#### FORCAST First Light Experience

TACFL – first light with SOFIA!

T. Herter and FORCAST Team

TLH: 11-Aug-10

#### Outline

#### Some photos on

- installation and checkout of FORCAST
- TACFL flight
- Some results on telescope and FORCAST performance

#### FORCAST Team members

- Joe Adams (Project Scientist), George Gull (Lead Engineer), Justin Schoenwald (Software Engineer), Chuck Henderson (Mechanical Eng), Luke Keller (Co-I)
- Gordon Stacey (Co-I), Thomas Nikola (Co-I), Keri Hoadley (REU student)

#### FORCAST in DAOF lab



FORCAST w/ foreoptics (test equipment), counterweight rack, and PI rack

#### FORCAST & Sky Emissivity Test







#### Installation on the plane



Installing PI rack & getting FORCAST into plane

#### Attaching FORCAST





- George and Charlie positioning FORCAST
- George and Chuck fastening FORCAST to telescope

#### Cryogen transfers on the plane



George and Luke in their Halloween costumes

## Line Ops



 PI position for flight – my computer screen on top of rack. Keri (seated) and Justin (standing behind PI rack on right)



 Jim, Joe, and Justin looking at data during line operation

#### Working on Line Ops...







TACFL experience

## TACFL flight

- Flight to characterize telescope performance, mainly jitter/pointing
  - FORCAST added to get high time resolution image motion data
  - Acquire data at ~ 400 500 Hz
  - Secondary goal IR backgrounds and telescope emissivity
- First light science object goal added
  - M82 and Jupiter selected

## **TACFL: In flight operations**



 Holgar, Randy, Andy, and Uli at work

- □ Jim and Joe (foreground),
- Alan (background)



#### **Point Spread Function**





- Image motion in elevation: left first 300 points, right full data set, ~ 8000 points
  - Peak-to-peak is 13 pixels (0.75 arcseconds/pixel)
- Axes of FORCAST images rotated by 139 degrees to align measurements with elevation and cross-elevation direction

#### Resonances (40-100 Hz)

![](_page_13_Figure_1.jpeg)

- Transformation of Flow 01 data set
- Axes of FORCAST images rotated by 139 degrees to align measurements with elevation and cross-elevation direction
- Note: This is square of amplitude

![](_page_14_Figure_0.jpeg)

- Transformation of Flow 01 data set
- Axes of FORCAST images rotated by 139 degrees
- Notes
  - These modes have a larger amplitude than the higher frequency ones
  - Again, this is square of the amplitude

#### **Chopper Performance** dЪ 36 60 den ch b п п 34 50 п × 40 30 30 n n CC D **G** 28 무무 20 100 20 80 120 0 20 40 60 80 100 120 0 40 60 plane plane

- Performance of chopper as measured on epsilon Sco
  - Frame rate is 508 Hz, amplitude on vertical axis is pixels
- □ 30 arcsec chop (in x) at 10 Hz
- Duty cycle very low and position never stabilizes
  - Need to run at much slower chop
  - For 3 arcmin chop 1/2 of time is spent in transition

#### **Background Response modeling**

 For a given filter, the photoelectric current in the detector due to the background is given by:

$$PE = A_{tel}\Omega_{pix}\int \left\{ \varepsilon_{sky}B_{\nu}(T_{sky})\tau_{tel}\tau_{win} + \varepsilon_{tel}B_{\nu}(T_{tel})\tau_{win} + \varepsilon_{win}B_{\nu}(T_{win}) \right\} \frac{\tau_{inst}}{h\nu}d\nu$$

- □ All emissivities ( $\epsilon$ ) and transmissions ( $\tau$ ) are frequency dependent ( $\tau$  here is transmission, not optical depth)
  - The filter and detector response are incorporated into the instrument throughput,  $\tau_{inst}$ .
  - The sky is assumed to be at a single temperature with an emissivity  $\varepsilon_{sky} = 1 \tau_{sky}$ , where the transmission comes from ATRAN.
  - The index of CsI is 1.72 which results in a reflectivity loss from both surfaces is  $r_{win} = 0.14$ . The total transmission  $\tau_{win} = 1 r_{win} \varepsilon_{win}$ .
  - Estimated window emissivity is ~ 6 %

## **Blockage/Obscuration**

**•** FORCAST pupil images show the obscured telescope area

![](_page_17_Picture_2.jpeg)

![](_page_17_Figure_3.jpeg)

![](_page_17_Picture_4.jpeg)

5.4 microns, bFT04\_0033.fits pupil image from TACFL

11.3 microns, bLP09\_0004.fits Image of gate valve from line Ops #1 used as flat

Flatten, normalized 5.4 micron pupil image which gives ~ 6% emissivity contribution

Neglecting sky emission the integrated pupil signal is proportional to

$$S_{tot} = A_o B_v (T_{tel}) \tau_{tel} \tau_{win} + A_p \varepsilon_{tel} B_v (T_{tel}) \tau_{win} + A_p \varepsilon_{win} B_v (T_{win}) = A_o B_v (T_{tel}) \tau_{tel} \tau_{win} + S_{unobs}$$

$$\implies \phi_o \equiv \frac{A_o}{A_p} = \frac{S_{tot} - S_{unobs}}{S_{unobs}} \frac{\varepsilon_{tel} + \varepsilon_{win}}{\tau_{win} \tau_{tel}}$$

 $\phi_p$  = fractional obscuration,  $A_p$  = pupil area,  $A_o$  = obscured area. The last step assumes  $T_{tel} = T_{win}$ 

Subtracting the median from the average over the pupil gives the normalized difference:  $(S_{tot} - S_{unobs})/S_{unobs} = (average - median) = 0.06$ 

Taking 
$$\tau_{tel} = \tau_{win} = 0.8$$
,  $\varepsilon_{tel} = 0.2$  and  $\varepsilon_{win} = 0.06$  then  $\phi_o = 0.06 \times 0.4 = 2.4\%$ 

## **Telescope Emissivity**

- This is somewhat difficult to pin down
  - Best estimate is between 10 and 20%
- Issues:
  - Difficult to measure from ground due large (and variable) atmospheric emissivity from DAOF tarmac
  - Could not perform sky "dip" during TACFL due to fixed elevation
  - In-flight dewar window temperature is uncertain
    - Estimate is emissivity of ~ 5 7 % but if warmer than telescope contributes more signal than expected

#### TACFL: First "Science" Integration

![](_page_19_Picture_1.jpeg)

**M82** – first chop-nod sequence: 24  $\mu$ m (left) and 37  $\mu$ m (right)

#### FORCAST Calibrations using Ganymede

- Response taken from FORCAST First Light/Flight
  - Jupiter causes detector artifacts
  - Ganymede = "point source" give response
- Photon noise from
  - atmospheric, telescope, and window emission
- Sensitivity models consistent with previous calculations

![](_page_20_Picture_7.jpeg)

Jupiter with Europa, Ganymede, Io: 5.4, 24, 37  $\mu$ m false color image

#### **TACFL Performance**

- Use Ganymede for response (e-/sec/Jy)
- Use M82 for noise from background
  - Ganymede compromised because of bright source (Jupiter and possible Ganymede itself)

Filter	Flux	Configuration
(um)	(Jy)	
19.7	0.108	dichroic
24.2	0.135	dichroic
31.4	0.321	dichroic
37.1	0.694	dichroic
31.4	0.238	lwc
37.1	0.468	lwc

Flux for S/N = 4 in 900 seconds assuming 49 pixels used for extraction of (point) source.

Performance is close to SOFIA website sensitivity calculator (SITE) using the same assumptions (35K feet, and 25° zenith angle)

## **Short Science Sensitivity**

![](_page_22_Figure_1.jpeg)

 Expect up to a factor of 2 – 3 improvement in sensitivity depending on filter for short science flights

#### TACFL: We've landed

![](_page_23_Picture_1.jpeg)

A nice crowd to greet us at the wee hours of the morning

#### Summary

#### TACFL flight – very successful

- Able to acquire and detect astronomical sources
- Telescope performance near nominal
  - Diffraction limited for  $\lambda > 50 \ \mu m$
  - Emissivity reasonable
- FORCAST within factor of 2 of projected performance

![](_page_25_Picture_0.jpeg)

![](_page_25_Picture_1.jpeg)

# **Questions?**

![](_page_25_Picture_3.jpeg)