Scanamorphos port to JAVA

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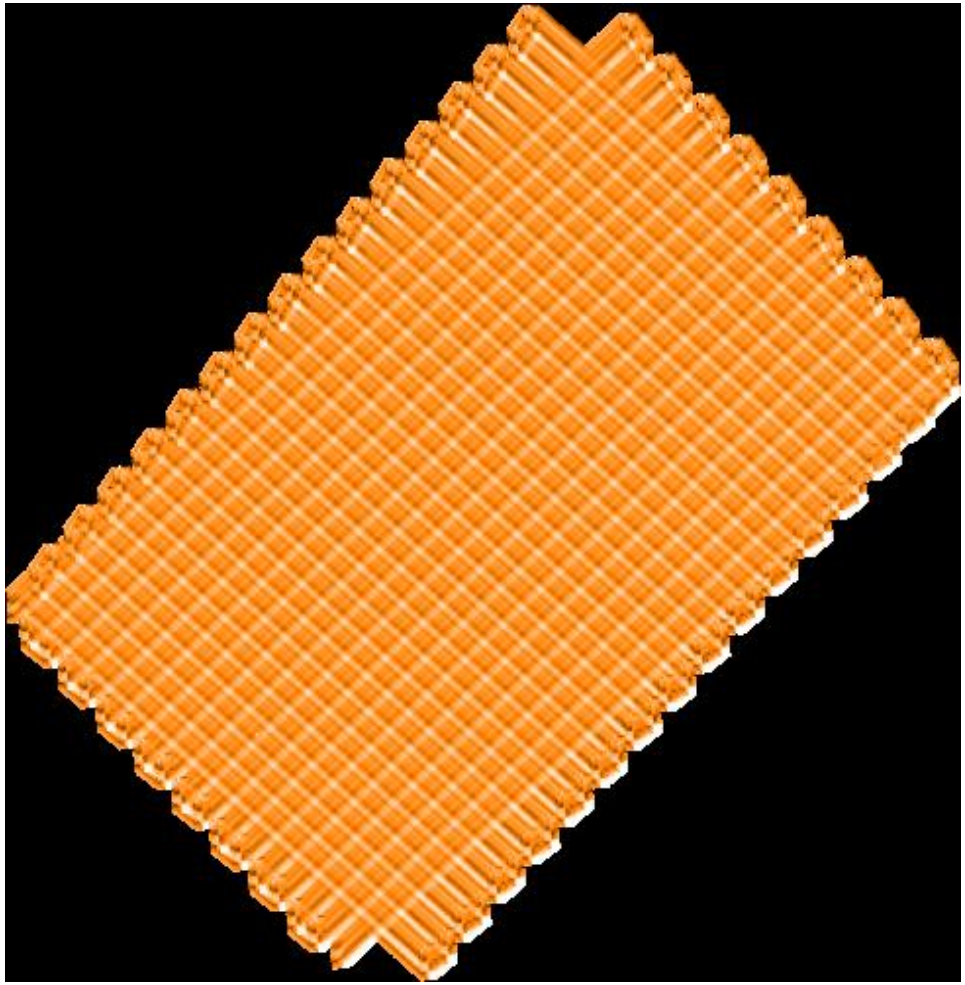
Why port Scanamorphos to Java?

- get a preview of the Scanamorphos results into the Herschel archive
- test our modules by direct comparison with Scanamorphos results
  (well – test Scanamorphos by direct comparison with our results too)
- test the processing idea of Scanamorphos with different code
- understand in detail, how Scanamorphos works

Contents

- remove Turnarounds
- baseline subtraction
- destriping
- remove average drifts (of all detector pixels)
- remove individual drifts (of every individual detector pixel)
- map

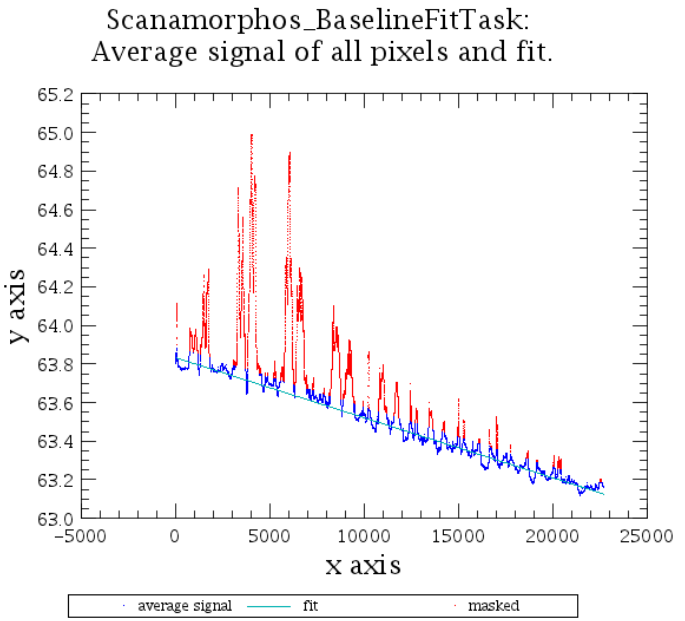
Level 1 of obsid 1342204362 + -63



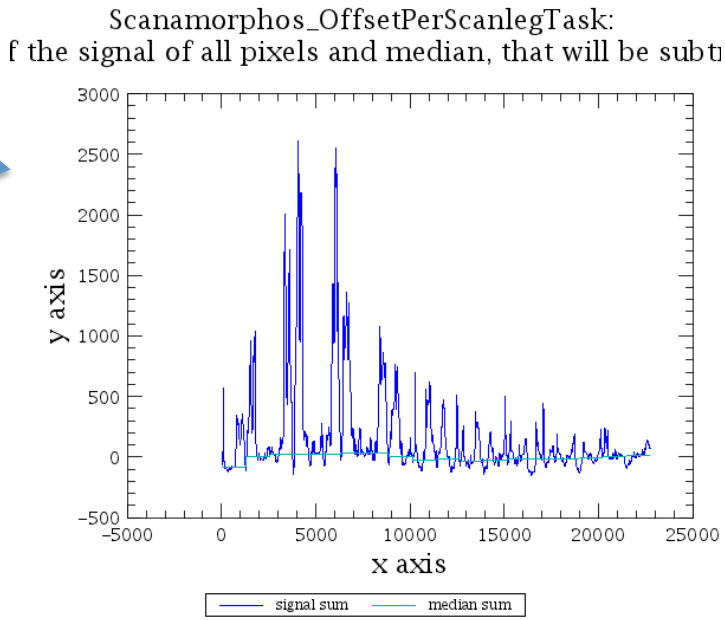
Baseline removal

Repetition by Repetition:

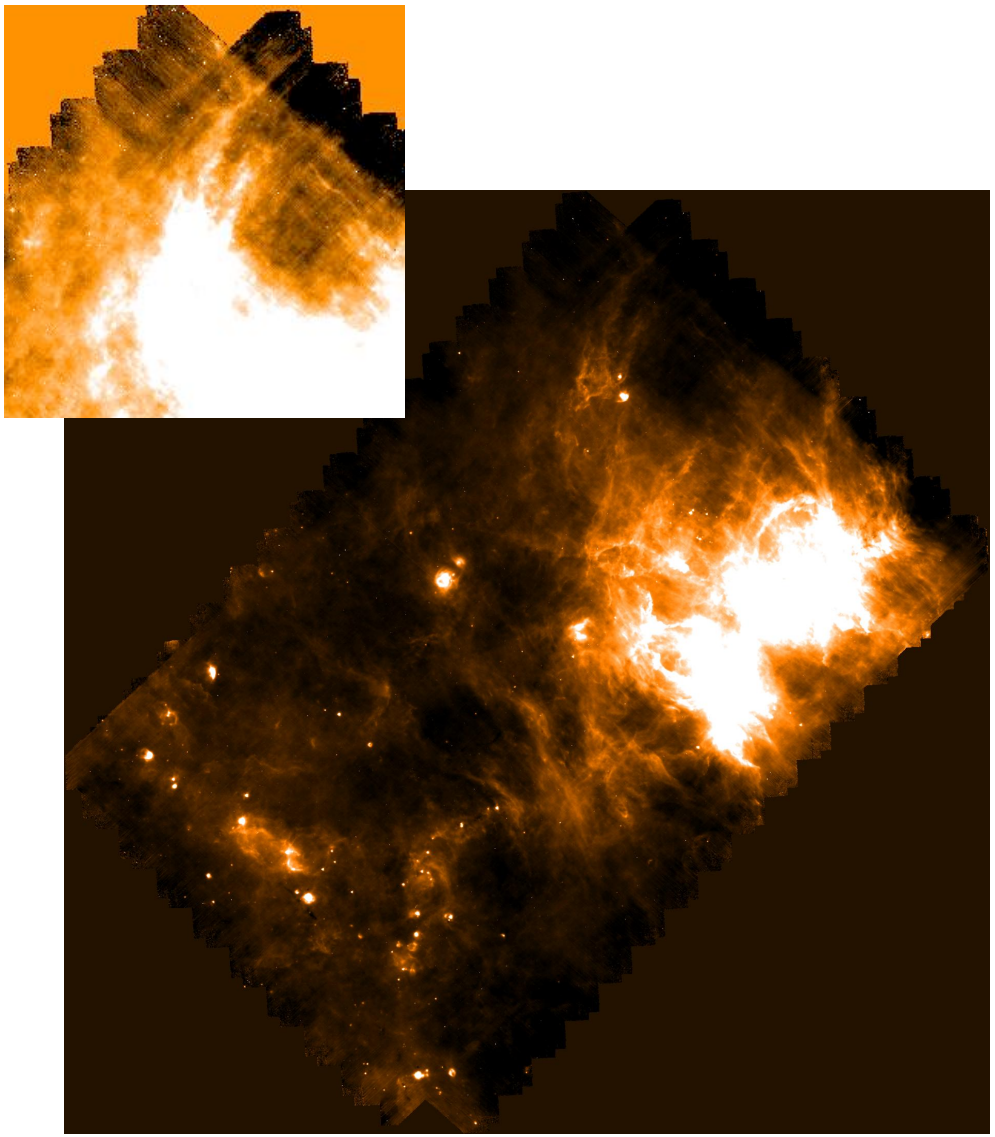
1. baseline fit of average signal, complete timeline. 3-sigma masking

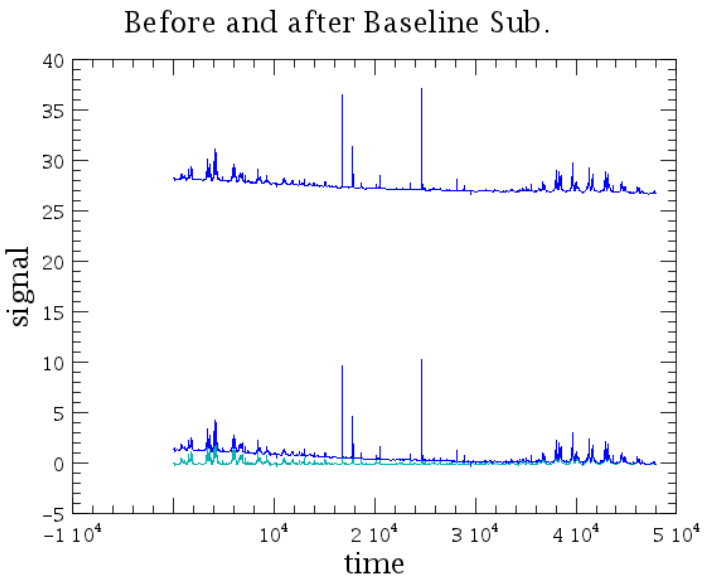


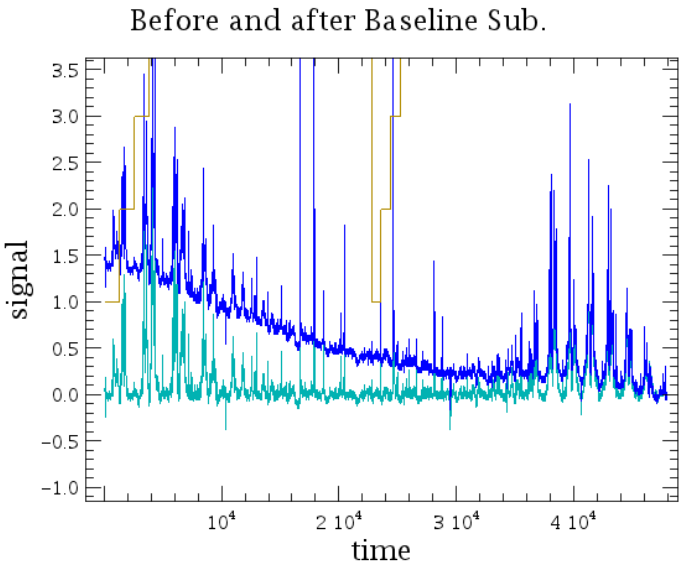
2. subtract the median of all unmasked values per scanleg
3. repeat 1 and 2
4. repeat 1
5. galactic option: repeat 2
6. no galactic: fit scanlegs per detector pixel, 3-sigma masking



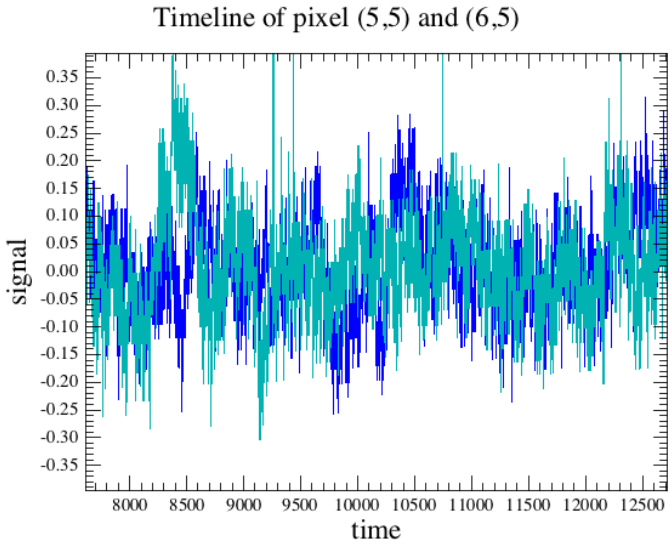
Baseline removal - result

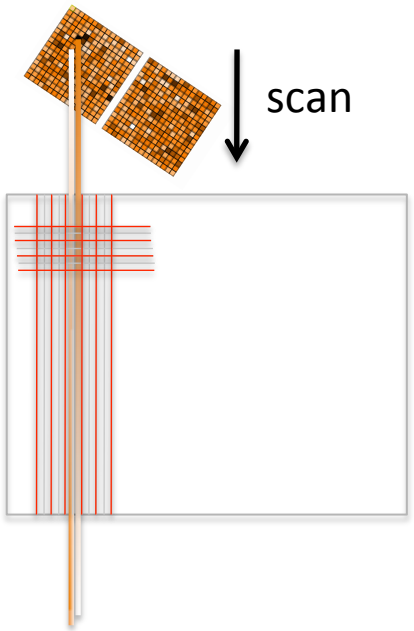






Destriping

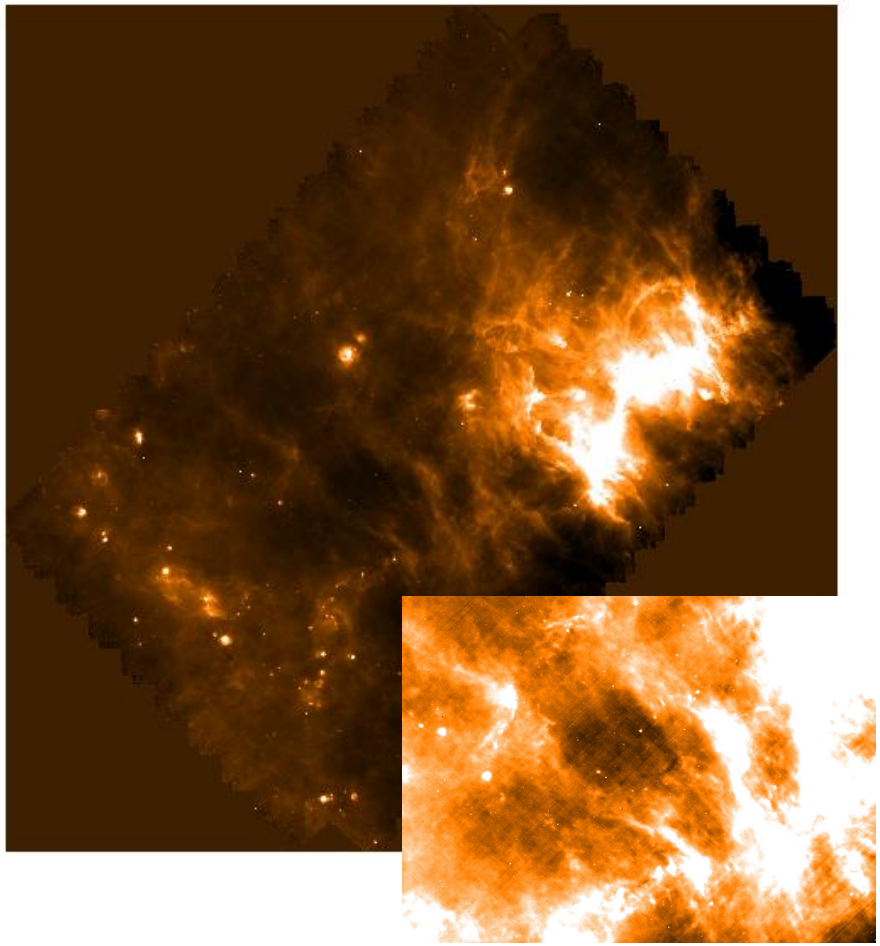




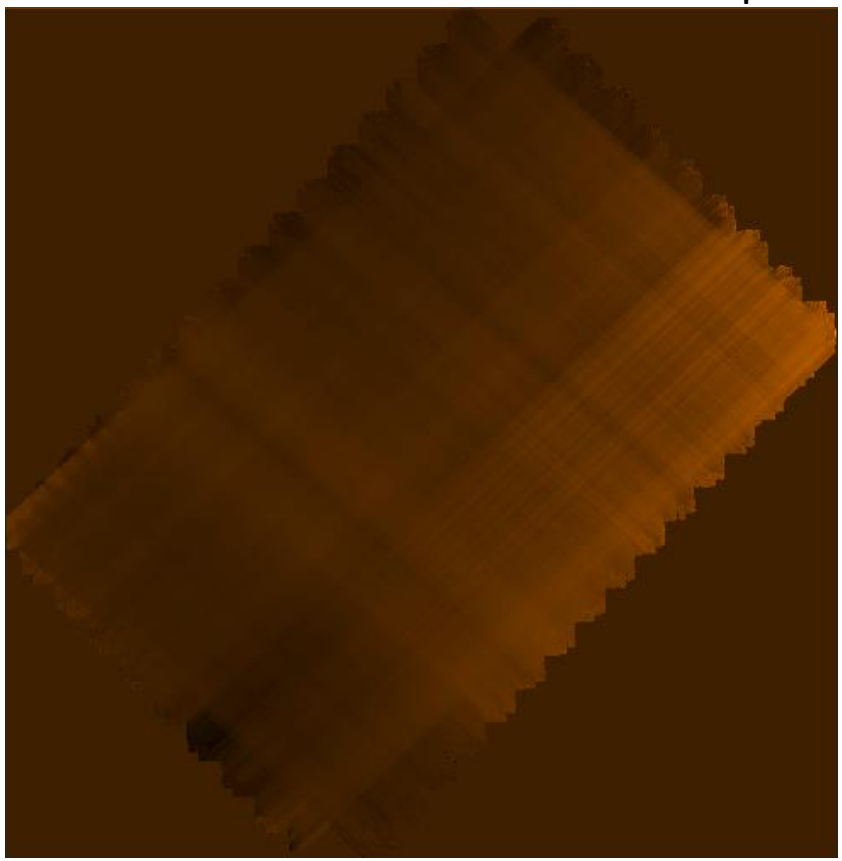
- Takes a Map and backprojects it into a Signal cube
  this should average out drifts
- subract this simulated cube from the real one
- fit the difference
- subtract fit from the signal
- Map
- iterate

Destriping - result

Destriped Map

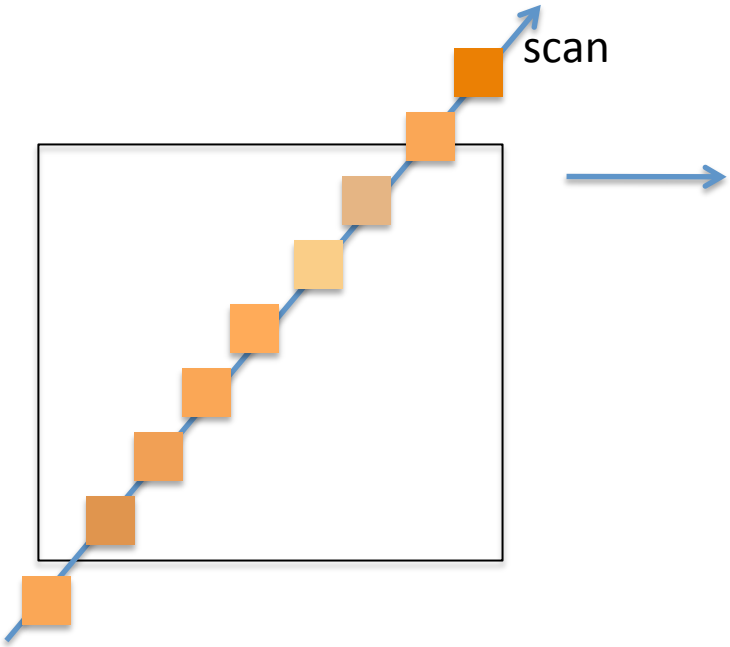


Difference to Baseline-Subtracted Map



Average Drifts

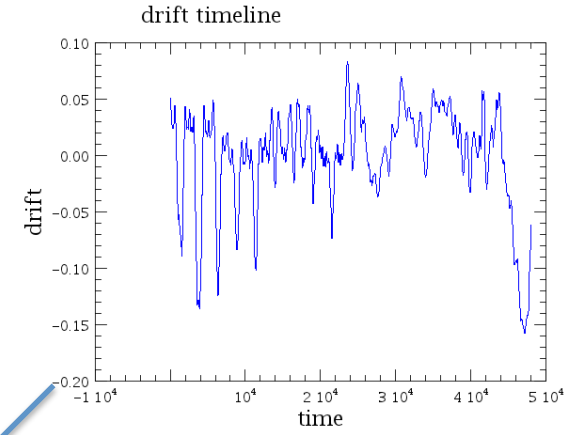
Goal: remove the drift that is common to all detector pixels
Approach:
Collect crossings of Detectors over a Map pixel



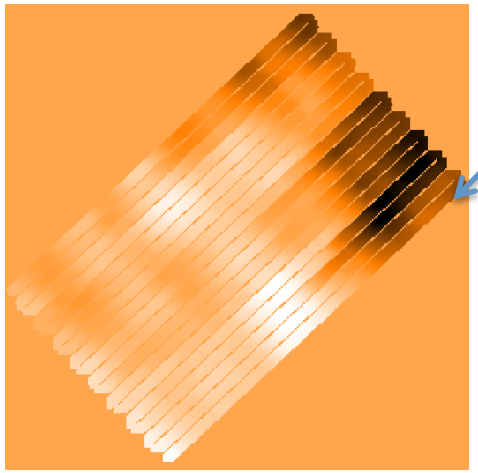
For every Map Pixel:
$\overline{Flux}_i, \sigma_i, \overline{time}_i$

Build drift matrix: Put $Flux_i, \sigma_i$ at $time_i$
Assign $\overline{Flux}(time_{k)} = 0$
Find difference: $\overline{drift}_{ki} = \overline{Flux}_k - \overline{Flux}_i$
Assign $\overline{Flux}_i$
Iterate over the matrix

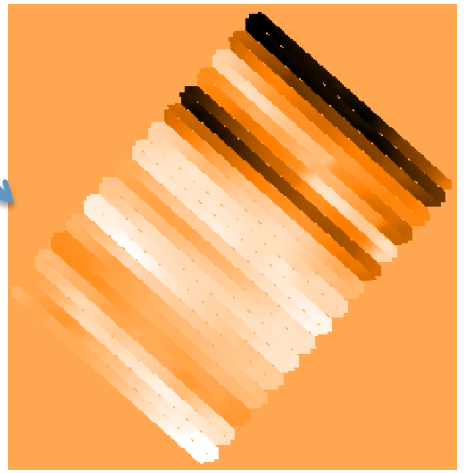
Average Drifts 2



scan

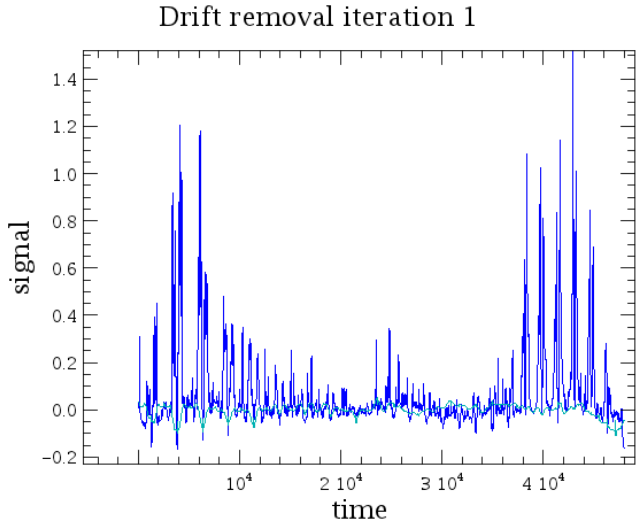


cross-scan



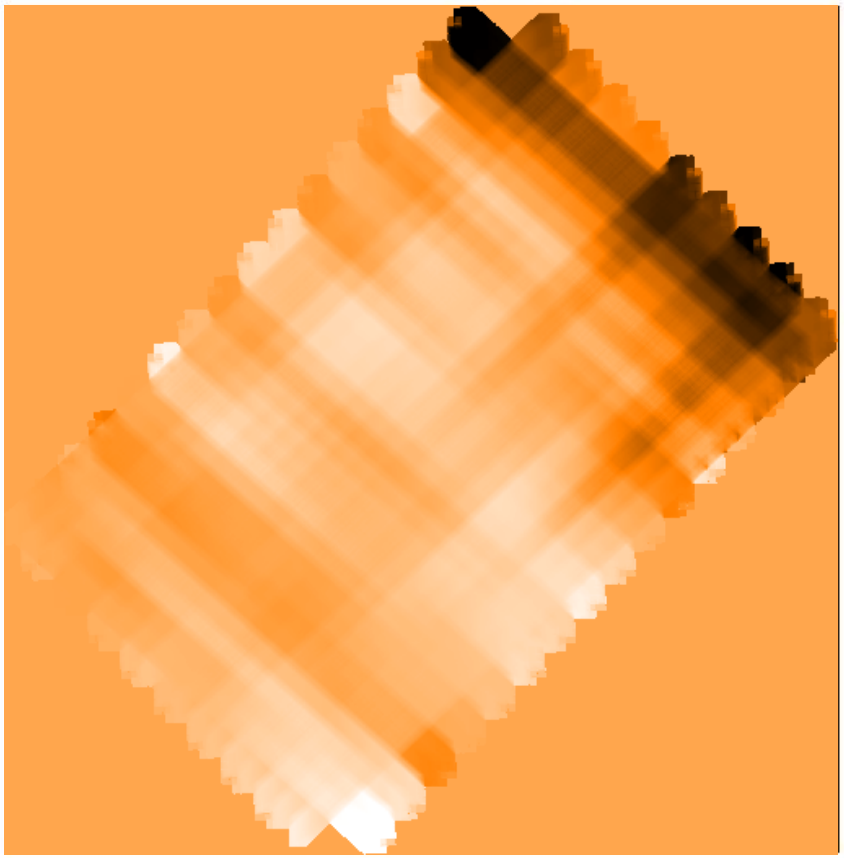
σ-map

σ-map

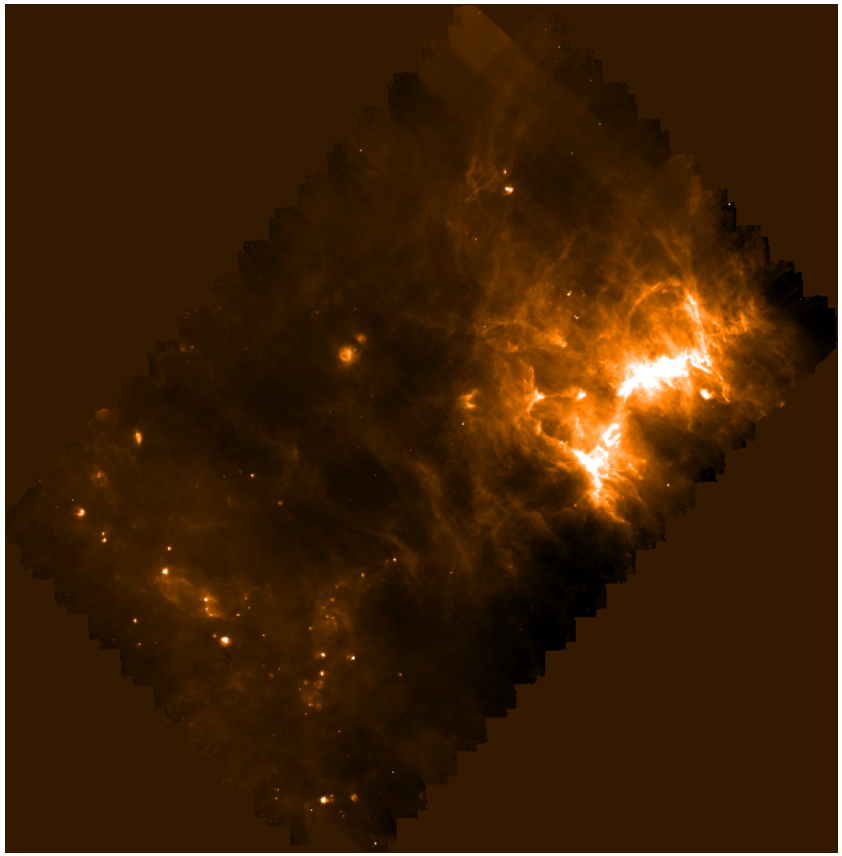


Average - result

Destriped Map

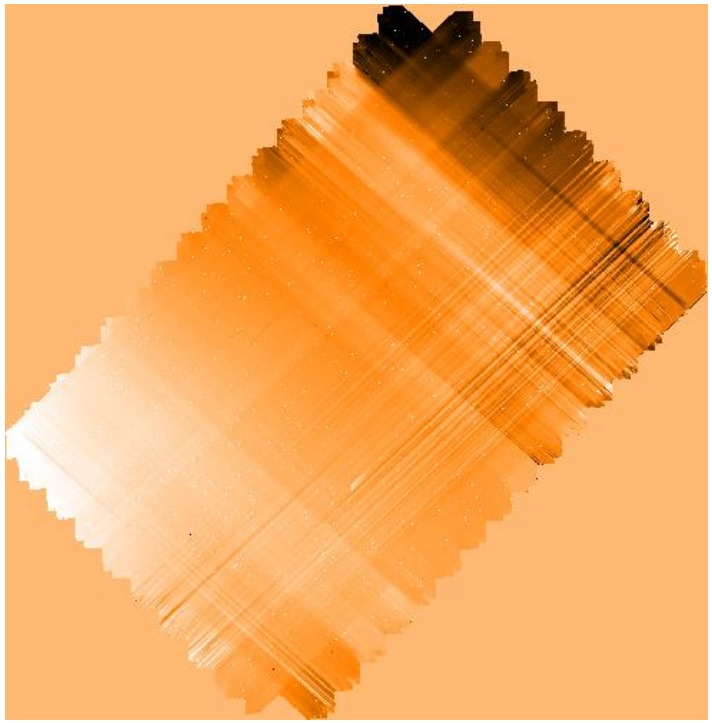


Map after average Drift removal

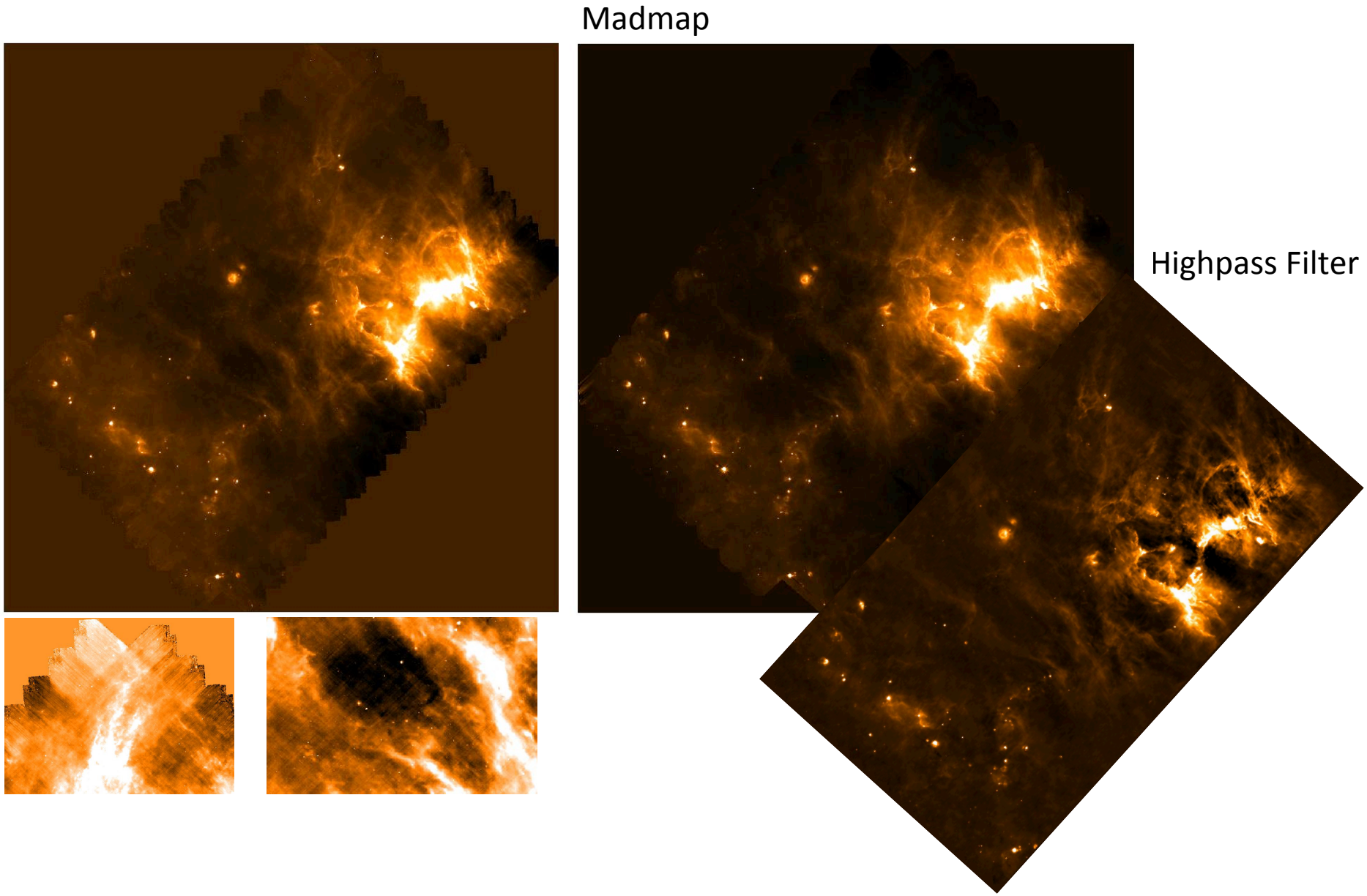


Individual Drifts

- Calculate the crossings again (like for the average drift)
- Calculate the average flux of all crossings for one Mappixel
- take the difference as drift and assign it to the timeline, this time for every detector pixel
- subtract the drift cube from the signal cube
- iterate



Compare



Next Steps

- Extended Documentation
- Process all scan-cross-scan pairs
- solve remaining problems (Average drift, perhaps destriper)
- get this ready for the pipeline from software version 9 on

... find a good name