf.	mJy	415
		Grid (1 value per band)		413
120	NSOURC	Number of Confirmed	NNN	413
	2	Sources (1 value per band)		
132	NCONF <sup>2</sup>	Number of Confused	NNN	413
	2	Confirmations (1 value per band)		2020
144	CIRRUS <sup>2</sup>	Number of 100 $\mu$ m only	NN	13
		Confirmed Sources		
147	NMERGE	Number of Merged Sources	NNN	13
150	SPARES	10 spare bytes		10A1

#### NOTES

<sup>&</sup>lt;sup>1</sup> Fields are listed in order of increasing Right Ascension of the Reference Grid center. Field header records are located at the beginning of the source listing for each field.

<sup>&</sup>lt;sup>2</sup> This quantity is listed in the printed version of the catalog.

The following is a brief description of the individual entries in the Field Headers of the tape version of the SSC.

Field Name: FNAME

The IRAS/SSC field name is the position of the center of the reference grid, given in the form hhmmssSddmmss.

Grid Number: RGRID, CGRID

The identifying number (see Section III.A) for the reference (R) and confirming (C) grids for the field. The reference grid has the lower 60  $\mu$ m median noise.

Observation Date: RDATE, CDATE

The observation dates for the reference (R) and confirming (C) grids in Julian Days -2445000.

Macro Type: MACRO

The macro identifying code is given in Table II.1.

Galactic Coordinates: GLON, GLAT

Galactic coordinates rounded to nearest degree

Position Differences: PDRAS, PDRA, PDDECS, PDDEC

The sign and magnitude of the position difference between reference and confirming grid centers, in the sense of (confirming - reference), in right ascension and declination.

Grid Orientation: RANGLE, CANGLE

The orientation of the in-scan direction of the reference and confirming grids on the sky, measured in degrees East of North.

Effective area: EFFAREA

The effective area of the sky covered by both the reference and confirming grids.

Redundant Fields: RUNDF

The number of additional grid pairs in the Serendipitous Survey, i.e. with different OBSID's, which overlap this field by more than 5%.

Grid Noise: RNOISE, CNOISE

The median noise of the reference and confirming grids.

Confirmed Sources: NSOURC

The number of confirmed sources in this field, in the 12, 25, 60 and 100  $\mu$ m bands, respectively.

Confused Sources: NCONF

The number of confused confirmations in this field, in the 12, 25, 60 and 100  $\mu$ m bands, respectively.

100 μm Only Sources: CIRRUS

The number of  $100 \mu m$  confirmed sources in the field that are not band merged. The density of such sources is taken to be a measure of the infrared "cirrus" in the field.

Band-Merged Sources: NMERGE
The number of band-merged sources in the field, i.e., the number of source records following the field header.

Table V.C. Format of Source Listings (SSC Tape Version)

Ctout	Nama	Description	Units	Format
Start	Name	Description	Offics	rormat
Byte	NAME <sup>2</sup>	Source Name		11A1
00 11			Hours	12
	HOUR	Right Ascension 1950	Minutes	12
13	MINUTE	Right Ascension 1950	Deci-seconds	13
15	SECOND	Right Ascension 1950		1A1
18	DSIGN	Declination Sign	+/-	
19	DECDEG	Declination 1950	Degree	12
21	DECMIN	Declination 1950	Arcmin	12
23	DECSEC	Declination 1950	Arcsec	12
25	SPARE	l spare byte		1A1
26	ANGLE	Position Angle of		13
00991		Source Error Box		4
29	SPARE	1 spare byte	2 V	1A1
30	FLUX <sup>2</sup>	Averaged Non-color	Jansky	4E9.3
		Corrected Flux Densities	$(10^{-26}  \text{W/m}^2/\text{Hz})$	
	2	(1 value per band)		
66	FQUAL <sup>2</sup>	Flux Density Quality		411
		(1 value per band)		
70	RGRID	Reference Grid Number		15
76	SPARE	9 spare bytes		9A1
		New Record		
80	RELUNC <sup>2</sup>	Percent Relative Flux		413
		Density Uncertainties		
		(1 value per band)		
92	TLSNR	10x Local Signal-to-Noise		414
	5287	Ratio (1 value per band)		
108	$CC^2$	Point Source Correlation		4A1
		Coefficient (1 value per band)		
112	TRFLUX	10x F <sub>c</sub> /F <sub>c</sub>		412
120	POSDRS12	Right Ascension Delta Sign	+/-	1A1
121	POSDR12	Right Ascension Delta	Arcsec	13
124	POSDDS12	Declination Delta Sign	+/-	1A1
125	POSDD12	Declination Delta	Arcsec	13
128		Repeat for 25 $\mu$ m Band	+/-	1A1
-135			Arcsec	13
136		Repeat for 60 $\mu$ m Band	+/-	1A1
-143		Repeat for oo pin bana	Arcsec	13
144		Repeat for 100 $\mu$ m Band	+/-	1A1
-151		Repeat for 100 pm band	Arcsec	13
152	PNEARC <sup>2</sup>	Number of Sources in	Mesec	411
132	TNLANC	Confusion Window		12
		(1 value per band)		12
156	$NID^2$	Number of Positional		12
156	MID			12
150	IDTYPE <sup>2</sup>	Associations		11
158	IDITPE	Type of Object		11

159	SPARE	1 spare bytes		1A1
		New Record		
160	CATNO	Catalog Number <sup>4</sup>		12
162	SOURCE	Source ID		15A1
177	IDTYPE	Source Type/Spectral Class <sup>5</sup>		5A1
182	<b>RADIUS</b>	Radius Vector from	Arcsec	13
		SSC Position to Association		
185	POS	Position Angle from	Degree	13
		SSC Position to Association (E of N)		
188	FIELD 1	Object Field #1	Catalog	14
			Dependent <sup>6</sup>	
192	FIELD2	Object Field #2	Catalog	14
			Dependent <sup>7</sup>	
196	FIELD3	Object Field #3	Catalog	14
			Dependent <sup>8</sup>	
200		Continuation of Associations		
-240		in Blocks of 40 Bytes		
	3.6	etc.		

# NOTES:

<sup>&</sup>lt;sup>1</sup> Sources are listed in order of increasing Right Ascension within each field.

<sup>&</sup>lt;sup>2</sup> This quantity is listed in the printed version of the SSC.

<sup>&</sup>lt;sup>3</sup> For associations with the IRAS/PSC, this value is 41.

<sup>&</sup>lt;sup>4</sup> For associations with the IRAS/PSC, this value is 3.

<sup>&</sup>lt;sup>5</sup> For associations with the IRAS/PSC, this field is left blank.

<sup>&</sup>lt;sup>6</sup> For associations with the IRAS/PSC, this value is a flag indicating the bands in which the source was detected with medium or high quality; it is encoded as indicated in the PSC Supplement Table X.B.2.

<sup>&</sup>lt;sup>7</sup> For associations with the IRAS/PSC, this value is the PSC 2.0 Flux Density in the shortest (first) wavelength band in which it was detected. Flux Densities higher than 10 Jy are encoded 9999.

<sup>&</sup>lt;sup>8</sup> For associations with the IRAS/PSC, this value is the PSC 2.0 Flux Density in the second wavelength band in which it was detected. Flux Densities higher than 10 Jy are encoded 9999.

The following is a brief description of the individual entries in the Source Listings of the tape version of the SSC.

# Source Name: NAME, APPNAME

The IRAS/SSC source name is constructed as for IRAS/PSC sources and is derived from its position by combining the hours, minutes and tenths of minutes of right ascension and the sign, degrees and minutes of the declination. In obtaining the minutes of right ascension and declination for the name, the positions were truncated. If sources within a field have duplicate positional names, they are distinguished by an appended letter (APPNAME), starting with the letter A.

Position: (HOUR,MINUTE,SECOND,DSIGN,DECDEG,DECMIN,DECSEC) Positions are, as in the IRAS/PSC, given for the equinox 1950.0 and epoch 1983.5. Hours (HOUR) and minutes (MINUTE) of right ascension are given as integers while seconds (SECOND) are rounded to integer deciseconds. The declination is given as a character sign (DSIGN) followed by integer values of degrees (DECDEG), minutes (DECMIN) and seconds (DECSEC).

## Position Angle: ANGLE

The position angle of the major axis of the SSC source error box expressed in degrees East of North.

## Flux Density: FLUX(4)

Each of the four wavelengths has a NON-COLOR-CORRECTED flux density in units of Janskys, (1 Jy =  $10^{-26}$  W m<sup>-2</sup>Hz<sup>-1</sup>). The quoted value is the noise weighted average as defined in Section III.C.2.

# Flux Quality: FQUAL(4)

Each flux density measurement is designated high quality, moderate quality or upper limit (FQUAL = 3, 2, or 1, respectively) based on the prescription discussed in Section III.C.

# Flux Density Uncertainty: RELUNC(4), TLSNR(4)

Each flux density measurement other than an upper limit has an associated uncertainty expressed in two ways; RELUNC is the uncertainty expressed as a 1 sigma value in units of 100x<n>/<F> (see Section III.C.2). TLSNR is ten times the local signal to noise ratio (see Section II.C) as determined from the reference or confirming grid, whichever is least.

# Point Source Correlation Coefficient: CC(4)

As discussed in Section III.B, SSC sources can have point source correlation coefficients between 70-100%. These are encoded as alphabetic characters with A=100, B=99.....Z=75-70, one value per band. The quoted correlation coefficients come from the reference or confirming grids, whichever is higher, for high quality sources.

## Flux Density Ratio: TRFLUX(4)

As discussed in Section III.B, SSC sources can have flux density

ratios 0.5 <  $F_{(c)}/F_{(r)}$  < 2.0. TRFLUX is the flux density ratio for high quality sources expressed as 10 x  $F_c/F_r$ .

Position differences: POSDRS12, POSDR12, POSDDS12, POSDD12....... The quoted positions of SSC sources are determined from a weighted average of the positions of the confirmed sources in each band with a high quality flux density( see Section III.C.1). POSDRS12, POSDRS12, POSDDS12 and POSDD12 give the sign and amplitude (in arcsec), of the difference in right ascension and declination respectively, between the final band-merged position and the  $12~\mu m$  confirmed source position. The following 12 entries repeat the above format for 25, 60 and  $100~\mu m$  confirmed source components.

# Confusion: PNEARC(4)

In regions of high source density, the Pointed Observation source extraction process, as well as the Serendipitous Survey Confirmation and Band Merging processing, can result in degraded positions and incorrectly band merged sources. PNEARC is 1-(number of confirmed sources in the confusion and band merge window)(See Section III.D) Any value greater than zero is indicative of potential confusion in the processing and the resulting source information should be examined carefully, e.g. by inspection of the grids in question.

Positional Associations: NID, IDTYPE, CATNO, SOURCE, TYPE, RADIUS, POS, FIELD 1-3 The positional associations formats and definitions are done as per the IRAS/PSC (Chapter X, Supplement), with the exceptions noted in Section III.F.

Table V.D Format of Overlapping Fields File (SSC Tape Version)

Fo	ormat
	15
	1A1
	15
a.	1A1
2	14
	9A1
	6A1

The quantities in the Overlapping Fields List are as follows:

Prime Reference Grid: GRID0

The grid against which other reference grids are checked for overlapping sky coverage.

First Overlapping Grid: GRID1

The number of the first reference grid with more than 5% overlap with GRIDO.

Overlap Area: AOVLP1

Area of overlapping sky coverage between GRID0 and GRID1 in square arcminutes.

The format is repeated for each additional grid overlapping with GRIDO. If more than 5 grids overlap with GRIDO, they are listed in succeeding records, as necessary; the first six bytes of each of these additional records begins with a string of 6 spaces.

### C. The Printed Version of the IRAS/SSC

The printed version of the IRAS/SSC is organized in the same fashion as the machine readable version, with the catalog sources listed in order of increasing right ascension within a given field and with the fields listed in order of increasing right ascension of the field center. Both the field header and the source listings of the printed version contain subsets of the information found in the machine readable version.

Table V.E. Format of Field Headers (SSC Printed Version)

Column	Title	Format	Machine-Readable Quantity
1-13	FIELD NAME	<b>HHMMSS±DDMMSS</b>	FNAME
14	Space		
15-20	LLL±BB	NNN±NN	GLON,GLAT
21-29	MN(12)	NNNNNNNN	$RNOISE(12)^{1}$
30-39	MN(25)	NNNNNNNN	RNOISE(25) <sup>1</sup>
40-49	MN(60)	NNNNNNNN	RNOISE(60) <sup>1</sup>
50-59	MN(100)	NNNNNNNN	RNOISE(100) <sup>1</sup>
60	Space		
61-64	POS	±NNN	RANGLE
65	Space		
66-68	N12	NNN	NSOURC(12)
69-71	N25	NNN	NSOURC(25)
72-74	N60	NNN .	NSOURC(60)
75-77	N100	NNN	NSOURC(100)
78	Space		
79-80	C	NN	CIRRUS
81	Space		
82-92	GRIDS	NNNNN NNNNN	RGRID CGRID
93	Space		
94-100	<b>OBS-DATES</b>	NNN NNN	RDATE CDATE

101	Space			
102	M	A	MACRO	
103	Space			
104-106	AR	NNN	EFFAREA	
107	Space			
108-110	OVP	NN	RUNDF	

# NOTES:

Table V.F. Format of Source Listings (SSC Printed Version)

Column	Title	Format	Machine-Readable
1-11	SRC NAME	HHMMM-DDMMA	Quantity NAME
1-11		ппими-ррима	NAME
	Space	ccc	SECOND <sup>1</sup>
13-16	S	SS.S	SECOND
17	Space	CC	DECCEC
18-19	D	SS	DECSEC
20-21	Spaces	CCCCC CCCI	ELLIV(12)2
21-30	FLUX(JY)12	FFFFF.FFFL	FLUX(12) <sup>2</sup>
31-40	25	FFFFF.FFFL	FLUX(25) <sup>2</sup>
41-50	60	FFFFF.FFFL	FLUX(60) <sup>2</sup>
51-60	100	FFFFF.FFFL	FLUX(100) <sup>2</sup>
61	Space	27.11	66(10) 66(05) 66(60) 66(100)
62-65	CC	AAAA	CC(12),CC(25),CC(60),CC(100)
66	Space		
67-68	R12	NNN	TRFLUX(12)
69	Space		A
70-71	R25	NNN	TRFLUX(25)
72	Space		
73-74	R60	NNN	TRFLUX(60)
75	Space		
76-77	R100	NNN	TRFLUX(100)
78-79	Spaces		
80-83	CONF	NNNN	PNEARC(12),PNEARC(25) PNEARC(60),PNEARC(100)
84	Space		in.
85-86	PSC	NN	FIELD 1 <sup>3</sup>
87	Space		
88-89	NID	NNN	NID
90	Space		
91-92	C#	NN	CATNO
93	Space		
94-113	NAME & TYPE		SOURCE, IDTYPE <sup>4</sup>
114-116	RAD	NNN	RADIUS

<sup>&</sup>lt;sup>1</sup> The median noise listed is  $1/(1/n_r^2 + 1/n_c^2)^{0.5}$  where  $n_r$  and  $n_c$  are the median noise levels of the reference and confirming grids, respectively.

#### NOTES:

An erroneous 6-digit value of the CIRRUS indicator "C" was printed in the headers of 11 fields in the SSC Printed Version *only*. The subsequent entries in the field headers are correct, but are offset 5 columns to the right. Below is a list of the Printed Version fields in which this occurred, along with the reference grid number of the field and the proper value of the CIRRUS indicator.

Table V.G. Fields With Incorrect CIRRUS Counts

Field Name	DCDID	
rieid Name	RGRID	C
053226-051906	1222	3
053828-020030	10951	1
102225-572609	6693	1
104148-591213	7082	3
104326-591832	5973	5
130916-621123	8850	3
163716-475203	10392	3
173114-323259	11387	3
180035-242137	12149	1
184238-031728	2450	2
203735+421259	3239	2

<sup>&</sup>lt;sup>1</sup> Right Ascension decimal seconds of time.

<sup>&</sup>lt;sup>2</sup> Flux densities are given in units of 1 Jy. Moderate quality flux densities are indicated with a colon(:) and upper limits are indicated with the letter L.

<sup>&</sup>lt;sup>3</sup> The flag indicating the wavelength bands in which the IRAS/PSC lists a high or moderate quality flux density, encoded as in the PSC Supplement, Table X.B.2.

<sup>&</sup>lt;sup>4</sup> Formatted as in the IRAS/PSC (PSC Supplement Section X.B).

#### VI. ADDITIONAL CONSIDERATIONS

# A. High Source Density Considerations

A significant fraction of the fields included in the SSC are in regions of high source density. In particular, the fields near the plane of the galaxy, in the Large and Small Magellanic Clouds, and in large molecular clouds all suffer from the effects of source confusion. These fields are included in the SSC because the large majority of the sources at 12 and 25 um are genuine, even in grids of very high density. THE USER IS CAUTIONED, HOWEVER, THAT THE LEVELS OF RELIABILITY, SENSITIVITY AND ACCURACY THAT APPLY TO LOW SOURCE DENSITY REGIONS ARE NOT SATISFIED IN THESE FIELDS. At the longer wavelengths, the observations are generally so heavily confused that only the brightest sources have any validity. This section documents a number of the known anomalies that can occur in high source density regions.

The FLUX filtering was designed to provide the highest sensitivity for the detection of weak point sources. As illustrated in the simulation shown in Section II.D, the large negative sidelobes complicate the effects of confusion. Additionally, the FLUX filter passes all spatial components of the background at the point source frequency. In regions of high, complicated backgrounds, "sources" may be present that are only point-like modulations of the extended background. These effects are particularly noticeable at 60 and 100  $\mu m$  in molecular clouds and at 100  $\mu m$  over large parts of the sky influenced by infrared cirrus. Figure VI.A shows the FLUX filtered 60  $\mu m$  map of a region of complicated background. Many of the 60  $\mu m$  "sources" are, in fact, components of infrared cirrus.

Figure VI.B is a portion of the 12  $\mu$ m FLUX filtered map for Grid 12871. This grid is representative of the highest 12  $\mu$ m source density in the SSC.

If sources are partially overlapping, they may appear as only a single entry in the SSC. Although the source extractor uses an algorithm to separate regions, it is reliable only in the simplest cases. The quoted position from the source extractor is a flux weighted centroid of all contiguous pixels above threshold. Therefore, the error in position will depend on the ratio of fluxes from the two sources. If one source is significantly brighter than the other, the quoted position will be close to the position of the brighter source, and the weaker source will be lost. This effect is shown in example "A" of Figure VI.B. If the sources are of roughly the same flux, the quoted position will not be correct for either source, as shown in example "B". Because of the shape of the IRAS beam, the source overlap problem is most severe in the cross scan direction.

The loss of photometric accuracy in crowded fields is illustrated in example "C", shown in Figure VI.B. Here the negative sidelobe of source "A" has reduced the flux density of the nearby source.

## **B.** Asteroids

The confirmation strategy used in the SSC required that each source be observed on two separate occasions. Unlike the Point Source Catalog, which used confirming observations separated by weeks or even months, the SSC has no explicit requirements for the time interval between confirming observations. For many pointed observations, the confirming observation was scheduled for the next orbit, giving a time delay of only 103 minutes. While effective for discriminating against dust particles and earth satellites, many asteroids may appear fixed at the IRAS resolution. The observation times for the reference and confirming grid are given

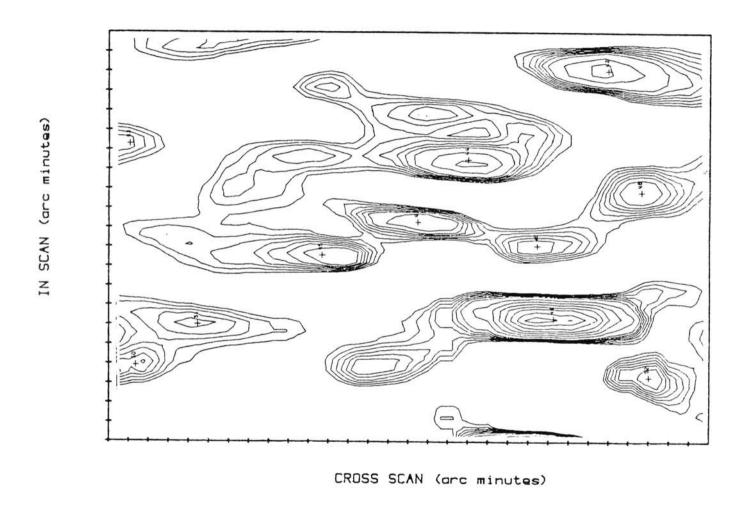


Figure VI.A FLUX filtered map at 60  $\mu m$  of a molecular cloud region. Many "sources" are actually modulations in the extended background at the point source spatial frequency.

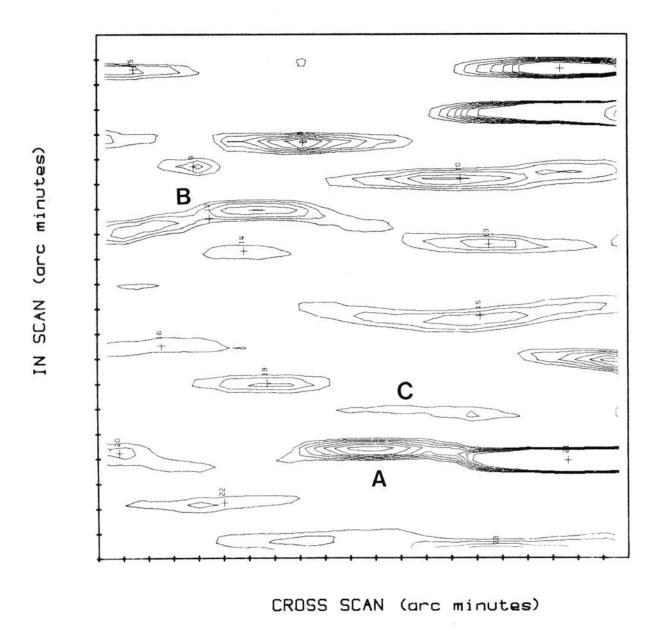


Figure VI.B FLUX filtered map at  $12~\mu m$  of a high source density region. "A" indicates a missed source not separated from a nearby brighter source. "B" indicates a single source listed at a position between two partially overlapping sources. "C" indicates a source whose flux is reduced by the negative sidelobe of source "A".

in the field header and may be used to judge the validity of a given source, particularly those within 5 degrees of the ecliptic plane. Typical catalog flux densities (i.e. not color corrected) of a 200 K asteroid, normalized to the peak at 25  $\mu$ m, are 0.3, 1.0, 0.6, and 0.25 at 12, 25, 60, and 100  $\mu$ m, respectively. Refer to Matson (1986) for a discussion of asteroids detected in the IRAS survey mode.

## C. Redundant Sources

The SSC is ordered on a field by field basis to maintain the organization of the Pointed Observation program. In regions covered by more than one SSC field, sources in the overlapping areas are included in both fields. Generally, these redundant sources have slightly different positions and flux densities but may, in a few cases, have identical names. It is recommended that the reference grid number be used as an additional identifier for these redundant sources. Location of areas where redundant sources occur is facilitated by the compilation of overlapping fields in Appendix A.

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#### **ACKNOWLEDGEMENTS**

This catalog was produced and supported by the NASA IRAS Extended Mission at the Infrared Processing and Analysis Center, by the Jet Propulsion Laboratory of the California Institute of Technology and by the National Science Foundation through the National Optical Astronomy Observatories operated by the Association of Universities for Research in Astronomy, Inc.. We extend our thanks to members of the IPAC staff who provided both support and technical assistance: Gael Squibb, Tom Soifer and Chas Beichman skillfully administered this support.

The Pointed Observations used in the SSC were reduced at IPAC by Gene Kopan and co-workers and formed the fundamental data base. The source extractions, also carried out at IPAC, were the contribution of Dave Gregorich and again were a basic step in the production of the SSC. Iffat Khan contributed to the catalog association processing. In addition to the scientific advice of the U. S. Science Team as a whole, we acknowledge the following individual members who made direct contributions to this work: Chas Beichman, Tom Chester, and Gerry Neugebauer.

The National Optical Astronomy Observatories generously provided support, including extensive use of their computing facilities throughout this project, making it possible for the work to be carried out in Tucson. The University of Arizona Steward Observatory also provided support and facilities. Tom Green, a Steward Observatory graduate student, deserves special thanks for his contributions to the analysis of the catalog. Special thanks also go to Pat Lambotte and Patsy Van Buren, who contributed generously to the typing and editing of this manuscript.

Most of the figures were generated using the program MONGO, developed by John L. Tonry.

# APPENDIX A: OVERLAPPING FIELD TABLE

GRIDO	GRID1	OVLP	GRID2	OVLP	GRID3	OVLP	GRID4	OVLP	GRID5	OVLP	GRID6	OVLP
17 58 65	2591 72 927 9428	792 846 296 1011	290 3076 409	2447 783 912	925 663	1599 670	98	665	914	1286	112	1874
72	3076 58	788 786	925 95	852 792		2014 1614	914	472	112	836	325	871
90 92	12205 95	619 723	92 90		11906 12205		814 3076	245 280	325	169	11906	1104
95	814 72 927	731 1357	12205 11906	1102 227	3076 814	781 1012	98	691	325	1545	92	784
98	914 72	180 2034	112 58	983 620	325 95	1213 738		523 1576	3076		12205	398
112	914 927	1107 553	98	1050	925	1769	3076	795	72	879	58	1839
121 135	164 8274 5074	765 998 328	8292 8236	931 705	8223	1249	8693	1391	6744	1568	6579	879
137 141 147	5074 5074 206											
153 155	206 169	464 832	208	781	275				10708		6948	1727
164	6579 169 8274	379 765 758	6650 121 8236	1220 832 293	8464 10631			2422 1253		1584 1444	6650	887
167 169	365 164	388	225 155	457 765	10708	923	10631	833	6948	719	6744	301
177	6579		6650	1444	8464		230					
195 206	314 147	440 461	9693 153	937 402								
208	155 216	847	275		303	1819	6948	1298	6650	404	230	857
216	230	1904 2005	8464 275	609 850		991 1246	6579 155	163 1651	6948	1615	10708	565
225 230	167	519 961	359 6650	357 1214	6579	395 2459	6948	1651	10708 216	920 1829	303	1708
260 262 275	8123 10580 208	397 1273 2358			303	1336	6948	1027	6650	218	230	393
283		1237	0503	626								
290 303	275			1741			10708	435	6948	1637	6650	872
314	8464 195		230	1745	210	2028						

# GRIDO GRID1 OVLP GRID2 OVLP GRID3 OVLP GRID4 OVLP GRID5 OVLP GRID6 OVLP

325		1148	3076		12205	1013	72	821	95	1570	92	211
250	927	941	814	626								
359 365	225 167	418										
388	7002	329 1304										
409	691	149	871	755	618	207	58	956	925	150	914	283
403	663		0/1	733	010	207	30	330	323	130	314	203
482	8895	2478	9235	2782								
495	177	485	11701	532								
543	9144	1753	8550									
548	6501	1162										
580	1925	1078	12804	895	9714	475	9092	381	3420	801	601	926
589	1979	353	3798	769								
601	580	974	1925	752	12804	151	3420	805				
618	871	2194	691	1592	409	235	663	328				
636	1626	991	1835	1626	12822	271	2433	535				
641	857	2281	1277	1798	832	2116	766	2027	1316	1296	776	904
648	744	1819	674	2255								
654	1512	1608	674		680	438	50	710				
663	409	2319	871	899	618	284	58	713				
674 680	1512 674	1649	654		680	663	0.5.1	270	1456	1215	15450	200
000	3589	676 792	1512 3607	876 791	654 3577	461 796	851 3617	270 769	1450	1315	15458	298
691	871	1013	618	1658	409	178	3017	709				
700	3607	805	3589	806	1489	1714	866	2023	3577	809	3617	803
700	2952	747	3303	000	1403	1/14	000	2023	3377	003	3017	003
744	648	1898										
763	10956	382										
766	641	2049	857	1644	1277	1312	832	1436	2454	1083	2543	1039
	1316	925		1066	1626	151						
774	10848	199										
776	1316	530	766	1112	641	964	857	553	1277	358	832	436
	2454	1088	1626	875								
781	2916	341		1353								
814	11906	671	92	1516	95	985	90	274	12205	1633	3076	154
000	325	601	1506	1000	0050	010						
	2009	374		1060	2952		700	1272	1216	1451	776	200
832 847	781	2191 1362	85/	2529	641	2067	700	1373	1316	1451	776	389
851	2433	230	1/0/	1051	14223	709	2749	809	2756	1006	15450	1016
031	680	233	1456		15458		3589	422	2/30	1000	15450	1010
855.		379	1430	331	13430	1000	3303	422				
857		2267	832	2613	641	2237	766	1579	1316	1456	776	500
859	855	346	002	2010	011	LLU	, 00	10,5	1010	1100	,,,	500
866	1489		700	2056	3607	827	3589	829	3577	835	3617	828
	2952	489										
871		2128	691	955	409	785	663	933				
891	2567	328										
899	902	1096										
902	899						00-		22		8 <u>21</u> 8258	
914	112		98	206	925	1748	3076	1076	72	487	58	1294
925	409 98		014	1601	110	1001	2076	051	70	000	F.0	1502
323	98	300	914	1691	112	1801	3076	951	72	880	58	1583

927		1407	58	266	72	1582	3076	952	98	1571	112	529
930	325 6306	996 824										
939	1027											
957		2045										
969 979		1907 1367										
983	995	465	1000	384								
995 1000	983 983	413 437										
1024		2459	1061	807								
1027		2737										
1033 1061	1024	2306 827	1339	951	2543	1334	2454	1062	3420	931		
		1229	12167	632	2010	1001	2101	1002	0 120	501		
	11547	991	11718	839								
1136 1183		1882 1009	3571 8860	941 1317	8876	1343	14239	1259				
1187	12454	1629										
1197 1204	9615 13358											
1257		2510	11241	316								
	11816	530	057	0050	C 4.1	1770	766	1056	1216	1640	776	222
1277	1835	2212 250	85/	2252	641	1770	/66	1256	1316	1640	776	323
1283	1033	2313										
1285 1294	969 1449	2113 311	12246	542								
1301		1286	12240	342								
1316	766	899	641	1297		1468	1277	1658	832	1474	776	490
1339	1835	901 2462	2433 1061	751 934	2749	400						
1367	11919	890										
1414 1430	10884 1925	1312 404	12113 9714	1214 704	9092	797	4043	805				
1432	1458	178		1307	3032	131	4043	003				
1449	1294			1789	0.51	0.00	14000	100	15450	1100	2500	010
1456	680 3607	1296 245	15450	415	851	368	14223	190	15458	1196	3589	818
1458	1432	209										
1469			3607	985	3589	550	966	1755	3577	1021	3617	994
1489	700 2952	1738 940	3007	900	3309	330	000	1/55	3311	1021	3017	334
1494	14223	923	851	1849	2749	359	2756	881	15450	1338	15458	1500
1512	3589 654		674	1645	680	886						
1530			0/4	1045	000	000						
1551			11055	170								
1564 1568		2442 1684	11355	173								
1582	3589	698								:25.330.771	2,542,5450	2023/200
1586				1010	3577	779			2009	686 1025		1054 1949
1626	1835	416	776	881	1316	156	766	161	030	1025	2433	1949

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2749 1372 2756 853 15450 326
1670 14447 392
1679 11241 331 1257 2471
    2971 426 14857 355 13743 956 9274 916
1713
1749 1785 2774 3885 1093
    3147 1640 2104 855
1775
1785 3885 1114 1749 2782
1835 1316 912 1277 242
                         1626 375
                                     636 1621 12822 583
1852 12808 1003
    4043 929 2583 1789
1866
                         1870 2119
1870 2583 1879 1866 2200
                         4043 855
1872 2270 2694 13147 967
                          3428
                               360
1878 2028 456 2203 1763
                         2635
                               501
1885 2205 2692
1925 12804 1132 9714 1075 9092 979 1430 362 580 1095 601 742
1979
     589 323
2009 1586 743 3617 182 826 404
2011 1530 2623
2028 1878 507
2035 10427 1193 15308 1181
2049 3036 154
2072 2912 2449 13230 1240
2081 3571 1416 1136 1877
2091 2231 2717
2104 3147 730
               1775 854
2120 11587 1282
2150 12609 1535 13320 1418
2170 3175 1862 2845 460
2188 14469 421
2203 1878 1726
2205 1885 2692
2214 11800 1186
2231 2091 2635
2270 13147 976 3428 393 1872 2684
2308 12094 1793
2343
      957 2042
2362 15065 1431 13762 1393 3734 1957
2366 13990 1280 13325 1304 13080 228
2378 13011 1493 14283 1396
2402 3548 2136 3693 1837
                          4049 1795 14875 1806
2408 11409 1137 14316 1453
2414 1564 2443 11355 299 11580 188
2433
     636 569 1626 1958 1316 800 2749 3892 2756 1770 15450 503
2454 2543 5348 1061 1096 3420 1993 766 1083 776 1089
2492 4276 308
2512 13462 1442
2528 3349 229
     1061 1334
               2454 5144 3420 2101
2543
                                     766 1039
2567
     891 328
2569
     2642 2807
     1866 1813 4043 799 1870 1881
2583
2588
     5571 919 5747 560 15376 365
2591
      17 791
                290 831
```

2598 2611 2628 2633 2635	2628 1878	1729 2782 2816 487	15376	785								
2642 2702 2749 2756 2764	13256 851	2792 1509 783 6157 475	3428 2433 851	293 4040 997		1403 1888	2756 1494	5965 839	15450 1626		15450	5825
2768 2774		1420 1924 252 1148 313	13682	1489								
2831	2861	1391 284	3036	749								
2845 2859	3175 2861	797 355	2170	496								
2861	2859	296	2831	344								
2881		5305										
2908	11525	1291	13230	1252								
2914			14464									
2916		5107	17707	1010								
2918	9820	620										
2950	3500	5013	3485	1574								
2952	3617	3283	3577	2752	866	520	1489	973	700	770	3607	1208
		1224	826	919								
2971		1378	1713	452								
2984	5712	918										
3012	3891	725	3744	580	3092	186						
3019	3169	188										
3030 3036	1568 2831	1684 706	2049	176								
3046		1651	2049	170								
3060	3066	2791	4193	1480	3804	2218	3644	1786	5153	1072	8389	761
3066		775 2807	4193	1469	3804	2197	3644	1775	5153	1063	8389	761
2076	9100	776	00	704	014	1072	110	706	225	407	72	700
3076	925 58	952 783	98 95	794 779	914	1072 283	112 927	796 952	325 814	497 160	72	788
3092	3012	192	93	113	32	203	321	332	014	100		
3111	3640											
3139			11589	1024								
3147	2104	686	1775									
3163	3278	4768										
3167	5144		5113		6705	828	6328	875		4177	3373	6502
		1018	5229		3522	2003	6677	859	5751	935		
3169	3019	188	2764	466								
3175	2845	803	2170		6670	020	7120	707	6155	011		
3179	6984 15182	801	7554	781	6679	829	7138	787	6455	844		
5201	10102	1023										

3203 3205	5629 5773	1089 410	4973 5174	1066 1118	5227 5170	972 1150	6429 5903	902 844	6334	911	7000	832
3257	15212	1768	0171	1110	0170	1100	0300	011	0001	711	, 000	002
3278		4567	5050	220	4701	1000	4100	1601				
3310 3318	6229 3356	1012 1144	5953	332	4731	1366	4129	1601				
3326	15108	902										
3334		1570										
3349	2528	197										
3356	3318	1109										
3373		6581	3167		5144		5113		6705	848	3528	1002
	6328	921	6141	1076	5229		3522		6677	883	5751	890
3381	3167		5144	1058	5113	1265	6705	838		1785	6328	904
2420		6762	6141 2543	1051		1214		2350	6677	789	5751	667
3420 3428	2454 2702	1993 268	13256		1061 13147	931 708	580 2270	801 375	601 1872	805 346		
3455		1010	13230	330	13147	700	2210	3/3	10/2	340		
3485		5399	2950	1697								
3494		1285										
3496	14568	1816										
3500	3485	5173	2950	5219								
3502	4276	2122	10 9000101		Translation (1981)							
3514	4525	304	4468	1544	4458	214	3812	976				
3522		1210	6141	633		2596	3381			2066	5144	1056
3528		1247 974	6705 6705	836 899		1234 1544	6328	903	6677	794	5751	817
3320		1066	6141	234		1349		1067 1305	3167 6677	542 349	3381 5751	1853 331
3534	3864		0141	234	3223	1343	3322	1303	00//	343	3/31	331
3544	15512		4105	2371								
3548				2503	4049	2459	14875	1832				
3552	3563											
3563		2555										
3571	2081	1419	1136	941								
3577	866	835	1489	1020	700	809	3607	4973	680	796	3617	4504
2500	7077017110071100	2704	1586	752	600	700	1.4000	000	2007	2720	700	000
3589	15458 1489	1430 519	1456 866	841 829	680 1582	730	14223	882	3607	3732	700	806
3607		3935	680	791	700	805	1489	977	866	827	3577	4780
3007		1156	000	131	700	003	1403	311	000	027	3311	4700
3617		4700	866	823	1489	998	700	802	680	779	2952	3284
		1010										
3640	3111	2438										
3644		1935	4193	1664	3060	1786	3066	1776	5153	1274	8389	768
	9100	773										
3646		1776										
3668		1854	E440	1220								
3678		1495	5442	1339								
3687 3693		1720	15157	161	2402	1840	4040	2799	14875	1825		
3709			14464	1813	2402	1040	4043	2100	140/3	1023		
	13384			968								
	15165			7.7								
3734	2362	1993	15065	1817	13762	1779						

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3748 4585 2117
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